Dynamical Entropy of Generalized Quantum Markov Chains

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Abstract. We compute the dynamical entropy in the sense of Connes, Narnhofer and Thirring of shift automorphism of generalized quantum Markov chains as defined by Accardi and Frigerio. For any generalized quantum Markov chain defined via a finite set of conditional density amplitudes we show that the dynamical entropy is equal to the mean entropy.
1. Introduction

In their paper [5] Connes, Naruhofer and Thirring (CNT) extended the notion of dynamical entropy of classical dynamical systems introduced by Kolmogorov and Sinai [7,14] to the case of automorphisms of $C^*$-algebras invariant with respect to a given state. As in the classical ergodic theory [18], the concept of the CNT entropy should be mathematically useful to find a classification of quantum chaotic systems. In this respect it should be important to develop the method which enable to compute the entropy for quantum systems. There have been many results on entropic computations ([8-12, 15-17] and references therein).

In this paper we compute the CNT entropy of shift automorphisms of generalized quantum Markov chains (GQMC) as defined by Accardi and Frigerio [1]. For any GQMC defined via a finite set of conditional density amplitudes we show that the dynamical (CNT) entropy is equal to the mean entropy.

It should be mentioned that Besson [3] computed the Connes-Størner (CS) entropy [6] of shift automorphism of quantum Markov chains (QMC). Later on the result was generalized by Quasthoff [13]. See also chapter 11 of Ref. [10] for additional informations. But, as mentioned in Ref. [1], one has to deal with the large class of GQMC in order to account the nearest neighbours potentials of interest for quantum statistical mechanics. Also it has been shown in [1] that any QMC belongs to the class we consider and so our result can be viewed as a non-trivial extension of that in [3]. On the other hand we are only able to deal with GQMC defined via conditional density amplitudes. Thus it must be desirable to find the method which is applicable to GQMC defined via a transition expectation directly.

We organize the paper as follows: In Section 2 we recall the definitions of generalized quantum Markov chains [1,2] and then describe the class which we consider in this paper. In Section 3 we review the dynamical entropy of $C^*$-algebra and then state our main theorem. In Section 4 we produce the proof of the main theorem.
2. Generalized Quantum Markov Chain

Let us recall the definition of generalized Quantum Markov chains [1,2]. Let $M_0 \subset M_d(C)$, $d > 1$, be a fixed subalgebra of $M_d(C)$ (the $d \times d$ complex matrices), and $\mathfrak{A}$ be the $C^*$-algebra $\mathfrak{A} = \otimes_{\mathbb{Z}} M_0$. Let $J_n$ be the canonical injection of $M_0$ into the $n$-th factor of $\mathfrak{A}$. For $I \subset \mathbb{Z}$ we denote by $\mathfrak{A}_I$ the algebra generated by $\{J_n(M_0) : n \in I\}$. In the above notation we have

$$\mathfrak{A} = \left( \bigcup_{I \subset \mathbb{Z}} \mathfrak{A}_I \right)^{-}, \quad \mathfrak{A}_I = \otimes_{n \in I} J_n(M_0),$$

where the bar denotes the norm closure.

The basic ingredients in the construction of a stationary (generalized) quantum Markov chain in the sense of Accardi and Frigerio [1] consist of a completely positive unital map (c.p.u.map) $E$, called a transition expectation:

$$E : M_0 \otimes M_0 \to M_0$$

$$E(1 \otimes 1) = 1$$

and a state $\phi_0$ on $M_0$, satisfying the following condition:

$$\phi_0(E(1 \otimes x)) = \phi_0(x), \quad x \in M_0.$$  \hspace{1cm} (2.3)

For any $\Lambda = [i, k] \equiv \{i, i + 1, \ldots, k\} \subset \mathbb{Z}$ and $x_j \in M_0$, $i \leq j \leq k$, one then defines

$$\omega_{\Lambda}(x_i \otimes x_{i+1} \otimes \cdots \otimes x_k)$$

$$= \phi_0(E(x_i \otimes E(x_{i+1} \otimes E(x_{i+2} \otimes \cdots \otimes E(x_k \otimes 1) \cdots)))).$$  \hspace{1cm} (2.4)

Notice that the family of local states $\{\omega_{\Lambda} : \Lambda \subset \mathbb{Z}\}$ satisfies a compatible condition by (2.2) and (2.3), and the state $\omega$ defined by $\omega_{\Lambda}, \Lambda \subset \mathbb{Z}$, is stationary.

**Definition 2.1 [1,2].** (a) Let $E$ be a transition expectation satisfying (2.2) and let $\phi_0$ be a state on $M_0$ satisfying (2.3). Then $(\phi_0, E)$ is called a Markov pair.

(b) The state $\omega$ on $\mathfrak{A}$ defined by the sequence $\{\omega_{[-n,n]}\}_{n \geq 1}$ is called a stationary generalized quantum Markov state. The dynamical system $(\mathfrak{A}, \alpha, \omega)$ is called a generalized quantum Markov chain, where $\alpha$ is the shift map on $\mathfrak{A}, \alpha(J_n(a)) = J_{n+1}(a)$.

Notice that by (2.3) the state $\omega$ is invariant with respect to the shift $\alpha$. 

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Remark 2.2. If the transition expectation satisfies the additional condition:

\[ E(x \otimes y) = E(x \otimes E(y \otimes 1)), \quad x, y \in M_0, \text{ mod. } \{ \phi_0, E \}, \]

then the corresponding dynamical system is called a Quantum Markov Chain [1].

In this paper we consider the generalized quantum Markov chains defined by a finite set of conditional density amplitudes [1,2]. We first consider the generalized quantum markov chain defined via a single conditional density amplitude. Let \( \text{Tr} \) be the trace on \( M_0 \) which takes the value 1 at each minimal projection, and let \( \tilde{\text{Tr}} \) be the trace on \( M_0 \otimes M_0 \).

Denote by \( \tilde{\text{Tr}}^{(i)}, \quad i = 1, 2 \), the partial traces defined by

\[
\tilde{\text{Tr}}^{(1)}(a \otimes b) = \text{Tr}(a)b \quad \tilde{\text{Tr}}^{(2)}(a \otimes b) = \text{Tr}(b)a. \tag{2.5}
\]

Let \( W_0 \in M_0 \) be a density matrix in \( M_0(W_0 \geq 0 \text{ and } \text{Tr}(W_0) = 1) \) and let \( K \in M_0 \otimes M_0 \) be an operator satisfying

\[
\tilde{\text{Tr}}^{(2)}(KK^*) = 1, \quad \tilde{\text{Tr}}^{(1)}((W_0 \otimes 1)K) = W_0. \tag{2.6}
\]

A positive operator \( K \in M_0 \otimes M_0 \) satisfying the above is called a conditional density amplitude [1,2]. For given conditional density amplitude \( K \), one can define a transition expectation \( E \) by

\[
E(x) = \tilde{\text{Tr}}^{(2)}(KxK^*), \quad x \in M_0 \otimes M_0. \tag{2.7}
\]

Let \( \phi_0 \) be the state on \( M_0 \) defined by the density matrix \( W_0 \). Then it follows from (2.5) and (2.6) that \( (\phi_0, E) \) is a Markov pair generated by the pair \( (W_0, K) \). For a conditional density amplitude \( K \), and for \( i, k, n \in \mathbb{Z} \), let

\[
K_{[i,n+1]} = (J_n \otimes J_{n+1})(K), \tag{2.8}
\]

\[
K_{[i,k+1]} = K_{[i,i+1]}K_{[i+1,i+2]} \cdots K_{[k,k+1]}, \quad i \leq k.
\]

We write that

\[
W_{[i,k+1]} = K_{[i,k+1]}^*J_i(W_0)K_{[i,k+1]}. \tag{2.9}
\]

It then follows from (2.4) and (2.7) that

\[
\omega_{[i,k]}(x_i \otimes x_{i+1} \otimes \cdots \otimes x_k) = \text{Tr}(W_{[i,k+1]}(x_i \otimes x_{i+1} \otimes \cdots \otimes x_k \otimes 1)). \tag{2.10}
\]
where $\text{Tr}$ is the trace on $\mathfrak{A}_{[i, k+1]}$.

The above construction of transition expectation can be generalized as follows: Let $\{K_1, K_2, \cdots, K_l\}$ be a finite subset of $M_0 \otimes M_0$ satisfying

$$
\sum_{j=1}^{l} \text{Tr}^{(2)}(K_j K_j^*) = 1, \quad \sum_{j=1}^{l} \text{Tr}^{(1)}(K_j^*(W_0 \otimes 1)K_j) = W_0, \tag{2.11}
$$

where $W_0 \in M_0$ is a density matrix. Then the most general transition expectation has the form [2]

$$
E(x) = \sum_{j=1}^{l} \text{Tr}^{(2)}(K_j^* x K_j), \quad x \in M_0 \otimes M_0. \tag{2.12}
$$

The set $\{K_1, K_2, \cdots, K_l\} \subset M_0 \otimes M_0$ satisfying the conditions in (2.11) will be called a set of conditional density amplitudes.

Next let us consider the mean entropy. For a given state $\omega$ on $\mathfrak{A}$ and finite $I \subset \mathbb{Z}$, let $S(\omega|\mathfrak{A}_I)$ be the entropy of the state $\omega$ on $\mathfrak{A}_I$ [5, 10], where $\omega|\mathfrak{A}_I$ is the state on $\mathfrak{A}_I$ defined by the restriction of $\omega$ on $\mathfrak{A}_I$. If $\omega|\mathfrak{A}_I$ is given by normalized density matrix $\rho_I (\text{Tr}(\rho_I) = 1)$, then

$$
S(\omega|\mathfrak{A}_I) = - \text{Tr}(\rho_I \ln \rho_I). \tag{2.13}
$$

By the subadditivity of $S(\omega|\mathfrak{A}_I)$ [4], the limit

$$
s(\omega) = \lim_{n \to \infty} \frac{1}{n+1} S(\omega|\mathfrak{A}_{[0,n]}) \tag{2.14}
$$

exists. The quantity $s(\omega)$ is called the mean entropy of the state $\omega$ on $\mathfrak{A}$. 
3. Dynamical Entropy and Main Result

Since $C^*$-algebra $\mathfrak{A}$ which we are dealing with is approximately finite (AF), we review entropic results for AF-algebras. For the general definition of the CNT entropy and related results we refer to [5]. Let $(\mathfrak{A}, \alpha, \omega)$ be a $C^*$-dynamical system, where $\mathfrak{A}$ is a unital $C^*$-algebra of AF type, $\alpha$ is an automorphism on $\mathfrak{A}$ and $\omega$ is a state on $\mathfrak{A}$ which is invariant with respect to $\alpha$.

For a given state $\omega$ on $\mathfrak{A}$ and $k \in \mathbb{N}$, let $\{\omega_{i_1,i_2,\ldots,i_k} : i_j \in \mathbb{N}, j = 1, \ldots, k\}$ be a finite decomposition of the state $\omega$:

$$\omega = \sum_{i_1,i_2,\ldots,i_k} \omega_{i_1,i_2,\ldots,i_k}.$$  

Let $\eta$ be the function on $[0,1]$ defined by $\eta(x) = -x \ln x$ if $x > 0$ and $\eta(0) = 0$. We write

$$\omega^{(l)}_{i_1} = \sum_{i_1,i_2,\ldots,i_k} \omega_{i_1,i_2,\ldots,i_k} \quad \text{and} \quad \omega^{(l)}_{i_1} = \frac{\omega^{(l)}_{i_1}}{\omega_{i_1}(1)}. \quad (3.1)$$

For given finite dimensional subalgebras $\mathfrak{A}_1, \mathfrak{A}_2, \ldots, \mathfrak{A}_k \subset \mathfrak{A}$, put

$$H_\omega(\mathfrak{A}_1, \mathfrak{A}_2, \ldots, \mathfrak{A}_k) \quad (3.2)$$

$$= \sup \left\{ \sum_{i_1,i_2,\ldots,i_k} \eta(\omega_{i_1,i_2,\ldots,i_k}(1)) - \sum_{l=1}^k \sum_{i_l} \eta(\omega^{(l)}_{i_1}(1)) \right\}$$

$$+ \sum_{l=1}^k S(\omega|\mathfrak{A}_l) - \sum_{l=1}^k \sum_{i_l} \omega^{(l)}_{i_1}(1) S\left(\omega^{(l)}_{i_1}|\mathfrak{A}_l\right),$$

where the sup is taken over finite decompositions of $\omega$. For any finite dimensional subalgebra $\mathfrak{M} \subset \mathfrak{A}$, let

$$h_{\omega,\alpha}(\mathfrak{M}) = \lim_{k \to \infty} \frac{1}{k} H_\omega(\mathfrak{M}, \alpha(\mathfrak{M}), \ldots, \alpha^{k-1}(\mathfrak{M})). \quad (3.3)$$

Let $h_\omega(\alpha)$ be the dynamical entropy defined as in [5]. For an AF-algebra $\mathfrak{A} = (\bigcup_{n=1}^\infty \mathfrak{A}_n)^-$ with $1 \in \mathfrak{A}_1 \subset \mathfrak{A}_2 \cdots$, finite dimensional, it turned out that the equality

$$h_\omega(\alpha) = \lim_{n} h_{\omega,\alpha}(\mathfrak{A}_n) \quad (3.4)$$

holds [5, Corollary V.4]. This Kolmogorov-Sinai type theorem has been extended to the setting of quasi local algebras in quantum statistical mechanics [11].
For later use we collect some entropic results from [5].

Lemma 3.1 [5, Proposition III.6]. (a) If $\mathcal{A}_i \subset \mathcal{A}_i$, $i = 1, \ldots, n$, then $H_{\omega}(\mathcal{A}_1', \mathcal{A}_2', \ldots, \mathcal{A}_n') \leq H_{\omega}(\mathcal{A}_1, \mathcal{A}_2, \ldots, \mathcal{A}_n)$. 

(b) $H_{\omega}(\mathcal{A}_1, \mathcal{A}_2, \ldots, \mathcal{A}_n)$ depends only upon the set $\{\mathcal{A}_1, \mathcal{A}_2, \ldots, \mathcal{A}_n\} = \mathcal{X}$.

(c) The inequalities

$$\max\{H_{\omega}(X), H_{\omega}(Y)\} \leq H_{\omega}(X \cup Y) \leq H_{\omega}(X) + H_{\omega}(Y)$$

hold with the notation in (b).

The above results are consequences of general results in [5].

We now state our main result. Let $(\mathcal{A}, \alpha, \omega)$ be a generalized quantum Markov chain introduced in Section 2, where $\alpha : \mathcal{A} \rightarrow \mathcal{A}$ is the shift automorphism.

Theorem 3.2. Let $W_0 \in M_0$ and $\{K_1, K_2, \ldots, K_l\} \subset M_0 \otimes M_0$ be a density matrix and a finite set of conditional density amplitudes satisfying (2.11) and let $(\mathcal{A}, \alpha, \omega)$ be the generalized quantum Markov chain constructed from $W_0$ and $\{K_1, K_2, \ldots, K_l\}$. Then the equality

$$h_{\omega}(\alpha) = s(\omega)$$

holds, where $s(\omega)$ is the mean entropy.

We will produce the proof of the above theorem in the next section.
4. Proof of Main Theorem

We prove Theorem 3.2 in this section. Notice that by (3.4) the dynamical entropy of a generalized quantum Markov chain \((\mathfrak{A}, \alpha, \omega)\) is given by

\[
h_\omega(\alpha) = \lim_{n \to -\infty} h_{\omega, \alpha}(\mathfrak{A}_{[-n,n]})
\]

\[
= \lim_{n \to -\infty} h_{\omega, \alpha}(\mathfrak{A}_{[1,n]}). \tag{4.1}
\]

Here we have used the fact that \(h_{\omega, \alpha}(\mathfrak{A}_{[-n,n]}) = h_{\omega, \alpha}(\mathfrak{A}_{[1,2n+1]})\) which follows from the invariance of \(\omega\) with respect to \(\alpha\) and the expression in (3.2). The upper bound \((h_\omega(\alpha) \leq s(\omega))\) follows from Lemma 3.1, (3.3) and the fact that \(H_\omega(\mathfrak{A}_n) \leq S(\omega^+|\mathfrak{A}_n)\) [5]:

\[
H_\omega(\mathfrak{A}_{[1,n]}, \alpha(\mathfrak{A}_{[1,n]}), \ldots, \alpha^K(\mathfrak{A}_{[1,n]}))
\]

\[
\leq H_\omega(\mathfrak{A}_{[1,n+k]})
\]

\[
\leq S(\mathfrak{A}_{[1,n+k]}).
\]

Dividing the above by \(k + 1\) and taking \(k\) to infinity we get the upper bound.

Thus we need to get the lower bound \(h_\omega(\alpha) \geq s(\omega)\). From Lemma 3.1 (c) it follows that

\[
H_\omega(\mathfrak{A}_{[1,n]}, \alpha(\mathfrak{A}_{[1,n]}), \ldots, \alpha^K(\mathfrak{A}_{[1,n]}))
\]

\[
\geq H_\omega(\mathfrak{A}_{[1,n]}, \mathfrak{A}_{[n+1, n+2n]}, \ldots, \mathfrak{A}_{[n(k-1)+1,nk]}).	ag{4.2}
\]

In order to show the main idea of the proof more clearly, we first consider the case in which the transition expectation is defined by a single conditional density amplitude \(K\) as in (2.7). To obtain the lower bound we have to choose an optimal decomposition of the state \(\omega\). For given \([l, m] \subset \mathbb{Z}\), let \(\{x_j\} \subset \mathfrak{A}^{+}_{[l,m]}\) be a finite decomposition of unity:

\[
\sum_j x_j = 1, \quad x_j \geq 0, \quad x_j \in \mathfrak{A}_{[l,m]}.
\]

For \([l, m] \subset [i + 1, k - 1]\), define states on \(\mathfrak{A}_{[i,k]}\) by

\[
\omega_{[i,k]}(y) \equiv \text{Tr}(K_{[i,k+1]}^* x_j J_i(W_0) K_{[i,k+1]} y), \quad y \in \mathfrak{A}_{[i,k]}.	ag{4.3}
\]
Notice that $x_I$ and $J_i(W_0)$ commute. It follows from (2.9), (2.10) and (4.3) that

$$\omega_{[i,k]} = \sum_J \omega_{[i,k],J}.$$ 

One may check that the family of states $\{\omega_{[i,k],J} : i \leq l, m \leq k\}$ is compatible. Let $\omega_J$ be the state on $\mathfrak{A}$ which is the extension of $\{\omega_{[i,k],J}\}$. Then we have

$$\sum_J \omega_J = \omega.$$

Thus from a decomposition of unity $\{x_J\}$ we obtain a decomposition of the state $\omega$.

Next we choose a decomposition of unity explicitly. Let $\{P_1, P_2, \ldots, P_{d'}\} \subset M_0$ be a family of minimal projections in $M_0$. Recall the expression in (4.2). For fixed $k \geq 1$ and $n \geq 1$, let $I$ be the multi-indices given by

$$I = \{J = (J_1, J_2, \ldots, J_k) : J_l \in \{1, 2, \ldots, d'\}^n\}.$$  

(4.4)

For each $J_l = (i_1, i_2, \ldots, i_n) \in \{1, 2, \ldots, d'\}^n$, put

$$P_{J_l} = J_{n(l-1)+1}(P_1)J_{n(l-1)+2}(P_2)\ldots J_{nl}(P_{i_n})$$  

(4.5)

and for given $J = (J_1, \ldots, J_k)$ we write

$$P_J = P_{J_1}P_{J_2}\ldots P_{J_k}.$$  

(4.6)

Then from the above definitions we have

$$\sum_{J \in I} P_J = 1 \quad \text{and} \quad P_J = \sum_{J_l \text{ fixed}} P_{J_l}.$$  

(4.7)

Denote by $\{\omega_J\}_{J \in I}$ the decomposition of the state obtained from the decomposition of unity $\{P_J\}_{J \in I}$ by (4.3). From (4.3) and (4.7) it follows that from $J = (J_1, J_2, \ldots, J_k)$ and $l \in \{1, 2, \ldots, k\}$

$$\sum_{J_l \text{ fixed}} \omega_J|\mathfrak{A}_{[n(l-1)+1,n]} = \omega_{J_l}|\mathfrak{A}_{[n(l-1)+1,n]}.$$
We now use (4.7) and the shift invariance of \( \omega \) to obtain from (4.2) that

\[
H_\omega (\mathfrak{A}_{[1,n]}, \mathfrak{A}_{[n+1,2n]}, \ldots, \mathfrak{A}_{[n(k-1)+1,nk]}) 
\geq \sum_{J \in \mathcal{I}} \eta(\omega_J(1)) - k \sum_{I \in \{1, \ldots, d'\}^n} \eta(\omega_I(1)) 
+ k S(\omega|\mathfrak{A}_{[1,n]}) - k \sum_{I \in \{1, \ldots, d'\}^n} \bar{\omega}_I(1) S(\bar{\omega}_I|\mathfrak{A}_{[1,n]}).
\]

The main idea to obtain the lower bound is to show that \( S(\bar{\omega}_I|\mathfrak{A}_{[1,n]})/n \) tends to zero as \( n \) tends to infinity.

**Proposition 4.1.** There exists a constant \( c \) independent of \( n \in \mathbb{N} \) and \( I \in \{1, 2, \ldots, d'\}^n \) such that the bound

\[
S(\bar{\omega}_I|\mathfrak{A}_{[1,n]}) \leq c
\]

hold uniformly in \( n \) and \( I \).

We postpone the proof of the above result. Now Theorem 3.2 for \( l = 1 \) is a consequence of Proposition 4.1.

**Proof of Theorem 3.2 for \( l = 1 \).** Let \( \mathfrak{B}_0 \) be the abelian \( C^* \)-algebra generated by \( \{P_1, P_2, \ldots, P_{d'}\} \subset M_0 \) and \( \mathfrak{B} = (\otimes \mathfrak{B}_0)^\mathbb{Z} \). As in Section 2, put

\[
\mathfrak{B}_{[l,m]} = \bigoplus_{i=1}^m J_i(\mathfrak{B}_0)
\]

for any \( [l, m] \subset \mathbb{Z} \). Define a state \( \mu \) on \( \mathfrak{B} \) by

\[
\mu(P_J) = \omega_J(1), \quad P_J \in \mathfrak{B}_{[l,m]} 
\]

where for \( J \in \{1, 2, \ldots, d'\}^{[l,m]} \), \( P_J = J_l(P_{i_1}) \cdots J_m(P_{i_m}) \). Then it follows that

\[
\sum_{J \in \{1, 2, \ldots, d'\}^{[l,m]}} \eta(\omega_J(1)) = S_\mu(\mathfrak{B}_{[l,m]}),
\]

where \( S_\mu(\mathfrak{B}_{[l,m]}) \) is the classical entropy. Since the classical mean entropy exists, we have

\[
\lim_{n \to \infty} \lim_{k \to \infty} \frac{1}{k n} \left\{ \sum_{J \in \mathcal{I}} \mu(\omega_J(1)) - k \sum_{I \in \{1, 2, \ldots, d'\}^n} \eta(\omega_I(1)) \right\} = 0. \quad (4.9)
\]
We now use (4.1), (4.2) and (4.8). We then divide both sides of (4.8) by $nk$ and take the limits. Then Theorem 4.2 follows from (4.9) and Proposition 4.1. This completes the proof of the main theorem for $l = 1$. □

Next we prove Proposition 4.1. We first need the following lemma:

**Lemma 4.2.** Let $\mathcal{H}$ be a finite dimensional Hilbert space and let $\mathcal{A}$ be a subalgebra of $\mathcal{L}(\mathcal{H})$. For given minimal projection $P \in \mathcal{A}$ and $A \in \mathcal{A}$, put

$$Q = APA^*/\text{Tr}(APA^*).$$

Then $Q$ is a minimal projection in $\mathcal{A}$.

**Proof.** Since $\mathcal{A}$ is isomorphic to $\oplus_{j=1}^{d} M_{n_j}$, one may assume that any minimal projection is a rank one projection. We first show that $Q$ is a projection. Since

$$Q^2 = APA^*APA^*/(\text{Tr}(APA^*))^2,$$

and since $PA^*AP = \lambda P$ by the minimality of $P$, where $\lambda = \text{Tr}(PA^*AP)$, it follows that $Q^2 = Q$. Since $APA^*$ is a rank one operator, $Q$ is a minimal projection. □

**Proof of Proposition 4.1.** Recall the definition of $\omega_I$:

$$\omega_I(y) = \text{Tr}(K_{[0,n+1]}^* P_I J_0(W_0) K_{[0,n+1]} y), \ y \in \mathbb{A}_{[1,n]}.$$

Notice that $\{P_I : I \in \{1,2,\cdots,d'\}^n\}$ is a family of minimal projections in $\mathbb{A}_{[1,n]}$ such that $\sum P_I = 1$. We denote by $\omega'_I$ the positive linear functional on $\mathbb{A}_{[0,n+1]}$ defined by the above relation for $y \in \mathbb{A}_{[0,n+1]}$:

$$\omega'_I(y) = \text{Tr}(K_{[0,n+1]}^* P_I J_0(W_0) K_{[0,n+1]} y), \ y \in \mathbb{A}_{[0,n+1]}.$$  \hfill (4.10)

Notice that $\omega'_I|\mathbb{A}_{[1,n]} = \omega_I|\mathbb{A}_{[1,n]}$. We first express the state $\delta_I' (= \omega'_I/\omega'_I(1))$ as a finite convex combination of pure states on $\mathbb{A}_{[0,n+1]}$ as follows: Consider $J_0(W_0)$ as a self-adjoint element in $J_0(M_0)$. Then $J_0(W_0)$ can be diagonalized as

$$J_0(W_0) = \sum_{i=0}^{d'} \lambda_i q_i.$$
where each $q_j$ is a minimal projection in $J_0(M_0)$. Thus as an element in $A_{[0,n+1]}$, $P_I J_0(W_0)$ can be written as

$$P_I J_0(W_0) = \sum_{j=1}^{d'^2} \hat{\lambda}_j \tilde{\rho}_j$$

where each $\tilde{\rho}_j$ is a minimal projection in $A_{[0,n+1]}$. For a given $j \in \{1, 2, \cdots, d'^2\}$, let $\tilde{\omega}_j$ be the state on $A_{[0,n+1]}$ defined by

$$\tilde{\omega}_j(\gamma) = \text{Tr} \left( K_{[0,n+1]}^j \tilde{\rho}_j K_{[0,n+1]} \gamma \right) / \left( \text{Tr} K_{[0,n+1]}^j \tilde{\rho}_j K_{[0,n+1]} \right).$$

Then it follows that there exist $\beta_j \geq 0$, $j = 1, \cdots, d'^2$, such that $\sum_j \beta_j = 1$ and

$$\tilde{\omega}_j^j(\gamma) = \sum_{j=1}^{d'^2} \beta_j \tilde{\omega}_j(\gamma), \quad \gamma \in A_{[0,n+1]}.$$

For any finite subset $A \subset \mathbb{Z}$, put $A_{[0,n+1]} = (C^d)^A$. Notice that, if the state $\tilde{\omega}_j$ on $A_{[0,n+1]}$ is extended to $\mathcal{L}(A_{[0,n+1]})$ by the means of the density matrix of $\tilde{\omega}_j$ in $A_{[0,n+1]}$, it follows that $S(\tilde{\omega}_j|A_{[0,n+1]}) = S(\tilde{\omega}_j|\mathcal{L}(A_{[0,n+1]}))$. Analogous equalities for $S(\tilde{\omega}_j|A_{[1,n]})$ and $S(\tilde{\omega}_j|A_{[0,n+1]})$ hold. Thus one can apply the triangle inequality and the convexity relation [4, Proposition 6.2.25] for entropies to obtain

$$S(\tilde{\omega}_j|A_{[1,n]}) = S(\tilde{\omega}_j|A_{[1,n]}) \leq S(\tilde{\omega}_j|A_{[0,n+1]}) + S(\tilde{\omega}_j|A_{[0,n+1]})$$

and

$$S(\tilde{\omega}_j|A_{[0,n+1]}) \leq \sum_{j=1}^{d'^2} \beta_j S(\tilde{\omega}_j) + \sum_{j=1}^{d'^2} \eta(\beta_j)$$

respectively. Since $\tilde{\rho}_j$ is minimal in $A_{[0,n+1]}$, it follows from Lemma 4.2 and (4.11) that $\tilde{\omega}_j$ is a pure state on $A_{[0,n+1]}$ and so $S(\tilde{\omega}_j) = 0$ for all $j = 1, 2, \cdots, d'^2$. Since $S(\tilde{\omega}_j|A_{[0,n+1]}) \leq \log(\dim(C^{d^2}))$ and $\sum_{j=1}^{d'^2} \eta(\beta_j) \leq \ln(d'^2)$, we obtain from the above inequalities that

$$S(\tilde{\omega}_j|A_{[1,n]}) \leq 4 \ln(d).$$

This proves the proposition completely. \qed
Finally we turn to the proof of the theorem for the general case. Let \( \{K_1, K_2, \cdots, K_l\} \subset M_0 \otimes M_0 \) be the set of conditional density amplitudes and let the transition expectation \( \mathcal{E} \) be given by (2.12).

**Proof of Theorem 3.2 for \( l \geq 2 \).** We first construct a generalized quantum Markov chain \( \tilde{\mathcal{A}}, \alpha, \tilde{\omega} \) such that it is generated by a density matrix \( \tilde{W}_0 \) and a single conditional density amplitude \( \tilde{K} \), and such that \( (\tilde{\mathcal{A}}, \alpha, \tilde{\omega}) \) is a sub-dynamical system of \( (\overline{\mathcal{A}}, \alpha, \omega) \), i.e., \( \tilde{\omega}|\tilde{\mathcal{A}} = \omega \). We then apply the method employed in the proof for \( l = 1 \). Let us enlarge the algebra \( \tilde{\mathcal{A}} \) as follows. Let \( D_0 \subset M_l(C) \) be the algebra of \( l \times l \) diagonal matrices and let \( \{e_1, e_2, \cdots, e_l\} \) be the minimal projections in \( D_0 \). Put

\[
\tilde{M}_0 = M_0 \otimes D_0.
\]  

(4.14)

Denote by \( \tilde{\mathcal{A}} \) the \( C^* \)-algebra generated by the one site algebra \( \tilde{M}_0 \). For given density matrix \( W_0 \in M_0 \) and \( \{K_1, K_2, \cdots, K_l\} \subset M_0 \otimes M_0 \), we write that

\[
\tilde{W}_0 = l^{-1}W_0 \otimes 1_{D_0} \quad (\in \tilde{M}_0)
\]  

(4.15)

\[
\tilde{K} = l^{-1/2} \sum_{j=1}^l K_j \otimes (e_j \otimes 1_{D_0}) \quad (\in \tilde{M}_0 \otimes \tilde{M}_0).
\]

It is easy to check that \( \tilde{\omega}|\tilde{\mathcal{A}} = \omega \), and \( \tilde{W}_0 \) and \( \tilde{K} \) satisfy the condition analogous to that of (2.6). Let \( (\overline{\mathcal{A}}, \alpha, \omega) \) be the generalized quantum Markov chain constructed from the pair \((\tilde{W}_0, \tilde{K})\). For any subalgebra \( \mathcal{A} \subset \tilde{\mathcal{A}} \), let \( \gamma : \mathcal{A} \to \mathcal{A} \) be the embedding map. Then the following inequality

\[
H_\omega (\mathcal{A}_{[1,n]}, \mathcal{A}_{[n+1,2n]}, \cdots, \mathcal{A}_{[n(k-1)+1,nk]}) \\
\geq H_\omega (\gamma(\mathcal{A}_{[1,n]}), \gamma(\mathcal{A}_{[n+1,2n]}), \cdots, \gamma(\mathcal{A}_{[n(k-1)+1,nk]}))
\]

(4.16)

holds [5,10].

We introduce a decomposition of the state \( \tilde{\omega} \) similar to that given in (4.4)-(4.6). For fixed \( k \geq 1 \) and \( n \geq 1 \), let \( \tilde{I} \) be the multi-indices given by

\[
\tilde{I} = \left\{ \tilde{J} = (J_1, J_2, \cdots, J_k) : J_i \in \{(1,2,\cdots,d') \times \{1,2,\cdots,l\}\}^n \right\}
\]

(4.17)

For each \( J_i = ((i_1,j_1),\cdots,(i_n,j_n)) \in (\{1,2,\cdots,d'\} \times \{1,2,\cdots,l\})^n \), put

\[
\tilde{P}_{J_i} = J_{n(i-1)+1}(P_{i_1} \otimes e_{j_1}) \cdots J_{nl}(P_{i_n} \otimes e_{j_n})
\]

(4.18)
and for given \( \tilde{J} = (J_1, \ldots, J_n) \) we write

\[
\tilde{P}_j = \tilde{P}_{j_1} \tilde{P}_{j_2} \cdots \tilde{P}_{j_n}
\]

for the index set \( \tilde{I} \), let

\[
\sum_{j \in \tilde{I}} \tilde{\omega}_j = \tilde{\omega}
\]

be the decomposition of the state \( \tilde{\omega} \) obtained by replacing \( \tilde{W}_0, \tilde{K}, \) and \( \tilde{J} \) by \( \tilde{W}_0, \tilde{K}, \) and \( \tilde{J} \) respectively in (4.3)-(4.7). We then have the result analogous to Proposition 4.1:

**Proposition 4.3.** There exists a constant \( c \) independent of \( n \in \mathbb{N} \) and \( I \in (\{1, 2, \ldots, d'\} \times \{1, 2, \ldots, l\})^n \) such that the bound

\[
S(\tilde{\omega}_I|\gamma(\mathfrak{A}_{[1,n]})) \leq c
\]

holds uniformly in \( n \) and \( I \).

Now the proof of Theorem 3.2 for \( l \geq 2 \) follows from (4.16), Proposition 4.3 and the method used in the proof of Theorem 3.2 for \( l = 1 \). We only note that \( S(\tilde{\omega}_I|\gamma(\mathfrak{A}_{[1,n]})) = S(\omega|\mathfrak{A}_{[1,n]}) \), and leave the detailed proof to the reader. \( \Box \)

**Proof of Proposition 4.3.** Let \( \tilde{\omega}^I \) be the positive linear functional on \( \tilde{\mathfrak{A}}_{[0,n+1]} \) defined by a relation analogous to that in (4.10). As the relation in the above of (4.11), one may write

\[
\tilde{P}_I J_0 (\tilde{W}_0) = \sum_{j=1}^{(td')^2} \tilde{\lambda}_j \tilde{q}_j
\]

where each \( \tilde{q}_j \) is a minimal projection in \( \tilde{\mathfrak{A}}_{[0,n+1]} \). Then as in (4.12) we have

\[
\tilde{\omega}^I(y) = \sum_{j=1}^{(td')^2} \beta_j \tilde{\omega}_j(y), \quad y \in \tilde{\mathfrak{A}}_{[0,n+1]},
\]

where each \( \tilde{\omega}_j \) is a pure state on \( \tilde{\mathfrak{A}}_{[0,n+1]} \).
Next, one may use the argument similar to that used in the proof of (4.13) to derive
the inequality
\[
S \left( \tilde{\omega}_I | \gamma(\mathcal{A}_{[1,n]}) \right) \leq S \left( \tilde{\omega}_I | \gamma(\mathcal{A}_{[0,n+1]}) \right) + S \left( \tilde{\omega}_I | \gamma(\mathcal{A}_{[0,n+1]}) \right).
\]
That is, extend the state \( \tilde{\omega}_I | \gamma(\mathcal{A}_{[0,n+1]}) \) to \( \mathcal{L}(\mathcal{D}_{[0,n+1]}) \) by the density matrix of \( \tilde{\omega}_I \), and then use the triangle inequality for entropies. Notice that
\[
\mathcal{A}_{[0,n+1]} = \mathcal{A}_{[0,n+1]} \otimes \mathcal{D}_{[0,n+1]},
\]
where \( \mathcal{D}_I = \bigotimes_{n \in I} \mathcal{J}_n(\mathcal{D}_0) \) is an abelian algebra for each \( I \subset \mathbb{Z} \). Since each state \( \tilde{\omega}_j \) in (4.22) is pure, there exist pure states \( \rho_{j,1} \) and \( \rho_{j,2} \) on \( \mathcal{A}_{[0,n+1]} \) and \( \mathcal{D}_{[0,n+1]} \) respectively such that
\[
\tilde{\omega}_j = \rho_{j,1} \otimes \rho_{j,2}.
\]
Thus \( S \left( \tilde{\omega}_j | \gamma(\mathcal{A}_{[0,n+1]}) \right) = S(\rho_{j,1}) = 0 \), and so the proposition follows from the argument similar to that used in the below of (4.13). This completes the proof of Proposition 4.3.

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References


