Estimates for the Luminosity Function of Galaxies and its Evolution

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ABSTRACT
A new method is presented to obtain a non-parametric maximum likelihood estimate of the luminosity function and the selection function of a flux limited redshift survey. The method parameterizes the selection function as a series of step-wise power laws and allows possible evolution of the luminosity function. We also propose a new technique to estimate the rate of evolution of the luminosity function. This is based on a minimization of the observed large-scale power with respect to the evolutionary model. We use an ensemble of mock surveys extracted from a N-body simulation to verify the power of this method.

We apply our estimators to the 1.2-Jy survey of IRAS galaxies. We find a far-infrared luminosity function in good agreement with previously published results and evidence for rather strong evolution. If the comoving number density of IRAS galaxies is assumed to scale $\propto (1 + z)^P$, we estimate $P = 4.3 \pm 1.4 \pm 1$.

Key words: methods: statistical – galaxies: evolution – infrared: galaxies.

1 INTRODUCTION

Flux limited redshift surveys are a major tool for studying the large-scale structure of the Universe. However, such catalogues show a strong decline of the mean number density of galaxies as a function of distance, simply because at larger distances more and more galaxies fall below the apparent flux limit. Most of the statistics that are used to analyse these surveys require an accurate knowledge of this dependence, which is described in terms of the selection function (SF). Hence the accuracy of the adopted SF can limit the reliability of such large-scale structure studies.

Closely related to the SF is the luminosity function (LF), which describes the distribution in luminosity of the galaxy population sampled by the particular redshift survey. This quantity is of more fundamental importance, since it should be reproduced by any viable theory of galaxy formation and evolution.

Here we revisit the problem of determining the LF and SF, given only the data of a flux limited redshift survey. Current standard methods for this task include Schmidt's $\frac{V}{V_{\text{max}}}$ estimator, and the maximum likelihood techniques first introduced by Turner and Sandage, Tamman & Yahil. The maximum likelihood methods are generally superior to the older techniques because they allow the construction of estimators which are not systematically biased by density inhomogeneities. For this reason we will focus on them in the following.

Two basic procedures have been used to find maximum likelihood estimates of the LF. In the so-called parametric maximum likelihood estimate an analytic form for the LF (or SF) is assumed that depends on a few (typically two to four) parameters. These are then determined by maximizing the likelihood of the observed data set.

However, because the maximum likelihood technique offers no built-in measure of goodness-of-fit, almost any functional form can be made to 'fit', although the function may provide only a poor description of the data. The parametric technique therefore requires an a priori knowledge of a suitable fitting form.

If this information is not available one can allow a very flexible shape of the LF by describing it by many parameters in a reasonable way. This so-called step-wise non-parametric maximum likelihood method has been used both to find luminosity functions and to estimate the run of radial density with distance. So far these applications only employed simple step functions to model the desired function.

In this paper we propose a non-parametric maximum likelihood estimator that uses a new parameterization in terms of piece-wise power laws. This method provides accurate information on the shapes of the SF and the LF and has a number of computational advantages. For example, it does not require iterative solutions and it provides error-estimates easily. The method is particularly useful for justifying specific analytic fitting forms for the SF and LF.

We also discuss ways to estimate evolution of the LF. Such evolution appears quite strong in the far-infrared. A
2 A NON-PARAMETRIC ESTIMATOR FOR THE SELECTION FUNCTION

2.1 Definitions

Let the field \( n_s(r, L) \, dL \) describe the comoving number density of galaxies at epoch \( z \), in the luminosity interval \([L, L + dL]\) and at comoving spatial position \( r \). Assuming that the luminosity distribution is independent of clustering the number density field may be written as

\[
n_s(r, L) = \frac{n_s(r)}{\bar{n}_s} \Phi_s(L), \tag{1}
\]

where \( \Phi_s(L) \) describes the LF. Here \( n_s(r) = \int_0^\infty n_s(r, L) \, dL \) is the local number density and \( \bar{n}_s = \langle n_s(r) \rangle \) signifies the mean number density, averaged over many realizations of the Universe. The LF is normalized as \( \int_0^\infty \Phi_s(L) \, dL = \bar{n}_s \) and the dependence on \( z \) takes care of a possible time evolution, if present. The luminosity cut \( L_0 \) may be used to handle a possible formal divergence of the integral over \( \Phi_s(L) \) at the lower end.

We define the selection function \( S(z) \) as the mean comoving number density of galaxies that one expects to see in a flux limited survey at redshift \( z \). Then \( S(z) \) is given by

\[
S(z) = \int_{L_{\text{min}}(z)}^\infty \Phi_s(L) \, dL, \tag{2}
\]

where \( L_{\text{min}}(z) \) denotes the minimum luminosity a source at redshift \( z \) may have without falling below the flux limit of the catalogue. In this work we neglect the peculiar velocities of galaxies and take all redshifts to be cosmological, i.e. we adopt a simple redshift-distance relation \( z = z(|r|) \).

2.2 The likelihood expression

We now imagine that the catalogue is drawn from an underlying parent distribution given by \( n_s(r, L) \) for \( L \geq L_{\text{min}}(z) \) and by 0 for \( L < L_{\text{min}}(z) \), where \( z = z(|r|) \). Then the conditional probability \( p(L_i|z_i) \, dL \) that a source observed at redshift \( z_i \) falls into the luminosity range \([L_i, L_i + dL]\) takes the form

\[
p(L_i|z_i) \, dL = \frac{n_{z_i}(r_i, L_i) \, dL}{\int_{L_{\text{min}}(z_i)}^\infty n_{z_i}(r_i, L') \, dL'}. \tag{3}
\]

The denominator simply counts the available number of galaxies at that distance and the numerator gives the number of galaxies in the particular luminosity range. Upon insertion of equations (1) and (2) this becomes

\[
p(L_i|z_i) = \frac{\Phi_{z_i}(L_i)}{S(z_i)}. \tag{4}
\]

Note that the density fluctuations have dropped out of this expression and so the dependence on \( r \) can be dropped in equation (3). This insensitivity to density inhomogeneities makes the maximum likelihood technique used here superior compared to older methods like the ordinary \( V/V_{\text{max}} \) estimator. If one now maximizes the likelihood

\[
\mathcal{L} = \prod_i p(L_i|z_i) \tag{5}
\]

of the whole data set with respect to \( S(z) \) one obtains an estimate of the SF that is not systematically biased by local density fluctuations.

In order to find this maximum in practice we first express \( \Phi_{z_i}(L_i) \) in terms of the SF with the help of equation (2). Here a model for the evolution of the LF has to be specified. For brevity we will only treat a case with pure density evolution according to

\[
\Phi_s(L) = g(z)\Phi_0(L). \tag{6}
\]

However, our method can be easily generalized to include luminosity evolution as well.

We further define a maximal redshift \( z_i^m \) for each source such that \( L_{\text{min}}(z_i^m) = L_i \). If then the derivative \( S'(z) \) of equation (2) is evaluated at \( z_i^m \) one obtains

\[
S'(z_i^m) = -\frac{g(z_i^m)}{g(z_i^m)} \Phi_s(L_i)L_{\text{min}}(z_i^m) + \frac{g'(z_i^m)}{g(z_i^m)} S(z_i^m), \tag{7}
\]

so that the probability of equation (4) can be expressed entirely in terms of \( S(z) \) and \( g(z) \). Hence one finally has to maximize

\[
\Lambda = \ln \mathcal{L} = \sum_i \ln \left( \frac{-S'(z_i^m)}{S(z_i)} + \frac{g'(z_i^m)}{g(z_i^m)} \frac{S(z_i^m)}{S(z_i)} \right) + \sum_i \ln \left( \frac{g(z_i)}{g(z_i^m)} \right) - \sum_i \ln L_{\text{min}}(z_i^m), \tag{8}
\]

where the constant sum of the last term may be dropped.

The above form suggests that one might be able to maximize \( \Lambda \) simultaneously for \( g(z) \) and \( S(z) \). However, if equation (4) is rewritten for the density evolution model it becomes

\[
p(L_i|z_i) = \frac{g(z_i)\Phi_0(L_i)}{\int_{L_{\text{min}}(z_i)}^\infty g(z_i)\Phi_0(L) \, dL} = \frac{\Phi_0(L_i)}{\int_{L_{\text{min}}(z_i)}^\infty \Phi_0(L) \, dL}. \tag{9}
\]

So the function \( g(z) \) drops out completely and there is no sensitivity to density evolution with this estimator. In fact, this was to be expected since estimates based on the likelihood (4) are independent of the density distribution by construction.
2.3 A non-parametric maximum likelihood estimator

Here we propose a new variant of the non-parametric method that models \( S(z) \) as a series of continuously linked power laws. This description seems appropriate since the SF is a smooth curve that covers a wide range of values and its local behaviour can be very well approximated by a power law.

We describe \( S(z) \) by \( n \) pieces. Let \( S_k = S(x_k) \) be the values of \( S(z) \) at a series of ascending redshifts \( x_k \) where \( k \in \{1, 2, \ldots, n\} \). Then bin 1 covers \( 0 < z \leq x_1 \), bin 2 covers \( x_1 < z \leq x_2 \), and so forth. In each piece \( k \), \( S(z) \) is taken to be a power law of the form

\[
S(z) = S_k \left( \frac{z}{x_k} \right)^{m_k} \quad \text{for} \quad x_{k-1} < z \leq x_k,
\]

where \( m_k \) is the logarithmic slope of the particular piece. These slopes are precisely the quantities needed to characterize the shape of the SF.

The different pieces have to join continuously, because \( S(z) \) is an integral over the LF. Continuity requires the \( m_k \) to be defined by

\[
S_k = S_1 \prod_{j=2}^{k} \left( \frac{x_j}{x_{j-1}} \right)^{m_j} \quad \text{for} \quad 1 < k \leq n .
\]

Let us further define \( a_i \) as the number of the bin to which the maximal redshift \( z_i^m \) of galaxy \( i \) belongs. Similarly, let \( b_i \) be the number of the interval that encloses the redshift \( z_i \) of galaxy \( i \). Then the likelihood (8) takes the form

\[
\Lambda = \sum_i \left[ \ln \left( -\frac{m_{a_i}}{z_i^m} \right) + m_{a_i} \ln \frac{g(z_i^m)}{g(z_i)} \right] + \sum_i m_j \ln \frac{z_i}{x_{j-1}} + \sum_i m_{b_i} \ln \frac{z_i}{x_{b_i}} + \sum_i \ln g(z_i^m) - \ln L_{\text{min}}(z_i^m).
\]

The best estimates for the \( m_k \) can be found by solving the likelihood equations

\[
\frac{\partial \Lambda}{\partial m_k} = \sum_i \delta_{k, a_i} \left( \frac{z_i}{x_{i-1}} \right)^{2m_k} \ln \frac{g(z_i^m)}{g(z_i)} + T_k = 0,
\]

where \( T_k \) is defined as

\[
T_k = \sum_{i = b_{i-1}}^{a_i} \delta_{j, k} \ln \frac{x_j}{x_{j-1}} + \sum_i \delta_{k, a_i} \ln \frac{z_i}{x_{a_i}} - \sum_i \delta_{k, b_i} \ln \frac{z_i}{x_{b_i}}.
\]

The equations (12) are not fully linear in \( m_k \), but almost. Since the redshift bins are narrow, replacing \( z_i^m \) by \( x_{a_i} \) will give a useful first approximation \( \tilde{m}_k \) to the true solution \( m_k \), which might then quickly be improved by an iteration technique. This starting value can be calculated as

\[
\tilde{m}_k = -\frac{m_k}{T_k} + x_k \left \frac{g(x_k)}{g(x_{a_k})} \right ,
\]

where \( n_k \) is the number of galaxies in bin \( k \). Note that in the case of no evolution the solution to equation (12) is simply given by \( m_k = -n_k T_k^{-1} \).

The maximum likelihood method also allows an estimate of the statistical uncertainties of the derived parameters (7). Asymptotically the distribution of \( \mathcal{L} \) is a multivariate Gaussian around the true values of the parameters. If the information matrix \( I \) is defined as

\[
I_{ij} = -\left \frac{\partial^2 \mathcal{L}}{\partial m_i \partial m_j} \right ,
\]

then the covariance matrix of the parameter estimates is given by \( \text{cov}(m_i, m_j) = (I^{-1})_{ij} \) evaluated at the maximum of \( \mathcal{L} \). This result holds asymptotically for large sample sizes.

Because the \( T_k \) don’t explicitly depend on any of the \( m_k \) the information matrix is simply found to be

\[
I_{kk} = \delta_{k, a_i} \sum_i \left ( \frac{z_i}{m_k - z_i^m \frac{g(z_i^m)}{g(z_i)}} \right )^2.
\]

One can therefore trivially invert this diagonal matrix and find error estimates for the \( m_k \) as

\[
\text{var}(m_k) = \sum_i \left ( \frac{z_i}{m_k - z_i^m \frac{g(z_i^m)}{g(z_i)}} \right )^2 \approx \frac{m_k^2}{n_k}.
\]

This is a surprisingly simple result. In particular, one can solve for each of the \( m_k \) independent of all the others. The \( m_k \) are mutually uncorrelated which shows that it is essentially the local logarithmic slope of the SF that is determined by the maximum likelihood estimator (5).

Once the non-parametric estimate of the shape of the SF is found, it can be used to find and justify an appropriate analytic fitting function for \( S(z) \). For this purpose one can directly employ a minimum \( \chi^2 \) fit of the \( m_k \) to the logarithmic slope of some fitting form for \( S(z) \). Of course, once an analytic form has been selected in this way, the values of its parameters can also be determined with the parametric maximum likelihood technique by using the fitting form directly in equation (8).

2.4 Normalization

Because the normalization of the SF is lost with the above estimator it has to be found in a second step. For this purpose we write the SF as

\[
S(z) = \psi s(z),
\]

where \( s(z) \) is the shape of the SF as determined above. Then an unbiased estimate \( \tilde{\psi} \) of the factor \( \psi \) is given by

\[
\tilde{\psi} = \frac{\int V m(r) w(r) \, dr}{\int V s(r) w(r) \, dr},
\]

for an arbitrary weight function \( w(r) \). Here \( m(r) = \sum_i \delta(r-r_i) \) represents the observed galaxy field and we employ the shorthand notation \( s(r) = s(z(r)) \).

Following Davis & Huchra (7) we choose the weight function \( w(r) \) such that the expected variance of \( \tilde{\psi} \) is minimized. This is to a good approximation the case for

\[
w(r) = \frac{1}{1 + J_3 \psi s(r)},
\]

where \( J_3 = \int_V 4\pi r^2 \xi(r) \, dr \) is the second moment of the two-point correlation function and \( V \) denotes the volume used in the normalization.
Note that the normalization estimate has to be found iteratively since the estimator depends implicitly on $\psi$. One also needs a model for the two-point correlation function in order to estimate $J_3$. However, this is uncrical because the dependence on $J_3$ is usually quite weak. Hence an estimate of $J_3$ based on a linear theory CDM power spectrum should be entirely sufficient.

The numerical value of $\psi$ itself does not provide a meaningful measure for the local number density of galaxies. In fact, such a measure is not well defined for a purely flux limited catalogue. Instead, the normalization is perhaps best expressed in terms of the expected number density $N$ of galaxies per unit solid angle on the sky, i.e.

$$N = \frac{1}{4\pi} \int S(z) \frac{4V}{dz} dz. \quad (21)$$

### 3 A NON-PARAMETRIC ESTIMATOR FOR THE LUMINOSITY FUNCTION

Using equation (2) it is possible to recover the underlying luminosity distribution if the SF is known, or vice versa. In particular one can readily derive a non-parametric LF estimate from the SF estimator described in the previous section.

We suppose that the SF has been determined with the estimator described above and that the function $L_{\text{min}}(z)$ and its inverse $z_{\text{max}}(L)$ are known. The piecewise description of the SF directly translates into a piecewise description of the LF if boundaries $L_k$ of luminosity intervals are defined by $L_k \equiv L_{\text{min}}(x_k)$. Upon evaluation of the derivative of equation (2) at $z = z_{\text{max}}(L)$ the present day LF results as

$$\Phi_0(L) = \left( \frac{g'(z_{\text{max}})}{g(z_{\text{max}})} S(z_{\text{max}}) - S'(z_{\text{max}}) \right) \times \left( g(z_{\text{max}}) L_{\text{min}}'(z_{\text{max}}) \right)^{-1}. \quad (22)$$

This translates into the piecewise description

$$\Phi_0(L) = \left( \frac{g'(z_{\text{max}})}{g(z_{\text{max}})} - \frac{m_k}{z_{\text{max}}} \right) \left( \frac{z_{\text{max}}}{x_k} \right)^{m_k} \times \frac{S_k}{g(z_{\text{max}}) L_{\text{min}}'(z_{\text{max}})} \quad (23)$$

for $L_{k-1} < L < L_k$, which is the desired non-parametric estimate.

The usual way to find a non-parametric maximum likelihood estimate of the LF utilizes a parameterization by a series of step functions $(T; T')$. We see two main advantages of our method as compared to this approach.

First, the shape of the LF over each bin is approximately a power law, so it is able to adapt to the true shape of the LF in a flexible way. Only very small discontinuities at the boundaries of bins remain and the estimate $\Phi_0(L)$ of equation (23) traces the smooth LF quite well. The conventional estimator on the other hand assumes constant $\Phi_0$ over each bin which leads to large discontinuous jumps in the LF at bin boundaries. Efstathiou et al. (7) show that the heights $\Phi_i$ of these bins are related by

$$\Phi_k \approx \frac{\int_{L_k}^{L_k+\Delta L/2} \Phi dN(L) / \int_{L_k}^{L_k+\Delta L/2} dN(L)}{\int_{L_k-\Delta L/2}^{L_k-\Delta L/2} \Phi dN(L)}$$

to the underlying luminosity distribution. It is therefore more complicated to infer the smooth underlying LF from this non-parametric estimate.

A second nice feature is that the absence of correlations among the $m_k$ simplifies the estimation of errors in the LF. To demonstrate this let us define the values $\Phi_k \equiv \Phi_0(L_k)$ of the LF at the points $L_k$. In appendix A we compute the covariance matrix

$$V_{kl} = \text{cov}(\ln \Phi_k, \ln \Phi_l) \quad (24)$$

of these quantities. The matrix $V_{kl}$ may then be used to fit an analytic model $\Phi_k$ to the non-parametric LF estimate by minimizing the covariance form

$$\chi^2 = \sum_{i,k} (\ln \Phi_i - \ln \Phi_i)V_{ij}^{-1}(\ln \Phi_i - \ln \Phi_i). \quad (25)$$

Although not of major importance a further practical advantage of the estimator presented here is its relative computational ease. In particular one does not have to resort to lengthy iteration techniques as required by the conventional parameterization with a series of step functions.

### 4 ESTIMATING EVOLUTION

#### 4.1 The radial density distribution

As was demonstrated above, the estimators based on equation (4) are insensitive to density evolution. If the latter is important (as appears to be the case in the IRAS surveys) a different approach is needed to determine its rate.

Instead of $p(L_i | r_i)$ as before we can equally well write down the conditional probability

$$p(r_i | L_i) dr = 4\pi r^n_i n_z(r_i, L_i) dr \int_0^{L_{\text{max}}} n_z(r, L_i) dV = 4\pi r^n_i n_z(r_i) dr \int_0^{L_{\text{max}}} n_z(r) dV \quad (26)$$

to find a galaxy with luminosity $L_i$ in a distance interval of width $dr$ at coordinate $r_i < L_{\text{max}}$. Here the density field has been averaged over direction and the definition $r_i \equiv \min(r^n_i, L_{\text{max}})$ allows an upper distance cut-off $L_{\text{max}}$ to be included. We consider the inclusion of the latter to be important because the density field is only known well to a finite depth. At large distances it is dominated by shot noise due to increasingly sparse sampling. In addition the completeness of most surveys is worst in this regime.

Equation (26) shows that the density distribution $n_z(r)$ can be estimated independent of the LF if

$$\Lambda = \sum_i \ln p(r_i | L_i) = \sum_i \ln \frac{n_z(r_i)}{\int_0^{r^n_i} n_z(r) dV} \quad (27)$$

is maximized with respect to $n_z(r)$. Saunders et al. (7) have used a parameterization of $n_z(r)$ in terms of a series of step functions leading to a non-parametric radial density estimator. This estimator is quite useful since it can indicate the presence of evolution and it can show the most prominent density features.

#### 4.2 The constant density method

In order to obtain an estimate of the evolutionary rate Saunders et al. (7) proposed replacing $n_z(r)$ in equation (26) by the expected mean density $\bar{n}_z = \bar{n} g(z)$ at epoch $z = z(r)$. Adopting an evolutionary model, for example
\[ g(z) = (1 + z)^P, \]  
(28)
one can then find the rate by maximizing
\[ \Lambda = \sum_i \ln \left( \frac{(1 + z)^P}{\int_{z_{\min}}^{x_i} (1 + z)^P \, dz} \right) \]  
(29)\]
with respect to \( P \). A number of subsequent studies (\text{?}, \text{?}) also applied this method to IRAS galaxies.

Of course, in reality the galaxies are not distributed uniformly. This fact leads to a serious drawback of the above estimator; the resulting estimate of \( P \) might be strongly influenced by density inhomogeneities. For example, an overdensity in the foreground mimics negative evolution, whereas an overdensity in the background can bias the evolution low.

Since this effect should be strongest nearby, a lower redshift cut-off \( z_{\min} \), as introduced above, may be used to partly reduce its influence. However, as will be seen in our application to the 1.2-Jy survey the evolutionary estimates can depend quite strongly on the particular redshift interval chosen and it is unclear which choice gives the most reliable answer.

### 4.3 The minimal variance method

We here want to propose an alternative evolutionary estimator that avoids the unphysical neglect of density fluctuations and that gets rid of the arbitrary choice of redshift interval used in equation (29).

As shown above the data of the redshift survey alone do not allow us to disentangle density evolution and large-scale structure. This is only possible if the fundamental assumption of statistical homogeneity is added. In a pragmatic approach we might then base the determination of evolution on the notion that the correct rate should lead to a universe that looks as close as possible to homogeneous on very large scales. As a quantitative measure for deviations from homogeneity one might, for example, take the variance \( \sigma^2 \) of the density field smoothed on some large scale \( \lambda \). The determination of the evolution might therefore be formulated in terms of an extremal principle: The evolutionary rate can be estimated by minimizing the observed power on large scales.

To estimate \( \sigma^2 \) we apply a slightly modified version of the method of Saunders et al. (\text{?}). We first compute a smoothed galaxy density field
\[ d_i = \sum_j w_{ij} \frac{m_j}{S_j} \]  
(30)\]
on a fine mesh. Here \( m_j \) denotes the number of galaxies in cell \( j \), \( S_j \) is the value of the SF and \( w_{ij} = W(r_i - r_j) \) a smoothing kernel, which we here take to be a Gaussian of the form
\[ W(x) = \frac{1}{\pi^{3/2} \lambda^3} \exp \left( -\frac{|x|^2}{\lambda^2} \right). \]  
(31)\]

Then unbiased estimators for the mean \( \bar{d} \) and the variance \( \sigma^2 \) of the galaxy density field are given by
\[ \bar{d} = \frac{\sum_i g_i d_i}{\sum_i g_i}, \]  
(32)\]and
\[ \sigma^2 = \frac{\sum_i h_i \left( \frac{d_i - \bar{d}}{\bar{d}} \right)^2 - Y_i^{(2)}}{\sum_i h_i}, \]  
(33)\]where
\[ Y_i^{(n)} = d^{1-n} \sum_j w_{ij}^{n} S_j^{n-1}. \]  
(34)\]

These estimators become minimum variance estimators in a good approximation if the weights are chosen as
\[ g_i = \left[ Y_i^{(2)} \right]^{-1} \]  
(35)\]and
\[ h_i = \left[ Y_i^{(4)} + 2 \left( Y_i^{(2)} \right)^2 + 2\sigma^4 + 3 \left( Y_i^{(2)} \right)^2 + 4Y_i^{(3)} + 4Y_i^{(2)} \right]^{-1}. \]  
(36)\]

Since the estimate of the variance depends on the SF it becomes a function of the adopted evolutionary model used in computing the SF. It is therefore possible to estimate the evolutionary rate by minimizing \( \sigma^2 \).

A difficulty with this technique is that it does not easily supply an error estimate for the evolutionary rate. Additionally it is unclear how to choose \( \lambda \) in an optimal way. A large \( \lambda \) allows the survey volume to be probed to greater depth, thereby increasing the sensitivity to evolution. However, the number of independent smoothing volumes declines simultaneously, thereby degrading the accuracy of the variance estimate. What is then the optimal choice?

We solve both of these problems by extracting an ensemble of mock catalogues from a large N-body simulation. The mock surveys mimic the statistical properties of the survey at hand in terms of the SF, the evolution, the sky coverage and the source density. This suite of catalogues can be used to find the optimal \( \lambda \) and to estimate the precision of the final evolutionary estimate.

Although computationally somewhat lengthy this scheme is well worth the effort because it offers an increased accuracy as we will demonstrate with the mock surveys in our application to the 1.2-Jy survey. A further advantage is that it is equally applicable to luminosity evolution, in contrast to the estimator discussed in section 4.2.

### 5 APPLICATION TO THE 1.2-JY REDSHIFT SURVEY

The data of the 1.2-Jy redshift survey (\text{?}) of IRAS galaxies has been published (\text{?}) and can be retrieved electronically from the Astronomical Data Center (ftp://adc.gsfc.nasa.gov). The 5321 galaxies of the survey are selected from the PSC catalogue above a flux limit of 1.2 Jy in the 60 \( \mu \)m band. The sky coverage is 87.6 per cent, excluding only the zone of avoidance for |\( b | < 5^\circ \) and a few unobserved or contaminated patches at higher latitude.

We convert the redshifts to the Local Group frame and use them subsequently to infer distances without further corrections for peculiar velocities.
5.1 K-correction and maximal redshift

The estimators presented above demand an accurate computation of the maximal redshift $z_i^m = z_{\text{max}}(L_i)$ that a given source could have without falling below the flux limit. A detailed calculation of this quantity involves K- and colour-corrections, which require a knowledge of the spectral energy distribution (SED) of the source, a specification of the responsivity $R(\nu)$ of the detector, and a choice for the cosmological background model.

For the case of the IRAS surveys Fisher et al. (?) have phrased this problem in terms of the useful equation

$$\frac{f_{\text{min}}}{f_i} = \frac{r_i^2}{r(z_i^m)^2} \frac{\Psi(\eta)}{\eta},$$

(37)

which implicitly specifies $z_i^m$ in a general form. Here $f_i$ is the quoted flux density of a source and $r_i$ is its comoving coordinate distance. $f_{\text{min}}$ gives the flux limit of the catalogue and $\eta$ is defined as $\eta = (1 + z_i^m)(1 + z)^{-1}$. The function

$$\Psi(\eta) = \frac{\int R(\nu) f_m(\nu \eta) \, d\nu}{\int R(\nu') f_m(\nu') \, d\nu'}$$

(38)

encodes K- and colour-corrections by means of the observed flux density $f_m(\nu)$ of the source. The cosmological background model enters via the function $r = r(z)$. We will adopt an Einstein-de-Sitter universe, i.e.

$$r(z) = \frac{2}{a_0 H_0} \left( 1 - \frac{1}{\sqrt{1+z}} \right).$$

(39)

The 60 $\mu$m band SED of IRAS galaxies might be approximated as a straight power law $L_{60}(\nu) \propto \nu^\alpha$ with $\alpha \approx -2$. In this case $\Psi(\eta) = \eta^\alpha$. We have typically used $\alpha = -2$, but also tried a gray-body model (?) fitted to 60 $\mu$m/100 $\mu$m flux ratios and the polynomial model of Fisher et al. (?) which results in a considerably shallower SED.

5.2 Selection function

In our determination of the SF and LF we will assume that the LF exhibits density evolution of the form $g(z) = (1 + z)^{\beta} \nu$ with $P = 4.3$. The actual estimation of the evolutionary rate is discussed below in section 5.4.

Figure 1 shows the estimated local slopes $m_k$ of the SF and a fit based on the functional form

$$S(z) = \frac{\psi}{z^\alpha (1 + (\frac{z}{z^*})^\gamma)^{\beta/\gamma}},$$

(40)

We used 40 redshift intervals, logarithmically spaced between $x_0 = 0.003$ and $x_39 = 0.15$, for the non-parametric estimate. A minimum $\chi^2$ fit of the measured $m_k$ to the form of equation (40) resulted in a reduced $\chi^2$ of 0.87 (for $\nu = 36$ degrees of freedom), which indicates a good fit. This form of the SF is slightly more general than the one used by Yahil et al. (?) and Fisher et al. (?) who essentially fixed $\gamma$ at the value 2. This gives a marginally worse $\chi^2$ of 0.91.

Our best estimates for the final SF parameters are listed in table 5.2. They are obtained by maximizing the likelihood of the parametric form directly. Although a fit to the non-parametric estimate gives a very close result, we prefer these numbers as final estimates, because they are free of any binning effects. For each of the parameters $\alpha$, $\beta$, $\gamma$, and $z^*$ the quoted errors give 1$\sigma$ confidence intervals obtained from the bounding box of the $\Lambda_{\text{max}} - 0.5$ likelihood contour.

Figure 2 shows the ratio of Fisher et al.’s (?) SF to our estimate. The agreement is quite good out to redshift around 0.1. However, relative to our result the predicted mean density of galaxies at redshift 0.15 is about 20 per cent higher in the Fisher et al. (?) result.

In order to normalize the SF we used the volume inside $z = 0.15$. This determines the parameter $\psi$ and results in $N = (490 \pm 13)$ sr$^{-1}$ expected galaxies per unit solid angle on the sky. Our final LF is also normalized to this number. The 1$\sigma$ error-estimate is based on a direct computation of the variance of $\psi$ by means of equation (19). Here the uncertainty in the shape of $s(z)$ is neglected.

5.3 Luminosity function

Figure 3 displays our non-parametric estimate of the far-infrared LF resulting from the method outlined in section 3.

Table 1. Parameters of the selection function fit.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value (1$\sigma$ uncertainty)</th>
</tr>
</thead>
<tbody>
<tr>
<td>$\alpha$</td>
<td>0.741 (0.128)</td>
</tr>
<tr>
<td>$\beta$</td>
<td>4.216 (0.419)</td>
</tr>
<tr>
<td>$\gamma$</td>
<td>1.582 (0.237)</td>
</tr>
</tbody>
</table>

Table 1. Parameters of the selection function fit.
Estimates for the Luminosity Function of Galaxies and its Evolution

For comparison also shown is the non-parametric estimate of Saunders et al. (7) which takes the form of a histogram because it uses step functions to model the LF. In order to facilitate a comparison with the literature we present the LF in terms of luminosity per decimal decade of luminosity, viz.

\[
\phi(L) = \Phi_0(L) L \ln 10,
\]

and we define \( L \) for a source with SED \( L_\nu(\nu) \) as \( L = \nu L_\nu(\nu) \) at 60 \( \mu m \).

We believe that our parameterization offers an improved description of the LF, without large unphysical jumps due to binning of sparse data. In particular, the quality of a fit with an analytic function can be judged quite easily.

As a fitting form we use the function

\[
\phi(L) = C \left( \frac{L}{L_*} \right)^{1-a} \left( 1 + \frac{L}{L_*\beta} \right)^{-\beta}
\]

proposed by Lawrence et al. (7) and give the best-fit parameters in table 2. The fit is based on a minimization of the covariance form (25), imposing a fixed normalization as described in appendix A. The cited errors for \( \alpha, \beta \) and \( L_* \) give 68.3 per cent confidence intervals derived from an increase of \( \Delta \chi^2 = \chi^2 - \chi^2_{\text{min}} \) by 1, where \( \Delta \chi^2 \) is marginalized in the space of \( \alpha, \beta, L_* \), and \( C \). Figure 4 shows contour levels of constant \( \Delta \chi^2 \) in the subspace of \( \alpha \) and \( \beta \). The contour of \( \Delta \chi^2 = 2.3 \) encloses the 68.3 per cent joint confidence region of \( \alpha \) and \( \beta \). The error given in table 2 for the normalization \( C \) is computed for a fixed shape of the LF.

The simple-two power law (42) does a remarkably good job in fitting the measurements as evidenced by the comparison in figure 3 and by a reduced \( \chi^2 \) of 1.06. In particular we find no need to choose a functional form that shows more curvature over the full range of luminosities (7). However, we must not forget that we have ignored velocity fields in this paper and that we cannot go as faint as Saunders et al. (7) who used an additional set of very local galaxies. This might affect the faint end slope; we find a value not quite as shallow as Saunders et al. (7), but somewhat flatter than Yahil et al. (7).
Table 2. Parameters of the luminosity function fit.

\[
\begin{align*}
\alpha &= 1.221_{-0.072}^{+0.068} \\
\beta &= 2.110_{-0.079}^{+0.080} \\
L_* &= 3.615_{-0.568}^{+0.646} \times 10^9 \\
C &= (1.670 \pm 0.045) \times 10^{-2}
\end{align*}
\]

5.4 Evolution

Evidence for evolution in IRAS galaxies has been reported by a number of authors using differential source counts (\(?; \ ?; \ ?; \ ?\)) and redshift surveys (\(?; \ ?; \ ?; \ ?\)). However, there has been some controversy about the magnitude of the evolution rate seen in the far-infrared LF. Saunders et al. (\(?\)) found \(P = 7 \pm 2\) for the QCD survey, whereas Fisher et al. (\(?\)) gave \(P = 2 \pm 3\) for the 1.2-Jy survey, a result apparently consistent with no evolution. Oliver et al. (\(?\)) found \(P = 6.25 \pm 1.5\) for a survey of faint IRAS galaxies and \(P = 4.2 \pm 2.3\) for the QDOT survey. More recently Bertin et al. (\(?\)) report \(P = 6.0 \pm 1.2\) for the FIR sample.

The low result for the 1.2-Jy survey, obtained with the method of section 4.2, was based on an early version of the catalogue. Since evolutionary estimates are quite sensitive to completeness we here analyse the final catalogue again. This is also necessary because the evolutionary rate is needed as input parameter for the determination of the SF and LF.

5.4.1 The run of radial density

A first indication that a correct treatment of evolution is important may be obtained with the radial density estimator based on equation (27). We adopt a parameterization of \(n_d(r)\) in terms of 45 step-functions (with \(R_{\text{max}} = 400 \ h^{-1}\text{Mpc}\)) of widths chosen such that the signal-to-noise ratio in each bin stays roughly constant.

In the resulting distribution, displayed in figure 5, the average density seems to rise with distance. A similar behaviour is also found if smaller patches of the sky are examined separately. As an illustration we have split the sample in 4 regions of approximately equal size selected in terms of the modulus \(|b|\) of the galactic latitude. In this way we also obtain a low latitude sample which might be less complete than the other parts of the survey. In detail these regions, labeled B1-B4, cover \(|b| < 18^\circ\) (B1), \(18^\circ \leq |b| < 33^\circ\) (B2), \(33^\circ \leq |b| < 52^\circ\) (B3), and \(52^\circ \leq |b|\) (B4). As evidenced by figure 5 the rise of density with distance can be seen in all four subsamples, albeit with variable strength. Prominent structures are also visible, in particular Perseus-Pisces (around 50 \(h^{-1}\text{Mpc}\)) and the Local Supercluster, which is responsible for the nearby overdensity seen in B4.

5.4.2 Evolutionary estimates with the constant density method

We now turn to estimates of the density evolution parameter \(P\) obtained with the estimator of section 4.2. Table 3 shows results for various redshift intervals, in each case computed for the full catalogue and for the subsamples B1–B4.

Although the statistical errors are large, they are in-
sufficient to explain the large differences in the estimates that result when the redshift boundaries are changed. For example, when the upper redshift cut-off is lowered from \( \infty \) to 0.1, the low latitude sample B1 shows a marked increase in \( P \) which is likely to be the result of incompleteness at large \( z \). The sample B4 on the other hand exhibits a very strong overdensity nearby, that biases evolution low if it is not excluded by imposing a lower redshift cut-off.

We have tried many different redshift intervals and find it hard to come to definite conclusions with this method, simply because the result is strongly affected by density inhomogeneities and the choice of a redshift interval exhibits a certain degree of arbitrariness. We therefore prefer to estimate evolution with the minimum variance method outlined in section 4.3.

5.4.3 An ensemble of mock surveys

In order to demonstrate that this method is indeed more reliable we have constructed an ensemble of 1.2-Jy-like mock catalogues by observing a large N-body simulation of a standard CDM universe. The simulation has been kindly provided by the Virgo collaboration (\(?\)). It contains \( 256^3 \) particles in a periodic box of size \( V = L^3 \) with \( L = 240 \, \text{h}^{-1} \text{Mpc} \) and is normalized to fluctuations of \( \sigma_8 = 0.6 \) in spheres of \( 8 \, \text{h}^{-1} \text{Mpc} \). The details of this model are not of much relevance for the following, the salient point is that the model exhibits clustering in realistic strength.

By randomly placing an observer in the periodic box we constructed 50 mock catalogues of this simulation. We used a SF very similar to the 1.2-Jy survey (with parameters \( \alpha = 0.84, \beta = 3.96, \gamma = 1.74, z^* = 0.018 \)) and imposed density evolution with \( P = 5 \). The mock catalogues featured the same angular mask as the 1.2-Jy survey and were sampled to a density of 5321 galaxies inside 460 \( \text{h}^{-1} \text{Mpc} \). The suite of these catalogues simulates Poisson sampling noise and – to a reasonable degree – cosmic variance as well. The catalogues can be ideally used to test the performance of the various estimators discussed in this paper.

First we applied the constant density estimator of section 4.2 to these catalogues. Using the redshift interval \([0, 0.1]\) we obtained \( \langle P \rangle = 5.7 \) with an rms scatter of 2.4 among the individual measurements. This scatter is somewhat larger than the statistical error of \( \approx 1.9 \) provided by the likelihood method itself. Smaller redshift intervals also led to estimates \( \langle P \rangle \) close to 5, however with larger scatter.

Next we applied our new minimum variance method to the mock catalogues. For this purpose we computed maximum likelihood SF fits for 11 different values of \( P \) in the range 0 to 10 individually for each catalogue. This allows the computation of a curve \( \sigma^2_N(P) \) for each catalogue, and – by fitting the minimum with a parabola – an estimate of \( P \).

We treated the technical difficulty of the presence of an angular mask in the surveys by using the ratio method of Melott & Dominik (\(?\)) in the smoothing process. This means that we actually chose

\[
 w_{ij} = \frac{W(r_i - r_j)}{\int W(r_i - r') M(r') \, dr'} \tag{43}
\]

as kernel in equation (30), where \( M(r) \) is a field equal to 1 in the actual survey volume and equal to 0 in the volume behind the angular mask. The estimation of the variance is only done with cells inside the survey volume.

The method finally requires the choice of a smoothing length \( \lambda \). Since the minimum variance estimator automatically turns off when the signal-to-noise ratio becomes too low a larger \( \lambda \) usually means that the the survey is probed to higher depth, thereby increasing the sensitivity to evolution. On the other hand, the accuracy of the measurement of the variance degrades with increasing \( \lambda \) because the number of independent smoothing volumes in the usable survey volume declines. We find a choice for \( \lambda \) that represents a compromise between these two effects by minimizing the rms scatter of the \( P \) measurements for the mock catalogues.

For this purpose we have computed estimates of \( \langle P \rangle \) and its scatter for a range of smoothing lengths and find that the uncertainty is smallest for \( \lambda \approx 60 \, \text{h}^{-1} \text{Mpc} \), however, any \( \lambda \) in the range 50-80 \( \text{h}^{-1} \text{Mpc} \) works almost equally well. For \( \lambda = 60 \, \text{h}^{-1} \text{Mpc} \) we obtain \( \langle P \rangle = 5.3 \) with rms fluctuations of 1.4. This is a considerable improvement compared to the constant density method, nearly cutting the random error in half. This is possible because the new method eliminates most of the systematic influence of density inhomogeneities on the estimate of \( P \). The remaining uncertainty is mainly due to counting statistics.

5.4.4 Evolutionary estimate with the minimum variance method

The above results show that the new estimator for density evolution gives a more precise estimate than the constant density method. Hence we apply it now to obtain our best estimate for the density evolutionary rate of the 1.2-Jy survey. Adopting \( \lambda = 60 \, \text{h}^{-1} \text{Mpc} \) and using the same procedure as applied to the mock surveys we find \( P = 4.31 \pm 1.4 \), where the error estimate is based on the mock surveys.

Clearly, this error estimate is somewhat too optimistic, because the 1.2-Jy survey is not as perfectly selected as the mock catalogues. Additionally there are a number of systematic uncertainties that degrade the accuracy of the evolutionary measurement.

For example, the SED might be shallower as we assumed here, leading to an overestimate of evolution. The gray-body model (we find \( P = 3.9 \)) does only very little change compared to the straight \( \alpha = -2 \) SED used here. On the other hand, Fisher et al.’s (\(?\)) significantly flatter polynomial model lowers the evolutionary rate quite strongly to \( P = 3.0 \). However, the SED of this model is likely to be too flat. In addition to 60 \( \mu \text{m} \) and 100 \( \mu \text{m} \) it tries to simultaneously fit the 25 \( \mu \text{m} \) fluxes which are typically underpredicted by the gray-body model. However, only half of the galaxies (the bright ones at 25 \( \mu \text{m} \)) have detections in this band at all, so the polynomial model is biased towards a shallow SED. The polynomial model will also underpredict the slope of the SED if the spectra are indeed comprised of a cool and a warm component, as seems often to be the case (\(?\)).

Because the 1.2-Jy survey is quite local, a change of background cosmology to a low density universe has very little effect, increasing the estimated \( P \) very slightly.

More serious are potential problems with the IRAS flux scale. Either a baseline flux error with accompanying Malmquist bias, or a nonlinear flux scale could lead to a sig-
significant overestimate of the evolutionary rate. However, so far there is no convincing evidence that the IRAS PSC is troubled with flux errors of the strength required to explain a significant fraction of the evolutionary signal. For example, Oliver et al. (7) give an upper limit of 36 mJy for the baseline flux error of the PSC. At this level, Malmquist bias is not an issue, as we have checked with mock surveys that exhibit artificial flux errors.

We believe that our new method for estimating the evolutionary rate has removed most of the uncertainty due to density inhomogeneities. However, sample incompleteness can bias the evolution low if a fraction of the faint high redshift objects is missed. At low latitude, this is indeed quite likely the case for the 1.2-Jy survey.

We think that an error of $\pm 1$ represents a reasonable estimate of these systematic uncertainties. Our final estimate for evolution is therefore $P = 4.3 \pm 1.4 \pm 1$. Given the uncertainties, this result is in good agreement with other determinations of $P$ cited above. However, it is notably higher than Fisher et al.'s (7) result for an early version of the 1.2-Jy survey.

6 DISCUSSION

An accurate determination of the SF of a redshift survey is a prerequisite for taking full advantage of its information about the large-scale structure of the Universe. For example, statistical methods that rely on estimates of the density field in large survey volumes, like power spectrum measurements or genus statistics, depend crucially on a precise knowledge of the mean density as a function of distance.

In this work we have proposed a flexible non-parametric maximum likelihood estimator for the SF and LF. The method is independent of density inhomogeneities, gives accurate information on the shapes of SF and LF, and provides estimates of the statistical uncertainties of the derived quantities with relative computational ease. We think that the technique should be useful for upcoming redshift surveys.

We have also proposed a new method to estimate evolution of the LF, based on the notion that the Universe should look homogeneous on large scales. With an ensemble of mock surveys we have demonstrated that the uncertainties due to density inhomogeneities, which troubled previous estimators, can be greatly reduced in this way.

In our application of these estimators to the 1.2-Jy survey of IRAS galaxies we have found evidence for strong evolution, confirming reports by several previous authors. Expressed in terms of density evolution $\propto (1 + z)^P$, we find $P = 4.3 \pm 1.4 \pm 1$. This high evolutionary rate for the far-infrared LF is hard to explain as a statistical fluke. If confirmed the strong evolution of the far-infrared LF will represent an interesting challenge for theories of galaxy formation, interaction and evolution.

APPENDIX A1: COVARIANCE MATRIX OF THE NON-PARAMETRIC LUMINOSITY FUNCTION ESTIMATE

In this section we compute the covariance matrix

$$V_{ki} = \text{cov}(\ln \Phi_k, \ln \Phi_i)$$  \hspace{1cm} (A1)