Abstract

A three-dimensional reduction of the two-particle Bethe-Salpeter equation is proposed. The proposed reduction is in the framework of light-front dynamics. It yields auxiliary quantities for the transition matrix and the bound state. The arising effective interaction can be perturbatively expanded according to the number of particles exchanged at a given light-front time. An example suggests that the convergence of the expansion is rapid. This result is particular for light-front dynamics. The covariant results of the Bethe-Salpeter equation can be recovered from the corresponding auxiliary three-dimensional ones. The technical procedure is developed for a two-boson case; the idea for an extension to fermions is given. The technical procedure appears quite practicable, possibly allowing one to go beyond the ladder approximation for the solution of the Bethe-Salpeter equation. The relation between the three-dimensional light-front reduction of the field-theoretic Bethe-Salpeter equation and a corresponding quantum-mechanical description is discussed.
I. INTRODUCTION

In relativistic field theory the Bethe-Salpeter equation (BSE) \[1\] describes two-particle systems in interaction. The inhomogeneous BSE

\[
T = V + VG_0 T
\]

(1)
yields the transition matrix \(T\) of two-particle scattering. In Eq. (1) \(G_0\) is the free resolvent which propagates two non-interacting particles, i.e.,

\[
G_0 = \frac{i}{\hat{k}_1^2 - m_1^2 + i\omega} + \frac{i}{\hat{k}_2^2 - m_2^2 + i\omega},
\]

(2)

\(\hat{k}_i^a\) denoting the momentum operator of particle \(i\) with mass \(m_i\), the hat on the variable emphasizing its operator character. The driving term \(V\) stands for the complete interaction, irreducible with respect to two-particle propagation; it also includes self-energy corrections, i.e., it may contain disconnected pieces. If the dynamics allows for a two-particle bound state \(|\Psi\rangle\) with total four-momentum \(K_B\), \(K_B^2 = M_B^2\), the vertex \(|\Gamma\rangle\) at the bound-state pole is solution of the homogeneous BSE

\[
|\Gamma\rangle = VG_0 |\Gamma\rangle
\]

(3)

with the relation

\[
|\Psi\rangle = G_0 |\Gamma\rangle
\]

(4)

to the bound state \(|\Psi\rangle\). Eqs. (1) and (3) do not determine the bound state \(|\Psi\rangle\) in full; the normalization condition has to be added. The two-particle total four-momentum \(K\) is conserved, i.e., all operators \(O_\alpha\) of Eqs. (1) and (3), \(O_\alpha = T, G_0\) or \(V\), and the states \(|\Psi\rangle\) and \(|\Gamma\rangle\) carry a four-dimensional \(\delta\)–function in momentum space, i.e.,

\[
\langle K' | O_\alpha | K \rangle = \delta(K' - K)O_\alpha(K),
\]

(5)

\[
\langle K' | \Psi \rangle = \delta(K' - K_B) |\Psi_B\rangle,
\]

(6)
\[ \langle K' \mid \Gamma \rangle = \delta(K' - K_B) \mid \Gamma_B \rangle, \quad (7) \]

the reduced quantities depending parametrically on \( K \), even if not spelled out explicitly for the states \( |\Gamma_B\rangle \) and \( |\Psi_B\rangle \). The reduced states \( |\Psi_B\rangle \) and \( |\Gamma_B\rangle \) belong to and the operators \( \mathcal{O}_a(K) \) act in a Hilbert space characterized by a four-dimensional momentum \( k^\mu \) or coordinate \( x^\mu \). They satisfy the Eqs. (1) and (3) in a corresponding fashion.

The inhomogeneous and homogeneous BSEs (1) and (3) are general and exact formulations for the scattering amplitude and bound state. However, for any realistic field theory solution of the BSE constitutes a difficult calculational task which has not been tackled in full. In practical calculations, the driving term \( V(K) \) has to be truncated to low orders of particle exchange. In Euclidean space, the fermion case has only been solved in ladder approximation [2], i.e., with single particle exchange for the driving term while the boson case has only been solved in ladder and crossed ladder approximation [3]. However, the step from the Euclidean-space to Minkowski-space solutions requires a complicated analytic continuation [4]. Direct solutions in Minkowski space are just now becoming available [5].

In the light of the great calculational difficulties, three-dimensional reductions of the BSE are still of high physics interest. The conceptual sacrifices generated by the reduction can possibly be outweighed by the gain in technical ease: One hopes to be able to include physical phenomena which the four-dimensional BSE with a highly truncated interaction is unable to account for. For example, the three-dimensional Gross approach [6] allows only one particle to propagate off-mass-shell, but it appears to go beyond the ladder approximation of BSE by single particle exchange and to include crossed exchanges implicitly; it manifestly preserves covariance. Other reduction schemes give up covariance, which then must be recovered through complicated correction schemes. An equal-time projection scheme has also been explored for the pion-nucleon system which fulfills requirements of covariance and discrete Poincarè symmetries [7]. The papers by Fuda [8] report on the comparision of one-meson exchange models in ladder approximation on both light-front and instant-form dynamics, without emphasis to the underlying field-theoretic framework.
The purpose of this paper is two-fold:

i) First, the paper attempts to find a three-dimensional equation for auxiliary quantities from which the full covariant solution of the BSE in the ladder or any other approximation can be obtained *with ease*. This is a technical objective with solutions well-known in the framework of instant-form dynamics. Here the advantages of light-front dynamics are to be explored.

ii) Second, the paper tries to illuminate the connection to a quantum-mechanical description of the two-particle system whose dynamic input is related to the underlying field theory.

Sect.II motivates our novel choice for three-dimensional auxiliary quantities from which the covariant solutions of the BSE are obtained. It motivates light-front dynamics as our choice for a dynamical framework. Sect.III gives our theoretical apparatus in full. Sect.IV tests the potential of the method in the example of a two-boson bound state. We perform numerical calculations for the two-boson bound state including up to four-particle intermediate states in lowest order and compare to the solutions of the four-dimensional BSE equation in the ladder approximation. Sect.V sketches the generalization of our theoretical apparatus to fermions. Sect.VI discusses the connection with light-front quantum mechanics. Our conclusions are summarized in Sect.VII.

**II. CHOICE OF TWO-PARTICLE AUXILIARY FREE RESOLVENT \( \tilde{G}_0(K) \).**

It is well known, from the work of Ref. [9], that the transition matrix \( T(k) \) and the bound state \( \mid \Psi_B \rangle \) of the covariant BSE can be obtained with the help of a convenient auxiliary resolvent \( \tilde{G}_0(K) \), still to be chosen. That is, we have

\[
T(K) = W(K) + W(K)\tilde{G}_0(K)T(K),
\]

\[
\mid \Gamma_B \rangle = W(K_B)\tilde{G}_0(K_B)\mid \Gamma_B \rangle,
\]

\[
\mid \Psi_B \rangle = G_0(K)\mid \Gamma_B \rangle,
\]
provided the driving term \( V(K) \) is changed to \( W(K) \) according to

\[
W(K) = V(K) + V(K)[G_0(K) - \tilde{G}_0(K)]W(K) .
\] (11)

Eqs. (9) and (10) do not determine the bound state \( |\Psi_B\rangle \) in full; the normalization condition

\[
\lim_{K^2 \to K_B^2} \left\langle \Psi_B \left| \frac{G_0(K)^{-1} - G_0(K_B)^{-1}}{K^2 - K_B^2} - \frac{V(K) - V(K_B)}{K^2 - K_B^2} \right| \Psi_B \right\rangle = 1
\] (12)

has to be added. It involves the original driving term \( V(K) \) \[10\]. The choice of \( \tilde{G}_0(K) \) is hoped to be sufficiently clever that the integral equation (11) does not have to be solved in full, but that a few terms of the infinite series

\[
W(K) = V(K) + V(K) \left( G_0(K) - \tilde{G}_0(K) \right) V(K) + ...
\] (13)

suffice. The auxiliary resolvent \( \tilde{G}_0(K) \) remains a four-dimensional one, but its choice may sacrifice the covariance which the resolvent \( G_0(K) \) possesses.

The dynamics of the interacting two-particle system can be fully described by its propagation between hyperplanes, the hyperplanes \( x^0 = \text{const.} \) in instant-form dynamics, the hyperplanes \( x^+ = x^0 + x^3 = \text{const.} \) in light-front dynamics \[11\]. In contrast, the free resolvent of the BSE depends on the individual times \( x_i^0 \) or on the individual light-front times \( x_i^+ \).

The free resolvent in instant-form coordinates \( k_i = (k_i^0, \vec{k}_i) \)

\[
\langle x_1^0, x_2^0 | G_0 | x_1^0, x_2^0 \rangle = -\frac{1}{(2\pi)^2} \int \frac{dk_1^0 dK^0}{(k_1^0)^2 - \vec{k}^2 - m_i^2 + i\epsilon} \left( e^{-ik_1^0(x_1^0 - x_2^0 - x_1^+ + x_2^+)} + e^{-iK^0(x_2^0 - x_1^0)} \right) \left( K^0 - k_1^0 \right)^2 - (\vec{K} - \vec{k}_1)^2 - m_i^2 + i\epsilon \] (14)

--- in fact only its dependence on individual times \( x_i^0 \) is made explicit --- reduces for propagation between the hyperplanes \( x^0 \) and \( x^0 \) to

\[
\langle x_1^0, x_2^0 | G_0 | x_1^0, x_2^0 \rangle = \frac{dK^0}{2\pi} e^{-iK^0(x_2^0 - x_1^0)} \int \frac{dk_1^0}{2\pi} e^{iK^0(k_1^0)} \left| G_0(K) \right|_{k_1^0} \right\rangle ,
\] (15)

\[
\equiv \frac{dK^0}{2\pi} e^{-iK^0(x_2^0 - x_1^0)} |0G_0(K)|_0 .
\] (16)
In Eq. (15) the notation

\[ \langle k_1^0 | G_0(K) | k_1^0 \rangle = -\frac{1}{2\pi} \frac{\delta(k_1^0 - k_1^0)}{(k_1^0)^2 - \tilde{k}_1^2 - m_i^2 + i\epsilon} \]  

is introduced, as well as the abbreviation

\[ |_0 G_0(K) |_0 : = \int dk_1^0 dk_1^0 \langle k_1^0 | G_0(K) | k_1^0 \rangle \]  

(18)

\[ = \frac{i}{2k_{1on} k_{2on}} \left( \frac{1}{(K^0 - \tilde{k}_{1on} - \tilde{k}_{2on} + i\epsilon)} - \frac{1}{(K^0 + \tilde{k}_{1on} + \tilde{k}_{2on} - i\epsilon)} \right). \]  

(19)

The matrix element \( \langle k_1^0 | G_0(K) | k_1^0 \rangle \) of Eq. (17), in which only the dependence on the ”dynamic” variable \( k_1^0 \) is made explicit remains an operator with respect to the ”kinematic” variables \( \tilde{k}_1 \), the operator character being carried by the operators \( \tilde{k}_{ion} = \sqrt{k_i^2 + m_i^2} \). The basis states for these kinematic variables are defined by \( \langle \tilde{x}_i | \tilde{k}_i \rangle = \exp(i\tilde{k}_i \cdot \tilde{x}_i) \) and are eigenfunctions of the momentum operator \( \tilde{k} \) and the free energy operator \( \tilde{k}_{ion} \). The states \( | \tilde{k} \rangle \) form an orthogonal and complete basis.

In Eq. (18), the vertical bar \( |_0 \) indicates that the dependence on \( k_1^0 \) is integrated out. The bar on the left of the resolvent represents integration on \( k_1^0 \) in the bra-state, the bar on the right in the ket-state; we shall encounter resolvents in which integration on \( k_1^0 \) is performed only on one side, the bar \( |_0 \) being placed on that side alone. The resulting operator \( |_0 G_0(K) |_0 \) is three-dimensional and depends only on the kinematic variables \( \tilde{k}_1 \). It is a global propagator, since it mediates between hyperplanes according to Eq.(16), not allowing for individual time differences between the two particles, it is not explicitly covariant. In instanton dynamics, the global propagator \( |_0 G_0(K) |_0 \) still allows for particle and antiparticle propagation. This is considered to be a technical disadvantage.

The free resolvent in light-front coordinates \( k_i = (k_i^- := k_i^0 - k_i^3 , k_i^+ := k_i^0 + k_i^3 , \tilde{k}_\perp) \)

\[ \langle x_1^+ x_2^+ | G_0 | x_1^+ x_2^+ \rangle = -\frac{1}{(2\pi)^2} \int dk_1^- dK^- e^{-\frac{i}{2}k_1^- (x_1^--x_2^--x_1^+ + x_2^+)e^{-\frac{i}{2}K^- (x_2^+ - x_2^-)}} \times \]  

\[ \frac{1}{k_1^+ (K^+ - \tilde{k}_1^+) \left(k_1^- - \frac{\tilde{k}_1^2 + m_i^2 - i\epsilon}{k_1^+} \right) \left(K^- - k_1^- - \frac{\tilde{k}_1^2 + m_i^2 - i\epsilon}{K^- - k_1^-} \right)} \]  

(20)
— only its dependence on the individual light-front ”times” \(x_i^+\) is made explicit — reduces, for propagation between the hyperplanes \(x^+\) and \(x^+\), to

\[
\langle x^+ x^+ | G_0 | x^+ x^+ \rangle = \int \frac{dK^-}{2\pi} e^{-\frac{i}{2}K^-(x^+-x^+)} \int dk_1^- dk_1^- \langle k_1^- | G_0(K) | k_1^- \rangle , \tag{21}
\]

\[
\equiv \int \frac{dK^-}{2\pi} e^{-\frac{i}{2}K^-(x^+-x^+)} | G_0(K) | . \tag{22}
\]

In Eq. (21) the notation

\[
\langle k_1^- | G_0(K) | k_1^- \rangle = - \frac{1}{2\pi} \frac{\delta (k_1^- - k_1^-)}{ \hat{k}_1^+(K^+ - \hat{k}_1^+) \left( k_1^- - \frac{\hat{k}_1^2 + m^2}{\hat{k}_1^+} \right) \left( K^- - k_1^- - \frac{\hat{k}_1^2 + m^2}{k^+ - k_1^-} \right)} \tag{23}
\]

is introduced with the abbreviation,

\[
|G_0(K)| : = \int dk_1^- dk_1^- \langle k_1^- | G_0(K) | k_1^- \rangle = \int \frac{dK^-}{2\pi} e^{-\frac{i}{2}K^-(x^+-x^+)}| G_0(K) | . \tag{24}
\]

\[
\equiv \frac{i\theta(K^+ - \hat{k}_1^+)\theta(\hat{k}_1^+)}{\hat{k}_1^+(K^+ - \hat{k}_1^+) \left( K^- - \hat{k}_{1on}^- - \hat{k}_{2on}^- + i\theta \right)} \tag{25}
\]

\[
:= g_0(K) , \tag{26}
\]

where \(K^+ > 0\) can be chosen without any loss of generality. The matrix element

\[
\langle k_1^- | G_0(K) | k_1^- \rangle \quad \text{of Eq.} \quad (23), \quad \text{in which only the dependence on the ”dynamic” variable} \quad k_1^- \quad \text{is made explicit, still remains an operator with respect to the ”kinematic” variables} \quad (k_1^+, \hat{k}_{1\perp}), \quad \hat{k}_{1on}^- = \frac{\hat{k}_{1\perp}^2 + m^2}{k_1^+} \quad \text{and} \quad \hat{k}_{2on}^- = \frac{(K^+ - \hat{k}_{1\perp})^2 + m^2}{K^+ - k_1^-} . \quad \text{The basis states for the kinematical light-front variables are defined by}
\]

\[
\langle x_i^- x_i^\perp | k_1^+ k_1^\perp \rangle = e^{-\frac{i}{2}(k_1^+ x_i^- - k_1^- x_i^\perp)} \tag{27}
\]

and are eigenfunctions of the momentum operators \((\hat{k}_1^+, \hat{k}_{1\perp})\) and the free energy operator \(\hat{k}_{1on}^-\). The states \(|k_1^+ k_1^\perp\rangle\) form an orthonormal and complete basis, e.g.,

\[
\int \frac{dk^+ dk^\perp}{2(2\pi)^3} (x^\perp x^\perp | k_1^+ k_1^\perp \rangle \langle k_1^+ k_1^\perp | x^\perp x^\perp \rangle = \delta(x^\perp - x^-)\delta(x^\perp - x^\perp) . \tag{28}
\]
right in the ket-state. We shall encounter resolvents in which integration on $k_1^-$ is done on one side alone, the bar $|$ being placed only on that side. The operator $g_0(K)$ is three-dimensional and it depends on the kinematic variables $(k_1^+, \vec{k}_{1\perp})$ only. It is a global propagator, since it mediates between hyperplanes according to Eq.(22), not allowing for individual light-front time differences between the two particles. It does not possesses explicit covariance but is still covariant under light-front boosts. In light-front dynamics, the global propagator $g_0(K)$ only allows particle propagation, no antiparticle propagation, due to the choice of $K^+ > 0$. This is the advantage of light-front dynamics, with which we work from now on.

The auxiliary four-dimensional resolvent $\tilde{G}_0(K)$, introduced in Eqs. (8)-(13) has to be chosen next. We require for $\tilde{G}_0(K)$:

$$\tilde{G}_0(K)\big| = G_0(K)\big| ,$$

(29)

$$|\tilde{G}_0(K) = |G_0(K) ,$$

(30)

$$|\tilde{G}_0(K)| = |G_0(K)| ,$$

(31)

and define a three-dimensional transition matrix $t(K)$ through

$$| \big[ \tilde{G}_0(K) + \tilde{G}_0(K)T(K)\tilde{G}_0(K) \big] | = g_0(K) + g_0(K)t(K)g_0(K) .$$

(32)

In Eqs.(29)-(32) the abbreviation $|$ for integrating out the $k_1^-$ dependence of operators is used. The conditions (29)-(32) are a rather mixed bag. The conditions (31) and (32) are physical ones: They require that the global-propagator form of $\tilde{G}_0(K)$ be the same as for the exact free resolvent $G_0(K)$ and that the full resolvent of BSE $G_0(K) + G_0(K)T(K)G_0(K)$ can be obtained from $|\tilde{G}_0(K)|$ and the three-dimensional $t(K)$. However, the two conditions (31) and (32) do not determine $\tilde{G}_0(K)$ in full. Our choice is

$$\tilde{G}_0(K) := G_0(K)|g_0^{-1}(K)|G_0(K) ,$$

(33)

though $\tilde{G}_0(K) = \delta \left( \hat{k}_1^- - \frac{K^-}{2} \right)g_0(K)\delta \left( \hat{k}_1^- - \frac{K^-}{2} \right)$ (and obvious variants of it) seems to be a legitimate alternative. However, if we demand that the kernel of the integral equation for the auxiliary transition matrix, $t(K)$, represents light-front propagation in higher Fock-states, then the choice is unique. The conditions (29) and (30) introduce the additional
convenience that the auxiliary resolvent be as close as possible to the exact free one. The auxiliary quantities are computed in Appendix A.

III. CALCULATIONAL PROCEDURE

Our calculational procedure amounts to solving three-dimensional integral equations, whose solutions then yield the covariant results of the BSE by quadrature.

The four-dimensional transition matrix $T(K)$ is obtained from the three-dimensional auxiliary one $t(K)$, defined by Eq.(32), through

$$t(K) = g_0(K)^{-1}|G_0(K)T(K)G_0(K)|g_0(K)^{-1}, \quad (34)$$

by first iterating the integral equation (8) once,

$$T(K) = W(K) + W(K) \left[ \tilde{G}_0(K) + \tilde{G}_0(K)T(K)\tilde{G}_0(K) \right] W(K), \quad (35)$$

and then making use of our choice, Eq.(33), for $\tilde{G}_0(K)$ and the result Eq.(34). The relation between the $T(K)$ and the auxiliary $t(K)$ is

$$T(K) = W(K) + W(K)G_0(K)\left[ g_0(K)^{-1} + t(K) \right]|G_0(K)W(K). \quad (35)$$

The auxiliary transition matrix $t(K)$ itself is obtained by the three-dimensional integral equation

$$t(K) = w(K) + w(K)g_0(K)t(K), \quad (36)$$

in which the driving term $w(K)$ is derived from the modified four-dimensional interaction $W(K)$ of Eq.(11) according to

$$w(K) := g_0(K)^{-1}|G_0(K)W(K)G_0(K)|g_0(K)^{-1}. \quad (37)$$

There is an integral equation for $w(K)$ as there is for $W(K)$, but we do not give it here. We hope that, through our choice (33) for $\tilde{G}_0(K)$, a few terms of the expansion Eq.(11), of $W(K)$ in powers of $V(K)$ will dynamically suffice to yield the full result of BSE with
satisfactory accuracy. The numerical example of Sect. IV where rapid convergence of \( w(K) \)
is seen, demonstrates the validity of this expectation.

If the transition matrix \( T(K) \) of the BSE has a bound-state pole at total four momentum\( K_B, K_B^2 = M_B^2 \), the auxiliary three-dimensional transition matrix \( t(K) \) also has a bound-state pole at exactly the same \( K_B \), according to Eq.(34), with the residue \( |\gamma_B\rangle \) being the solution of the homogeneous three-dimensional equation

\[
|\gamma_B\rangle = w(K_B)g_0(K_B)|\gamma_B\rangle ,
\]

(38)
corresponding to the inhomogeneous one, Eq.(36). From \( |\gamma_B\rangle \), the residue \( |\Gamma_B\rangle \) of BSE can be recovered according to Eq.(35)

\[
|\Gamma_B\rangle = W(K_B)G_0(K_B)|\gamma_B\rangle
\]

(39)
as well as the bound state \( |\Psi_B\rangle \) of BSE, i.e.

\[
|\Psi_B\rangle = G_0(K_B)W(K_B)G_0(K_B)|\gamma_B\rangle ;
\]

(40)
\[
|\Psi_B\rangle = \left[ 1 + \left( G_0(K_B) - G_0(K_B)|g_0(K_B)|^{-1}|G_0(K_B)\right) W(K_B) \right] G_0(K_B)|\gamma_B\rangle .
\]

(41)
For the form Eq.(41) of the bound state, the condition Eq.(38) \(|\gamma_B\rangle - w(K_B)g_0(K_B)|\gamma_B\rangle = 0\) is used. The step from the three-dimensional residue \( |\gamma_B\rangle \) to the four-dimensional bound state \( |\Psi_B\rangle \) appears predominantly a kinematic one, effected by the operator \( G_0(K_B) \). Only the second term in Eq.(41) depends on the interaction, and it is expected to be a small correction.

The four-dimensional bound state \( |\Psi_B\rangle \) is related to the auxiliary three-dimensional \( |\phi_B\rangle \), defined by

\[
|\phi_B\rangle := g_0(K_B)|\gamma_B\rangle
\]

(42)
and satisfying

\[
|\phi_B\rangle = g_0(K_B)w(K_B)|\phi_B\rangle ,
\]

(43)
in an obvious way by
\[
\int dk_1^- \langle k_1^- | \Psi_B \rangle = | \phi_B \rangle .
\] (44)

The result Eq.(44) follows immediately from Eq.(41). The auxiliary bound-state wave-function $| \phi_B \rangle$ is the projection of the bound-state $| \Psi_B \rangle$ of BSE to equal light-front individual times $x_i^+ = x^+$, taken on the hyperplane $x^+ = 0$.

The bound-state $| \Psi_B \rangle$ of BSE and its three-dimensional auxiliary version $| \phi_B \rangle$ still have to be normalized. If the dependence on $K$ of the original interaction $V(K)$ is weak, i.e.,

\[
\frac{(V(K) - V(K_B))}{(K^2 - K_B^2)} \simeq 0
\]

and if furthermore the interaction-dependent term in the step from $| \phi_B \rangle$ to $| \Psi_B \rangle$ according to Eq.(41) is small, i.e., $| \Psi_B \rangle \simeq G_0(K_B)|g_0(K_B)^{-1}| \phi_B \rangle$,

then

\[
\lim_{K^2 \to K_B^2} \left\langle \Psi_B \left| \frac{G_0(K)^{-1} - G_0(K_B)^{-1}}{K^2 - K_B^2} \right| \Psi_B \right\rangle \simeq
\lim_{K^2 \to K_B^2} \left\langle \phi_B \left| \frac{g_0(K)^{-1} - g_0(K_B)^{-1}}{K^2 - K_B^2} \right| \phi_B \right\rangle = 1 .
\] (45)

For any further applications, i.e., for predicting physical observables, we now have two equally valid options. We may either work with covariant operators using the bound state $| \Psi_B \rangle$ and/or the transition matrix $T(K)$ of the BSE or we may derive effective operators suited for the context of the auxiliary three-dimensional bound state $| \phi_B \rangle$ and/or the auxiliary three-dimensional transition matrix $t(K)$. We give an example of each of the possible strategies:

We use the electroweak current $J^\mu(Q)$ as example and assume that it connects an initial bound state $| \Psi_{Bi} \rangle$ to a final one $| \Psi_{Bf} \rangle$ in an elastic process. We take $J^\mu(Q)$ to be the current appropriate for the hadronic field theory with four-momentum transfer $Q = K_{Bf} - K_{Bi}$. The matrix element for describing the process $\langle \Psi_{Bf} | J^\mu(Q) | \Psi_{Bi} \rangle$ can be obtained from the three-dimensional bound state $| \phi_B \rangle$ by

\[
\langle \Psi_{Bf} | J^\mu(K_{Bf} - K_{Bi}) | \Psi_{Bi} \rangle = \langle \phi_{Bf} | j^\mu(K_{Bf}, K_{Bi}) | \phi_{Bi} \rangle ,
\] (46)
with the effective current in three-dimensional space

\[ j^\mu(K_f, K_i) := g_0(K_f)^{-1}|G_0(K_f)| \left[ 1 + W(K_f) \left( G_0(K_f) - G_0(K_f)|g_0(K_f)^{-1}|G_0(K_f) \right) \right] \]

\[ J^\mu(K_f - K_i) \left[ 1 + \left( G_0(K_i) - G_0(K_i)|g_0(K_i)^{-1}|G_0(K_i) \right) W(K_i) \right] G_0(K_i)|g_0(K_i)^{-1}. \]  

(47)

For the relation between the bound states |Ψ_B⟩ and |φ_B⟩, Eq.(41) is used, which separates the kinematic and dynamic, i.e., interaction-dependent, steps in that relation from each other. The bound state has to be calculated for the initial and final four-momenta K_{Bi} and K_{Bf}. The effective current j^\mu(K_f, K_i) is predominantly derived kinematically from the covariant one through g_0(K_f)^{-1}|G_0(K_f)| but it also depends on the interaction W(K) of Eq.(11). If W(K) is not computed in full, but only expanded up to a certain order in the original interaction V(K) of the BSE, the effective current should be expanded consistently up that order.

IV. A NUMERICAL TEST CASE

We use the bound state of a schematic two-boson system as a test case of the power of the suggested numerical technique. The employed interaction Lagrangian is

\[ \mathcal{L}_I = g_S \phi_1^1 \phi_1 \sigma + g_S \phi_2^1 \phi_2 \sigma, \]  

(48)

where the bosons with fields φ_1 and φ_2 have masses m_1 and m_2, which we take to be equal, m_1 = m_2 = m, and the exchanged boson with field σ has mass μ. The coupling constant is g_S.

Using standard techniques in Euclidean space, the homogeneous BSE is solved for the bound-state vertex |Γ_B⟩ in the ladder approximation, i.e.,

\[ \langle k_1' | Γ_B \rangle = \frac{i g_S^2}{(2\pi)^4} \int \frac{d^4k_1}{((k_1' - k_1)^2 - \mu^2 + i\varepsilon)(k_1^2 - m^2 + i\varepsilon)} \langle k_1 | Γ_B \rangle \]  

(49)

The solution is calculated in the two-particle c.m. system, i.e., for K_B = (M_B, 0), and for the ratio of masses μ/m = 0.5. Requiring the bound state mass to have a particular
value $M_B$ fixes the coupling constant $g_S$. The four-dimensional bound-state vertex $\langle k_1 | \Gamma_B \rangle$ depends on all Euclidean four components of the momentum $k_1$ of boson 1. The exact four-dimensional bound state is obtained according to Eq.(10). However, the representation of the vertex and bound state in terms of Minkowski momenta is difficult. We do not attempt it.

In contrast, the four-dimensional bound-state obtained by the numerical technique suggested in Sect.III is available in Minkowski space. We calculate it only approximately by using for the driving term $w(K_B)$ of the auxiliary three-dimensional equation Eq.(38), an expansion in orders of the interaction $V(K)$ of BSE in Eqs. (13) and (37), i.e., in powers of the coupling constant $g_S$ of the interaction Lagrangian (48). We use the approximation up to the second and fourth powers of $g_S$, i.e., $w(K_B) \simeq w^{(2)}(K_B)$ and $w(K_B) \simeq w^{(2)}(K_B) + w^{(4)}(K_B)$.

In a time-ordered view, the BSE allows for an exchange of an infinite number of $\sigma$ bosons in stretched configurations. In contrast, the approximative $w^{(2)}(K_B)$ allows only for one exchange (Fig.1a), while $w^{(4)}(K_B)$ allows for two (Fig.1b). The analytic forms of $w^{(2)}(K_B)$ and $w^{(4)}(K_B)$ are given in Appendices B and C. The explicit forms of the homogeneous integral equation for $|\gamma_B\rangle$, Eq.(38), for the above approximations in the driving term are given in Appendix D. In order to make a comparison with the exact bound state we study the projected forms of the bound states, i.e.,

$$f_{\text{exact}}(\sqrt{k_{1\perp}^2}) = \int dk_1^- dk_1^+ \langle k_1 | \Psi_B \rangle$$

$$= 2 \int dk_1^0 dk_1^3 \langle k_1^0 k_1^3 | G_0(K_B) | \Gamma_B \rangle .$$

$$f_{\text{app}}(n)(\sqrt{k_{1\perp}^2}) = \int dk_1^+ \langle k_1^+ k_{1\perp} | \phi_B^{(n)} \rangle_{\text{app}}$$

$$= \int dk_1^+ \langle k_1^+ k_{1\perp} | g_0(K_B) | \gamma_B^{(n)} \rangle_{\text{app}} .$$

The superscripts $(n)$ in Eq.(51) indicate the power of the coupling constant up to which the approximation is carried, i.e., $w(K_B) \simeq \sum_{i=2}^n w^{(i)}(K_B)$. The comparison between exact and approximate results is carried out on two levels:
In Fig. 2 the relation between $g_S$ and $M_B$ is tested for $\mu = 0.5m$ against the four-dimensional results. Whereas the exact relation is already satisfactorily reproduced by the approximation based on $w^{(2)}(K_B)$, the approximation based on $w^{(2)}(K_B) + w^{(4)}(K_B)$ improves the agreement.

In Figs. 3 and 4, the projected bound-states $f(\sqrt{k_{1,\perp}^2})$ are compared for two cases. In the first case $M_B = 0$, i.e., the binding is very strong. It is of the order of the masses of the interacting particles as encountered in quark systems. In the other case $M_B = 1.98m$, i.e., the binding is very weak. It is only 2% of the masses of the interacting particles, as encountered in nuclear systems. In both cases the approximation based on $w^{(2)}(K_B)$ is already quite accurate. The improvement due to the inclusion of $w^{(4)}(K_B)$ is particularly noticeable for the case of strong binding.

The fact that a low-order approximation of $w^{(n)}(K_B)$ works surprisingly well is a virtue of light-front dynamics. It is well known that the analogous approximation scheme in instant-form dynamics has much poorer convergence properties with respect to the number of exchanged $\sigma$ bosons [12].

V. EXTENSION TO FERMIONS

The free resolvent which propagates two fermions disconnectedly contains self-energy corrections as in the case of bosons. They are usually left out of the ladder approximation of interaction. The two-fermion free resolvent then takes the form which we immediately rewrite conveniently as

$$G_F^0 = \frac{\hat{k}_1 + m_1 \hat{k}_2 + m_2}{k_1^2 - m_1^2 k_2^2 - m_2^2}$$

$$G_F^0 = \Delta G_F^0 + \left(\hat{k}_{1on} + m_1\right) \left(\hat{k}_{2on} + m_2\right) G_0,$$

where $\hat{k}_{1on} = \frac{\hat{k}_{1\perp} + m_1}{k_1}$ and $\hat{k}_{2on} = \frac{\hat{k}_{2\perp} + m_2}{k_2}$. In Eq.(53) $G_0$ is the covariant propagator the paper has worked with in the conceptual development until now. Furthermore, Eq.(53) is the definition of $\Delta G_F^0$ which contains – except for the particular spin-dependent opera-
tors \((\hat{k}_{1\on} + m_1)\) and \((\hat{k}_{2\on} + m_2)\) that commute with \(G_0\) — all particular divergences and subtleties connected with the fermion motion. The operator

\[
\Delta_0^F = \frac{\gamma^1_+ \hat{k}_{2\on} + m_2}{2k_1^+ k_2^2 - m_2^2} + \frac{\hat{k}_{1\on} + m_1 \gamma^2_+}{k_1^2 - m_1^2} + \frac{\gamma^1_+ \gamma^2_+}{2k_1^+ k_2^2}
\]

(54)
carries the instantaneous part of the fermion propagators in light-front time. Its is singular under \(k_1^-\) integration. We therefore suggest the following strategy for fermions: We apply the reduction to an auxiliary resolvent \(\tilde{G}_0\) twice, using the apparatus of Sects. I and II. The operator dependence on the total two-fermion four momentum \(K\) is factored out as there. All operators become then parametrically dependent on \(K\).

In the first step, the two-fermion resolvent \((\hat{k}_{1\on} + m_1) (\hat{k}_{2\on} + m_2) G_0(K)\) is introduced instead of \(G^\beta_0(K)\). We use formulae (8)-(13) to do this. All the physics of anomalous two-fermion propagation is contained in the new effective interaction \(W(K)\) of Eq.(11). Thus, one arrives at a new BSE, corresponding to Eq.(1) after reduction with respect to \(K\), with the four dimensional resolvent \((\hat{k}_{1\on} + m_1) (\hat{k}_{2\on} + m_2) G_0(K)\) and the new interaction. The resulting two-fermion equation is now solved with the technique as developed for two bosons. This is possible due to the fact that the spin-dependent operator \((\hat{k}_{1\on} + m_1) (\hat{k}_{2\on} + m_2)\) also commutes with the auxiliary one \(\tilde{G}_0(K) = G_0(K)|g_0(K)^{-1}|G_0(K)\), i.e.,

\[
(\hat{k}_{1\on} + m_1) (\hat{k}_{2\on} + m_2) \tilde{G}_0(K) = \tilde{G}_0(K) (\hat{k}_{1\on} + m_1) (\hat{k}_{2\on} + m_2) .
\]

(55)

This idea will not be further developed in this paper, but indicates that the scope of the method extends beyond the two-boson system.

VI. RELATION TO LIGHT-FRONT QUANTUM MECHANICS

Sects. I-IV used the notion of a bound state, but scattering states were not introduced. The later could have been introduced in the BSE (1) as well as in the auxiliary three-dimensional equation (36) for \(t(K)\) with the global propagator \(g_0(K)\). Given an initial two-particle plane-wave state \(|k_1^+ \bar{k}_{1\perp} K_{\on}\rangle\) with total momentum \(K_{\on}\) and light-front ”energy”
\[ K_{\text{on}} = \frac{\vec{k}^2 + m^2}{k^+_1} + \frac{(K_\perp - \vec{k}_1^\perp)^2 + m^2}{K^+ - k^+_1}, \]

one may define the corresponding three-dimensional scattering state \( \phi^{(+)}(k^+_1 \vec{k}_1^\perp K_{\text{on}}) \) with outgoing light-front boundary conditions as the solution of a standard Lippman-Schwinger type of equation, i.e.,

\[
\phi^{(+)}(k^+_1 \vec{k}_1^\perp K_{\text{on}}) = \left| k^+_1 \vec{k}_1^\perp K_{\text{on}} \right> + g_0(K_{\text{on}}) w(K_{\text{on}}) \phi^{(+)}(k^+_1 \vec{k}_1^\perp K_{\text{on}}) \]

(56)

with four-momentum \( K_{\text{on}} = (K^+_{\text{on}}, K^+, \vec{K}_\perp) \). The relation to the auxiliary transition operator \( t(K) \) is obvious,

\[
t(K_{\text{on}}) \left| k^+_1 \vec{k}_1^\perp K_{\text{on}} \right> = w(K_{\text{on}}) \phi^{(+)}(k^+_1 \vec{k}_1^\perp K_{\text{on}}) \]

(57)

Furthermore, it satisfies the homogeneous equation

\[
\left[ g_0(K_{\text{on}})^{-1} - w(K_{\text{on}}) \right] \phi^{(+)}(k^+_1 \vec{k}_1^\perp K_{\text{on}}) = 0
\]

(58)

in the same way as the auxiliary bound state \( |\phi_B\rangle \) of Eq.(38) does, i.e.,

\[
\left[ g_0(K_B)^{-1} - w(K_B) \right] |\phi_B\rangle = 0
\]

(59)

Eqs. (58) and (59) formally look like the eigenvalue equations of quantum mechanics with the only difference being that the two-particle interaction \( w(K) \) depends on the eigenvalue.

Untill now the relationship to quantum mechanics has indeed been entirely formal. The states \( |\phi_B\rangle \) and \( |\phi^{(+)}(k^+_1 \vec{k}_1^\perp K_{\text{on}})\rangle \) and the corresponding transition matrix have significance only as quantities from which the solutions of the BSE can be obtained with comparative ease. On the other hand, at this stage a quantum-mechanical description of the two-particle system can be given which corresponds dynamically to the underlying field-theoretic one, though it is by no means equivalent to it. Quantum-mechanical two-particle states \( |\varphi\rangle \) are required to satisfy the eigenvalue equation for the squared mass operator,

\[
\left[ M_0^2 + v(K^+, \vec{K}_\perp) \right] |\varphi\rangle = M_B^2 |\varphi\rangle,
\]

(60)

where the squared free-mass operator is

\[
M_0^2 = \frac{\vec{k}^2 + m^2}{\hat{x}} + \frac{(\vec{K}_\perp - \vec{k}_1^\perp)^2 + m^2}{1 - \hat{x}},
\]

(61)
and \( \hat{x} = \frac{k^+}{K^+} \). The states are elements of a Hilbert-space spanned by the free-particle on-mass-shell basis states. Boundary conditions must be imposed on the solutions of Eq.(60) in order to make them acceptable. Bound-state and scattering state solutions to the mass squared operator equation exist and are orthonormalized. The orthonormalization for scattering states is of the \( \delta \)-function type. The states have a probability interpretation. The quantum mechanical bound-state normalization is

\[
\langle \varphi_B | \varphi_B \rangle = 1. \tag{62}
\]

The two-particle potential \( v(K^+, \vec{K}_\perp) \) is independent of the eigenvalue \( K^- \), the eigenvalue \( K^-_B \) to be calculated for the bound state and the eigenvalue \( K^-_m \) prescribed for the scattering states; the potential is hermitian it is instantaneous in light-front time; it conserves the kinematic components \((K^+, \vec{K}_\perp)\) of the total two-particle four-momentum \( K \). In quantum mechanics \( v(K^+, \vec{K}_\perp) \) may be parametrized by fitting it to observables. If contact is attempted to a corresponding field theory a standard form of identification is

\[
\langle k_1^+ \vec{k}_1^\perp | v(K^+, \vec{K}_\perp) | k_1^+ \vec{k}_1^\perp \rangle := i \sqrt{\frac{K^+}{k_1^+ (K^+ - k_1^+)}} \langle k_1^+ \vec{k}_1^\perp | w(K_v) | k_1^+ \vec{k}_1^\perp \rangle \sqrt{\frac{K^+}{k_1^+ (K^+ - k_1^+)}} \tag{63}
\]

with

\[
K_v = (\frac{1}{2} K^-_m + \frac{1}{2} K^-_m, K^+, \vec{K}_\perp). \tag{64}
\]

The defined relativistic quantum mechanical interaction is cooked in the framework of light-front dynamics. The value \( K^-_m \) is defined in the context of Eq.(60). This choice guarantees that the S-matrix calculated field-theoretically to first order in \( w(K) \) and calculated quantum-mechanically to first order in \( v(K^+, \vec{K}_\perp) \) are identical. The S-matrix carries a \( \delta \)-function for light-front energy \( K^- \) between initial and final states. The definition of Eq. (63) removes that \( \delta \)-function from \( v(K^+, \vec{K}_\perp) \) and allows for general off \( K^- \)-shell matrix elements. Thus, Eq.(64) implies a very particular off-shell extension. This procedure of identification – it is no derivation – is standard for the instant-form of quantum mechanics, e.g., when the one-boson exchange potential between nucleons is introduced. This paper extends that
procedure to light-front quantum mechanics. Furthermore, the potential is usually defined in the two-particle c.m. system, i.e., for $\vec{K}_\perp = 0$, and is considered unchanged in moving systems, i.e., independent of $\vec{K}_\perp$ and $K^+$.

The identification (63) motivates a quantum-mechanical potential. It does not attempt to derive it. The goal of the identification is to simulate exact solutions of the BSE in best accord with a chosen physics criterion, quantum mechanics description has different objectives than matching a field-theory result. It rather attempts to describe many-particle systems with the same rules once it has done so satisfactorily for the two-particle system with the same rules. Thus, when the quantum-mechanical potential cannot be derived completely, as is the case in hadronic physics, the potential is tuned to known experimental properties of the two-particle system and then considered a vehicle which carries that two-particle information to many-particle systems. Despite the particular many-particle aspect of quantum mechanics, a study of its predictive quality even for the two-particle system is interesting. Figs. 2-4 perform such study for the two-boson system of Sect.IV. The bound state constitutes an especially stringent test. For the instantaneous choice, the approximation, $K^- = K_{\infty}^- > m_1 + m_2$ in the interaction in the c.m. system is quite severe, because in this case field theory requires $K^- = K_B^- < m_1 + m_2$. The relation between the coupling constant $g_S$ and the bound-state mass $M_B$ and the dependence of the bound-state wave-function $f(q)$ on the momentum $q = \sqrt{\vec{k}_\perp^2}$ are compared in the field-theoretic and quantum-mechanical descriptions. Results are studied for the approximations $w(K) \simeq w^{(2)}(K)$ and $w(K) \simeq w^{(2)}(K) + w^{(4)}(K)$ up to second order and fourth-order in the coupling constant $g_S$. The quantum-mechanical binding energy and wave-function preserve most field-theoretic characteristics, expectedly better in the case of small binding rather than in the case of strong binding. The quantum-mechanical choice of the potential is usually based on the one-boson exchange, i.e., on the approximation $w(K) \simeq w^{(2)}(K)$. We are happy to find that this identification accounts better for the field-theoretic results than the choice based on $w(K) \simeq w^{(2)}(K) + w^{(4)}(K)$.

Instead of solving Eq.(60), its formal identity with the energy eigenvalue problem for a
nonrelativistic hamiltonian is often exploited [13] and $|\varphi_B\rangle$ is applied directly in the framework of light-front quantum-mechanics.

The response of the quantum-mechanical system to an electromagnetic probe is given by a four-vector current $j^\mu_v(K'^+ - K^+, \vec{K}'_\perp - \vec{K}_\perp)$ which, as the quantum-mechanical potential is a three-dimensional operator and it depends on the three-dimensional momentum transfer $(Q^+, Q'_\perp) = (K'^+-K^+, \vec{K}'_\perp - \vec{K}_\perp)$. As in the case of the potential, contact can be attempted with the corresponding field theory. A possible identification is

$$\langle k'_{1\perp}^+ k_{1\perp}^+ | j^\mu_v(K'^+ - K^+, \vec{K}'_\perp - \vec{K}_\perp) | k_{1\perp}^+ k_{1\perp}^+ \rangle := \sqrt{\frac{K^+}{k_{1\perp}^+(K^+ - k_1^+)}} \langle k'_{1\perp}^+ k_{1\perp}^+ | j^\mu_v(K'_v - K_v) | k_{1\perp}^+ k_{1\perp}^+ \rangle \sqrt{\frac{K^+}{k_{1\perp}^+(K^+ - k_1^+)}}$$

(65)

with

$$K'_v = (K'_v, K^+, \vec{K}'_\perp)$$

$$K'_v = (K'_v, K'^+, \vec{K}'_\perp) \quad (66)$$

The field-theoretic $j^\mu_v(K' - K)$ is the one of Eq.(47) in Sect. III. It contains the field-theoretic interaction in the form of $w(K)$. The quantum-mechanical current $j^\mu_v(K'^+ - K^+, \vec{K}'_\perp - \vec{K}_\perp)$, is derived in the special case of elastic scattering between bound states. Thus, the identification of Eq.(65) is not consistent with the choice of Eq.(63), which guaranteed the agreement of the field-theoretic and the quantum-mechanical S-matrix in first order in the interaction. Nevertheless, the quantum-mechanical current $j^\mu_v(K'^+ - K^+, \vec{K}'_\perp - \vec{K}_\perp)$ can be meaningfully studied and separated into interaction-free single particle and interaction-dependent two-particle pieces. Thus, the definition of Eq.(65) implicitly contains a possible quantum-mechanical definition of an interaction-dependent two-particle current. At this stage, the standard definition based on the identification of the S-matrix could also be given [14]. It also exploits the formal identity of the eigenvalue problem with a nonrelativistic hamiltonian with equations like (60), but it then identifies the nonrelativistic bound state with the solution $|\varphi_B\rangle$ of Eq.(59), the auxiliary field-theoretic bound state for the BSE. Thus, the calculation of the electromagnetic deuteron form factors in Ref. [14] is performed in the field-theoretic
spirit of Eq.(59). The two-particle current operators of pion range in Ref. [14] should not be confused with the quantum-mechanical interaction-dependent two-particle currents of this section.

VII. CONCLUSION

The paper suggests a calculational procedure for solving the BSE with comparative ease and in principle, with any desired accuracy. The procedure is based on an auxiliary three-dimensional integral equation, in the framework of light-front dynamics, whose solution then yields the result of the BSE by quadrature. The intermediate auxiliary quantities do not display covariance; covariance is restored in the final step to the full result of BSE.

The calculational procedure is exact, but it also offers an efficient approximative scheme: Only particles propagate. Antiparticles do not. Antiparticle propagation is relegated to the effective interaction. The convergence with respect to the number of exchanged particles mediating the interaction appears to be rapid. Though only an indication of that fact comes from the simple test case of a BSE bound state in ladder approximation, it gets supported by the similar result of Ref. [12] for the corresponding scattering amplitude. Calculational improvements are possible in a systematic manner. Thus, as a further and physically more interesting consequence, the solution of the BSE for bound state and scattering up to fourth order in the coupling constant, i.e., in ladder and crossed ladder approximation and with the inclusion of self-energy corrections is obtained based on a simplifying three-dimensional calculational procedure. The procedure capitalizes on beneficial properties of light-front dynamics. It should be an interesting alternative to the Gross approach [6] which is also three-dimensional and which has been suggested to include the cross-ladder exchanges approximately.

The calculational procedure is general, though it is given in this paper for an interacting two-boson system only. The ideas needed for an extension to fermions are developed but important technical details have not yet been worked out and unforeseen difficulties may still
arise. The problem of rotational invariance in light-front dynamics will become especially acute for fermions when spin and orbital angular momentum are to be coupled. The auxiliary three-dimensional quantities will then be hampered by their lack of rotational invariance. We strongly believe however, that the final step to the covariant result of BSE will overcome that difficulty.

The auxiliary thee-dimensional quantities, i.e., the operators and equations, that mediate the solution of the BSE, are close in spirit to relativistic quantum mechanics. The paper also discusses this relation. First, only particles and not antiparticles, propagate in the three-dimensional equations and in quantum mechanics. Second, the quantum-mechanical interaction is an instantaneous potential, the corresponding interaction $w(K)$ in the three-dimensional equation is not. However, this paper finds that the instantaneous choice for the potential does not distort the physics of the underlying field theory. Thus, the relation between quantum mechanics and field theory can be made close. However, compared to field theory, quantum mechanics has the virtue of an instant extension to many-particle systems: Barring small corrections due to many-particle forces and the quantum mechanical interaction is additive in the instantaneous pairwise potentials. In fact, the conceptual strategy of quantum mechanics often is to tune away shortcomings of the chosen instantaneous potential by adjusting undetermined phenomenological parameters to vital known experimental properties of the considered two-particle system. In this way the potential carries the accepted knowledge on the two-particle system over to many-particle systems.

The paper left open the relationship of the theoretical apparatus developed to realistic physics problems. We have in mind applications to hadronic and subhadronic systems. The concept of light-front wave-functions was applied in the context of nuclear physics to describe the deuteron [13] and the discussion of its properties in the light-front continues to the present [15]. The BSE is supposed to yield bound states and the scattering amplitude for those two-particle systems. In contrast, the response of such a two-particle system towards an eletroweak probe is considered in perturbation theory. The required matrix element is determined by the field-theoretic current between states of the BSE. The paper offers
two equivalent routes for calculation: Either the covariant states of BSE are constructed and then used in their four-dimensional forms or the field-theoretic current is reduced to a three-dimensional one, consistent with the auxiliary three-dimensional ones. Again, the latter calculational scheme is close to the quantum-mechanical one in spirit. The definition of two-particle exchange currents for the use in quantum mechanics is sketched.

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APPENDIX A: EVALUATION OF AUXILIARY QUANTITIES

The operators $G_0(K)|g_0(K)^{-1}$ and $g_0^{-1}|G_0(K)$ connect three-dimensional and four-dimensional basis states. The two operators are related by conjugation; we therefore discuss only one, i.e., $G_0(K)|g_0(K)^{-1}$.

The momentum space matrix elements of $G_0(K)|g_0(K)^{-1}$ for $K^+ > 0$, are

$$
\langle k_1^- k_1^+ \vec{k}_{1\perp} | G_0(K)|g_0(K)^{-1} | k_1^+ \vec{k}_{1\perp} \rangle = \frac{i}{2\pi} \frac{\delta (k_1^+ - k_1^-) \delta (\vec{k}_{1\perp}^+ - \vec{k}_{1\perp}^-)}{\left( k_1^+ - \frac{k_{1\perp}^2 + m_2^2 - io}{k_{1\perp}^+} \right)} \times \frac{(K^- - k_{1on}^- - k_{2on}^- + io) \theta(K^+ - k_1^+) \theta(k_1^-)}{\left( K^- - k_1^- - \frac{(k_{1\perp}^- - \vec{k}_{1\perp}^-)^2 + m_2^2 - io}{K^+ - k_1^+} \right)} .
$$

(A1)

When the available light-front “energy” $K^-$ is not on-shell, i.e., $K^- \neq k_{1on}^- + k_{2on}^-$. The two singular propagators $\left( k_{1\perp}^- - \frac{k_{1\perp}^2 + m_2^2 - io}{k_{1\perp}^+} \right)^{-1}$ and $\left( K^- - k_1^- - \frac{(k_{1\perp}^- - \vec{k}_{1\perp}^-)^2 + m_2^2 - io}{K^+ - k_1^+} \right)^{-1}$ can be rewritten as a $\delta$-function and principal-part singularity; integration on $k_1^-$ can be carried out with usual techniques.

A problem arises, when the available light-front “energy” $K^-$ is on-shell, i.e., $K^- = K_{on}^- = k_{1on}^- + k_{2on}^-$. Without losing generality, we will have suppose that $K^+ > 0$ and $k_1^+ > 0$. Then, $K^- - k_{1on}^- - k_{2on}^- + io = +io$ and the limiting process of going to the real axis must be performed with care. However, in this situation the matrix element will always be integrated with respect to $k_1^-$, over a function $f(k_1^-)$ still to be determined and, unfortunately with unknown analyticity properties, i.e.,

$$
\int dk_1^- f(k_1^-) \langle k_1^- k_1^+ \vec{k}_{1\perp} | G_0(K)|g_0(K)^{-1} | k_1^+ \vec{k}_{1\perp} \rangle = \frac{i}{2\pi} \frac{\delta (k_1^+ - k_1^-) \delta (\vec{k}_{1\perp}^+ - \vec{k}_{1\perp}^-)}{\left( k_1^+ - \frac{k_{1\perp}^2 + m_2^2 - io}{k_{1\perp}^+} \right)} \times \frac{1}{(K^- - k_1^- - k_{2on}^- + io)} \left( k_{1\perp}^- - \vec{k}_{1\perp}^- \right) .
$$

(A2)

Without any loss of generality, we can think of $f(k_1^-)$ as being split into a part $f_{uhp}(k_1^-)$ having singularities only in the upper half $k_1^-\text{-plane}$ and a part $f_{lhp}(k_1^-)$ having singularities only in the lower half $k_1^-\text{-plane}$, i.e.,

$$
f(k_1^-) = f_{uhp}(k_1^-) + f_{lhp}(k_1^-) .
$$

(A3)
In the case that there is a part with poles simultaneously in both half planes, they can be fully separated, i.e.,

\[
g(k_1^-) \frac{1}{k_1^- - \alpha_1 - i\alpha_2} \frac{1}{k_1^- - \beta_1 + i\beta_2} = g(k_1^-) \frac{1}{(\alpha - \beta) + i(\alpha_2 + \beta_2)} \left[ \frac{1}{k_1^- - \alpha_1 - i\alpha_2} - \frac{1}{k_1^- - \beta_1 + i\beta_2} \right] \tag{A4}
\]

with \( g(k_1^-) \) being singularity free. The integration in Eq.(A2) can now be carried out using Cauchy’s theorem:

\[
\int dk_1^- f(k_1^-) \langle k_1^- k_1^+ \bar{k}_{1\perp} \mid G_0(K) \mid g_0(K)^{-1} \mid k_1^+ \bar{k}_{1\perp} \rangle = \delta \left( k_1^+ - k_1^+ \right) \delta \left( \vec{k}_{1\perp} - \vec{k}_{1\perp} \right) \times 
\left( \frac{1}{K^--k_{1on}^- - k_{2on}^- + i\alpha} \right) \times 
\left[ f_{uhp}(k_{1on}^-) \frac{1}{K^- - k_{1on}^- - k_{2on}^- + i\alpha} + f_{lhp}(K^- - k_{2on}^-) \frac{1}{K^- - k_{2on}^- - k_{1on}^- + i\alpha} \right] 
= \delta \left( k_1^+ - k_1^+ \right) \delta \left( \vec{k}_{1\perp} - \vec{k}_{1\perp} \right) \left[ f_{uhp}(k_{1on}^-) + f_{lhp}(K^- - k_{2on}^-) \right]. \tag{A5}
\]

We note that propagators cancel and no singularity remains. However, the result (A5) is for practical purposes useless, since the split into two parts with disjoint singularities is not known in a numerical calculation. If, however, the light-front ”energy” is on-shell, \( K^- = K_{on}^- \), then the two terms can be recombined to the original function, i.e.,

\[
\int dk_1^- f(k_1^-) \langle k_1^- k_1^+ \bar{k}_{1\perp} \mid G_0(K) \mid g_0(K)^{-1} \mid k_1^+ \bar{k}_{1\perp} \rangle = \delta \left( k_1^+ - k_1^+ \right) \delta \left( \vec{k}_{1\perp} - \vec{k}_{1\perp} \right) f(k_{1on}^-) \tag{A6}
\]

for \( K^- = K_{on}^- \).
APPENDIX B: INTERACTION IN FIRST ORDER

The interaction $w(k)$, defined by Eqs. (37) and (11) to lowest order of the driving term $V(K)$, is given by

$$w^{(2)}(K) = g_0(K)^{-1}|G_0(K)V(K)G_0(K)|g_0(K)^{-1}, \quad (B1)$$

where the matrix element of the operator $|G_0(K)V(K)G_0(K)|$ is

$$\langle k_1^+ \vec{k}_{1\perp} \mid |G_0(K)V(K)G_0(K)| \mid k_1^+ k_{1\perp} \rangle = i \frac{(ig_s)^2}{(2\pi)^2} \int dk_1^- dk_1^-$$

$$\times \frac{1}{k_1^+(K^+ - k_1^+) \left( k_1^- - \frac{k_1^+ + m_1^2 - i\omega}{k_1^+} \right)} \left( k^- - k_1^- - \frac{(k_1^- - k_1^\perp)^2 + m_1^2 - i\omega}{k_1^- - k_1^+} \right)$$

$$\times \frac{1}{k_1^+(K^+ - k_1^+) \left( k_1^- - \frac{k_1^+ + m_1^2 - i\omega}{k_1^+} \right)} \left( k^- - k_1^- - \frac{(k_1^- - k_1^\perp)^2 + m_1^2 - i\omega}{k_1^- - k_1^+} \right). \quad (B2)$$

The double integration in $k^-$ in Eq. (B2) is performed analytically using Cauchy’s theorem and the condition $K^+ > 0$. The integration is nonzero for $K^+ > k_1^+$, and $K^+ > k_1^+ > 0$. Two possibilities also appear for $\sigma$ forward propagation. For $k_1^+ > k_1^+$, a $\sigma$ is emitted by particle 1 and otherwise absorbed:

$$\langle k_1^+ \vec{k}_{1\perp} \mid |G_0(K)V(K)G_0(K)| \mid k_1^+ k_{1\perp} \rangle = (ig_s)^2 \frac{i\theta(K^+ - k_1^+)}{k_1^+(K^+ - k_1^+) \left( k^- - k_1^- - k_{1\perp}^+- k_{2\perp}^- + i\omega \right)}$$

$$\times \left( \frac{\theta(k_1^+ - k_1^+)}{k_1^+(K^+ - k_1^+) \left( k^- - k_1^- - k_{1\perp}^+- k_{2\perp}^- + i\omega \right)} + \frac{\theta(k_1^+ - k_1^+)}{k_1^+(K^+ - k_1^+) \left( k^- - k_1^- - k_{1\perp}^+- k_{2\perp}^- + i\omega \right)} \right)$$

$$\times \frac{i\theta(K^+ - k_1^+)}{k_1^+(K^+ - k_1^+) \left( k^- - k_1^- - k_{1\perp}^+- k_{2\perp}^- + i\omega \right)} \right), \quad (B3)$$

where the light-front “energies” of the intermediate states of the individual particles are given by

$$k_{1\perp}^2 = \frac{k_{1\perp}^2 + m_1^2}{k_1^+},$$

$$k_{1\perp}^2 = \frac{k_{1\perp}^2 + m_1^2}{k_1^+},$$

25
\[
\begin{align*}
    k_{2on}^- &= \frac{(\vec{K}_\perp - \vec{k}_{1\perp})^2 + m_2^2}{K^+ - k_{1\perp}^+}, \\
    k_{2on}^- &= \frac{(\vec{K}_\perp - \vec{k}_{1\perp})^2 + m_2^2}{K^+ - k_{1\perp}^+}, \\
    k_{\sigma on}^- &= \frac{\vec{k}_{1\perp}^2 - \vec{k}_{1\perp}^2 + \mu^2}{k^+_1 - k_{1\perp}^+}, \\
    k_{\sigma on}^- &= \frac{\vec{k}_{1\perp}^2 - \vec{k}_{1\perp}^2 + \mu^2}{k^+_1 - k_{1\perp}^+}. 
\end{align*}
\]  

(B4)

The global three-particle propagator for 1, 2 and \(\sigma\) appears in Eq.(B3), in two cases: when \(\sigma\) is either emitted or absorbed by particle 1.

The matrix element \( \langle k_{1\perp}^+ \vec{k}_{1\perp}^- | w^{(2)}(K) | k_{1\perp}^+ \vec{k}_{1\perp}^- \rangle \) is obtained from Eq.(B3) by multiplying both sides by the matrix element of the operator \( g_0(K)^{-1} \) from Eq.(25).

\[
\begin{align*}
    \langle k_{1\perp}^+ \vec{k}_{1\perp}^- | w^{(2)}(K) | k_{1\perp}^+ \vec{k}_{1\perp}^- \rangle &= \\
    = (igs)^2 \frac{\theta(k_{1\perp}^+ - k_{1\perp}^+)}{(k_{1\perp}^+ - k_{1\perp}^+)} \frac{i}{(K^- - k_{1on}^- - k_{2on}^- - k_{\sigma on}^- + io)} \\
    + (igs)^2 \frac{\theta(k_{1\perp}^+ - k_{1\perp}^+)}{(k_{1\perp}^+ - k_{1\perp}^+)} \frac{i}{(K^- - k_{1on}^- - k_{2on}^- - k_{\sigma on}^- + io)} \\
    = (igs)^2 \frac{\theta(k_{1\perp}^+ - k_{1\perp}^+)}{(k_{1\perp}^+ - k_{1\perp}^+)} \frac{i}{(K^- - \frac{k_{2\perp}^2 + m_2^2}{k_{1\perp}^+} - (\vec{k}_{1\perp} - \vec{k}_{1\perp})^2 + m_2^2 - \frac{(\vec{k}_{1\perp} - \vec{k}_{1\perp})^2 + \mu^2}{k_{1\perp}^+ - k_{1\perp}^+} + io)} \\
    + (igs)^2 \frac{\theta(k_{1\perp}^+ - k_{1\perp}^+)}{(k_{1\perp}^+ - k_{1\perp}^+)} \frac{i}{(K^- - \frac{k_{2\perp}^2 + m_2^2}{k_{1\perp}^+} - (\vec{k}_{1\perp} - \vec{k}_{1\perp})^2 + m_2^2 - \frac{(\vec{k}_{1\perp} - \vec{k}_{1\perp})^2 + \mu^2}{k_{1\perp}^+ - k_{1\perp}^+} + io)}. 
\end{align*}
\]  

(B5)
APPENDIX C: INTERACTION IN SECOND ORDER

The interaction $w(k)$, defined by Eqs.(37) and (11) to second order in the driving term $V(K)$, is given by

$$w(K) \simeq w^{(2)}(K) + w^{(4)}(K)$$  \hspace{1cm} (C1)

where $w^{(2)}(K)$ is given by Eq.(B5) and

$$w^{(4)}(K) = g_0(K)^{-1}|G_0(K)\delta V(K)G_0(K)\delta V(K)G_0(K)|g_0(K)^{-1}$$  
$$- g_0(K)^{-1}|G_0(K)\delta V(K)\tilde{G}_0(K)\delta V(K)G_0(K)|g_0(K)^{-1}.$$  \hspace{1cm} (C2)

The second term in Eq.(C2) corresponds to the iteration of the interaction $w^{(2)}(K)$

$$g_0(K)^{-1}|G_0(K)\delta V(K)\tilde{G}_0(K)\delta V(K)G_0(K)|g_0(K)^{-1} =$$
$$= g_0(K)^{-1}|G_0(K)\delta V(K)G_0(K)|g_0(K)^{-1}|G_0(K)\delta V(K)G_0(K)G_0(K)|g_0(K)^{-1}$$
$$= w^{(2)}g_0(K)w^{(2)}.$$  \hspace{1cm} (C3)

The matrix element of the operator $|G_0(K)\delta V(K)G_0(K)\delta V(K)G_0(K)|$ is

$$\langle k_1^+k_1^-|G_0(K)\delta V(K)G_0(K)\delta V(K)G_0(K)||k_1^+\tilde{k}_1 \rangle = \frac{(ig_s)^4}{2(2\pi)^6} \int dk_1^-dp_1^-dk_1^-dp_1^+d^2p_1$$
$$\times \frac{1}{k_1^+\left(K^+-k_1^+ight)} \frac{1}{\left(k_1^--k_1^\prime^+-m_2^{-}\right)} \frac{1}{\left(K^--k_1^--\frac{(K_1^-\tilde{k}_1^-)^2+m_2^{-}}{k_1^+\tilde{k}_1^-}\right)}$$
$$\times \frac{1}{\left(k_1^+\tilde{k}_1^\prime^+-p_1^+\right)} \frac{1}{\left(k_1^--p_1^--\frac{(K_1^-\tilde{k}_1^-)^2+\mu^2}{k_1^+\tilde{k}_1^-}\right)}$$
$$\times \frac{1}{p_1^+(K_-\tilde{p}_1)} \frac{1}{p_1^--p_1^\prime^--\frac{(p_1^\prime-\tilde{p}_1^\prime)^2+\mu^2}{p_1^\prime-k_1^-}}$$
$$\times \frac{1}{(p_1^+^--k_1^+)} \frac{1}{(p_1^-\tilde{k}_1^-\tilde{p}_1^--\frac{(p_1^\prime-\tilde{p}_1^\prime)^2+\mu^2}{p_1^\prime-k_1^-}}$$
$$\times \frac{1}{k_1^+(K^+-k_1^+)} \frac{1}{k_1^--k_1^\prime^--\frac{(K_1^-\tilde{k}_1^-)^2+2m_2}\{k_1^+\tilde{k}_1^-\}}.$$  \hspace{1cm} (C4)

The on-energy-shell values of the light-front minus momentum in Eq.(C4) are given in Eq.(B4), and
The matrix element \( \langle k_1^+, \vec{k}_{1\perp} | G_0(K) \psi(K) G_0(K) \psi(K) G_0(K) | k_1^+, \vec{k}_{1\perp} \rangle \) is found by analytical integration in the light-front “energies” in Eq.(C4). To separate the intermediate four particle propagation, which occurs for \( k_1^+ \), \( p_1^+ \) and \( k_1^+ \) satisfying \( 0 < k_1^+ < p_1^+ < k_1^+ < K^+ \), the following factorization is necessary

\[
\begin{align*}
p_{1\text{on}}^- &= \frac{p_{1\perp}^2 + m_1^2}{p_1^+}, \\
p_{2\text{on}}^- &= \frac{(\vec{K}_{\perp} - \vec{p}_{1\perp})^2 + m_2^2}{K^+ - p_1^+}.
\end{align*}
\] 

(C5)

After the Cauchy integration in the light-front “energies” the result for \( \langle k_1^+, \vec{k}_{1\perp} | G_0(K) \psi(K) G_0(K) \psi(K) G_0(K) | k_1^+, \vec{k}_{1\perp} \rangle \) in the region of \( 0 < k_1^+ < p_1^+ < k_1^+ < K^+ \), which is denoted by \( \langle k_1^+, \vec{k}_{1\perp} | G_0(K) \psi(K) G_0(K) \psi(K) G_0(K) | (a) k_1^+, \vec{k}_{1\perp} \rangle \), is given by

\[
\begin{align*}
\langle k_1^+, \vec{k}_{1\perp} | G_0(K) \psi(K) G_0(K) \psi(K) G_0(K) | (a) k_1^+, \vec{k}_{1\perp} \rangle &= \frac{(igs)^4}{2(2\pi)^3} \int dp_1^+ d^2p_{1\perp} \frac{\theta(k_1^+)}{k_1^+(K^+ - k_1^+)} \frac{\theta(K^+ - k_1^+)}{K^+ - k_1^+ - \frac{(\vec{K}_{\perp} - \vec{p}_{1\perp})^2 + m_2^2}{K^+ - k_1^+ + io}} \\
&\times \left[ F'(K) + F''(K) \right] \frac{\theta(k_1^+)}{k_1^+(K^+ - k_1^+)} \frac{\theta(K^+ - k_1^+)}{K^+ - k_1^+ - \frac{(\vec{K}_{\perp} - \vec{p}_{1\perp})^2 + m_2^2}{K^+ - k_1^+} + io}.
\end{align*}
\] 

(C7)

with

\[
\begin{align*}
F'(K) &= \frac{\theta(k_1^+ - p_1^+)}{(k_1^+ - p_1^+)} \frac{\theta(p_1^+)}{p_1^+(K^+ - p_1^+)} \frac{\theta(K^+ - p_1^+)}{K^+ - p_1^+ - \frac{(\vec{K}_{\perp} - \vec{p}_{1\perp})^2 + m_2^2}{K^+ - p_1^+} + io} \\
&\times \frac{i}{k_1^+(K^+ - p_1^+)} \frac{\theta(K^+ - p_1^+)}{K^+ - p_1^+ - \frac{(\vec{K}_{\perp} - \vec{p}_{1\perp})^2 + m_2^2}{K^+ - p_1^+} + io} \\
&\times \frac{\theta(p_1^+ - k_1^+)}{(p_1^+ - k_1^+)} \frac{i}{K^+ - p_1^+ - \frac{(\vec{K}_{\perp} - \vec{p}_{1\perp})^2 + m_2^2}{K^+ - p_1^+} + io}.
\end{align*}
\] 

(C8)
\[ F''(K) = \frac{\theta(k_1^{'+} - p_1^+)}{(k_1^+ - p_1^+)} \frac{i}{K^- - \frac{\varepsilon_1^2 + m_1^2}{k_1^+} - \frac{(K_\perp - \varepsilon_1^\perp)^2 + m_1^2}{K^- - k_1^+} - \frac{(\varepsilon_1^\perp - \varepsilon_1^\perp)^2 + \mu^2}{k_1^+ - p_1^+} + i\omega} \times \frac{i}{K^- - \frac{\varepsilon_1^2 + m_1^2}{k_1^+} - \frac{(K_\perp - \varepsilon_1^\perp)^2 + m_1^2}{K^- - k_1^+} - \frac{(\varepsilon_1^\perp - \varepsilon_1^\perp)^2 + \mu^2}{k_1^+ - p_1^+} + i\omega} \times \frac{\theta(p_1^+ - k_1^+)}{(p_1^+ - k_1^+)} \frac{i}{K^- - \frac{\varepsilon_1^2 + m_1^2}{k_1^+} - \frac{(K_\perp - \varepsilon_1^\perp)^2 + m_1^2}{K^- - p_1^+} - \frac{(\varepsilon_1^\perp - \varepsilon_1^\perp)^2 + \mu^2}{p_1^+ - k_1^+} + i\omega}. \] (C9)

The part of the propagator given by Eq. (C7) contains the virtual light-front propagation of intermediate states with up to four particles. The function \( F' \) contains only intermediate states up to three particles and is two-body reducible. It will eventually be canceled by the corresponding piece in the second term in (C2). The function \( F'' \) has one intermediate state in which four-particle propagator which can be recognized as the middle piece of Eq. (C9). The other possibility which includes up to four particles in the intermediate state propagation is given by \( 0 < k_1^+ < p_1^+ < k_1^+ < K^+ \). To obtain this part, we perform the transformation \( k_1^+ \leftrightarrow k_1 \) in Eq. (C7).

The contribution of the region \( 0 < p_1^+ < k_1^+ < k_1^+ < K^+ \) to the matrix element \( \langle k_1^+ \varepsilon_1^\perp \mid ||G_0(K)V(K)G_0(K)G_0(K)|| \mid k_1^+ \varepsilon_1^\perp \rangle \) is denoted by \( \langle k_1^+ \varepsilon_1^\perp \mid ||G_0(K)V(K)G_0(K)V(K)G_0(K)|| \mid 0 \rangle \mid k_1^+ \varepsilon_1^\perp \rangle \). It contains only up to three-particle intermediate states and is two-body reducible. Consequently, it will be canceled by the corresponding piece of the second term in (C2). It is given by

\[
\langle k_1^+ \varepsilon_1^\perp \mid ||G_0(K)V(K)G_0(K)V(K)G_0(K)|| \mid 0 \rangle \mid k_1^+ \varepsilon_1^\perp \rangle = \frac{(i\gamma_5)^4}{2(2\pi)^3} \int dp_1^+ d^2 p_1^- \frac{\theta(k_1^{'+})\theta(K^- - k_1^{'+})}{k_1^{'+}(K^- - k_1^{'+})} \frac{i}{K^- - \frac{\varepsilon_1^2 + m_1^2}{k_1^{'+}} - \frac{(K_\perp - \varepsilon_1^\perp)^2 + m_1^2}{K^- - k_1^{'+}} - \frac{(\varepsilon_1^\perp - \varepsilon_1^\perp)^2 + \mu^2}{k_1^{'+} - p_1^+} + i\omega} \times \frac{\theta(k_1^{'+} - k_1^+)}{(k_1^{'+} - k_1^+)} \frac{i}{K^- - \frac{\varepsilon_1^2 + m_1^2}{k_1^{'+}} - \frac{(K_\perp - \varepsilon_1^\perp)^2 + m_1^2}{K^- - k_1^+} - \frac{(\varepsilon_1^\perp - \varepsilon_1^\perp)^2 + \mu^2}{k_1^+ - p_1^+} + i\omega} \times \frac{\theta(p_1^+)\theta(K^- - p_1^+)}{p_1^+(K^- - p_1^+)} \frac{i}{K^- - \frac{\varepsilon_1^2 + m_1^2}{p_1^+} - \frac{(K_\perp - \varepsilon_1^\perp)^2 + m_1^2}{K^- - p_1^+} + i\omega} \times \frac{\theta(k_1^+ - p_1^+)}{(k_1^+ - p_1^+)} K^- - \frac{\varepsilon_1^2 + m_1^2}{p_1^+} - \frac{(K_\perp - \varepsilon_1^\perp)^2 + m_1^2}{K^- - k_1^+} - \frac{(\varepsilon_1^\perp - \varepsilon_1^\perp)^2 + \mu^2}{k_1^+ - p_1^+} + i\omega.
\]
\[ \times \frac{\theta(k_1^+ \theta(K^+ - k_1^-))}{k_1^+ (K^+ - k_1^-)} \frac{i}{K^- - \frac{k_{1\perp}^2 + m_1^2}{k_1^+} - \frac{(K_{\perp} - k_{1\perp})^2 + m_2^2}{K^+ - k_1^+}}. \]  

(C10)

For the momentum region satisfying \( 0 < k_1'^+ < k_1^+ < p_1^+ < K^+ \), the contribution to the matrix element \( \langle k_1'^+ k_1\perp \mid |G_0(K)V(K)G_0(K)V(K)G_0(K)| \mid k_1'^+ k_1\perp \rangle \) can be obtained from Eq.(C10) by performing the following transformation on the kinematical momentum:

\( k_1' \leftrightarrow K - k_1', k_1 \leftrightarrow K - k_1 \) and \( m_1 \leftrightarrow m_2 \). From Eqs. (C9) and (C10), the following result is obtained

\[ \langle k_1'^+ k_1\perp \mid |G_0(K)V(K)G_0(K)V(K)G_0(K)| \mid k_1'^+ k_1\perp \rangle = \]

\( = \left( \langle k_1'^+ k_1\perp \mid |G_0(K)V(K)G_0(K)V(K)G_0(K)|_{(a)} \mid k_1'^+ k_1\perp \rangle + [k_1' \leftrightarrow k_1] \right) \]

\( + \left( \langle k_1'^+ k_1\perp \mid G_0(K)V(K)G_0(K)V(K)G_0(K)\rangle_{(b)} \mid k_1'^+ k_1\perp \rangle \right) \]

\( + [k_1' \leftrightarrow K - k_1', k_1 \leftrightarrow K - k_1, m_1 \leftrightarrow m_2] \).  

(C11)

The subtraction of the iterated first order driving term in Eq.(C2) cancels the corresponding terms in Eq.(C11) such that the matrix element \( \langle k_1'^+ k_1\perp \mid w^{(4)}(K) \mid k_1'^+ k_1\perp \rangle \) is two-body irreducible with a global four-body propagation. It is obtained from Eqs.(C7), (C9) and (C2) as

\[ \langle k_1'^+ k_1\perp \mid w^{(4)}(K) \mid k_1'^+ k_1\perp \rangle = \]

\( = \frac{(ig)^4}{2(2\pi)^3} \int dp_1^+ dp_1\perp \theta(k_1'^+ - p_1^+) \frac{\theta(k_1'^+ - p_1^-)}{(k_1'^+ - p_1^-)} \frac{i}{K^- - \frac{p_{1\perp}^2 + m_1^2}{p_1^+} - \frac{(K_{\perp} - k_{1\perp})^2 + m_2^2}{K^+ - k_1^+} - \frac{(k_{1\perp} - p_{1\perp})^2 + \mu^2}{k_1'^+ - p_1^-} + io} \]

\( \times \frac{i}{K^- - \frac{\hat{p}_{1\perp}^2 + m_1^2}{k_1'} - \frac{(\hat{K}_{\perp} - \hat{k}_{1\perp})^2 + m_2^2}{k_1'^+ - p_1^-} - \frac{(\hat{k}_{1\perp} - \hat{p}_{1\perp})^2 + \mu^2}{p_1^+ - k_1'^+} + io} \]

\( \times \theta(p_1^+ - k_1'^+) \)

\( \frac{1}{(p_1^+ - k_1^+)} \cdot \frac{i}{K^- - \frac{\hat{p}_{1\perp}^2 + m_1^2}{k_1'} - \frac{(\hat{K}_{\perp} - \hat{k}_{1\perp})^2 + m_2^2}{k_1'^+ - p_1^-} - \frac{(\hat{k}_{1\perp} - \hat{p}_{1\perp})^2 + \mu^2}{p_1^+ - k_1'^+} + io} \]

\( + [k_1' \leftrightarrow k_1] \).

(C12)
APPENDIX D: INTEGRAL EQUATION FOR THE BOUND-STATE

In the approximation considered, the vertex function satisfies an integral equation with the kernel containing two parts, one corresponding to Eq.(B5) and the other to Eq.(C12). The plus momentum are rescaled by $K^+$, such that the momentum fractions $x = \frac{k_1^+}{K}$, $y = \frac{k_1^+ + p_1^+}{K}$, and $z = \frac{p_1^+}{K}$, are used. The notation $\langle k_1^+ \tilde{k}_{1\perp} | \gamma_B \rangle \equiv \tilde{\gamma}_B(y, \tilde{k}_{1\perp})$ is introduced. The homogeneous integral equation for the light-front vertex function is evaluated in the center of mass system,

$$\gamma_B(y, \tilde{k}_{1\perp}) = \frac{1}{(2\pi)^3} \int \frac{d^2k_{1\perp} dx}{2x(1-x)} \frac{K^{(2)}(y, \tilde{k}_{1\perp}; x, \tilde{k}_{1\perp}) + K^{(4)}(y, \tilde{k}_{1\perp}; x, \tilde{k}_{1\perp})}{M_B^2 - M_0^2} \gamma_B(x, \tilde{k}_{1\perp}) , \quad (D1)$$

where the free two-body mass is $M_0^2 = \frac{E_1^2 + m_1^2}{x(1-x)}$ and $0 < x < 1$.

The part of the kernel which has only the propagation of virtual three particles forward in the light-front time is obtained from Eq.(B5),

$$K^{(2)}(y, \tilde{k}_{1\perp}; x, \tilde{k}_{1\perp}) = g_S^2 \frac{\theta(y) \theta(x)}{(x - y) \left( M_B^2 - \frac{k_{1\perp}^2 + m_1^2}{y} - \frac{k_{1\perp}^2}{1 - x} - \frac{(k_{1\perp}^2 - \tilde{k}_{1\perp}^2)^2 + \mu^2}{x - y} \right)} + \left[ x \leftrightarrow y, \tilde{k}_{1\perp} \leftrightarrow \tilde{k}_{1\perp} \right]. \quad (D2)$$

Eq.(D1) with the effective interaction given by (D2) corresponds to the Weinberg equation derived from the BSE in the infinitum momentum frame [16]. It has also been solved in Ref. [17] and in Ref. [18] including self-energy correction. The equivalent equation for fermions has been discussed in Ref. [19].

The contribution to the kernel from the virtual four-body propagation is obtained from Eq.(C12),

$$K^{(4)}(y, \tilde{k}_{1\perp}; x, \tilde{k}_{1\perp}) = \frac{g_S^4}{(2\pi)^3} \int \frac{d^2p_1 d\theta}{2\pi (1 - z)(z - x) (y - z)} \frac{\theta(z - y) \theta(x - z)}{M_B^2 - \frac{k_{1\perp}^2 + m_1^2}{y} - \frac{p_{1\perp}^2 + m_1^2}{1 - z} - \frac{(p_{1\perp}^2 - \tilde{k}_{1\perp}^2)^2 + \mu^2}{z - y}} \times \left( M_B^2 - \frac{k_{1\perp}^2 + m_1^2}{y} - \frac{k_{1\perp}^2}{1 - x} - \frac{(k_{1\perp}^2 - \tilde{k}_{1\perp}^2)^2 + \mu^2}{x - y} \right)$$

$$\times \left( M_B^2 - \frac{p_{1\perp}^2 + m_1^2}{z} - \frac{k_{1\perp}^2 + m_1^2}{1 - x} - \frac{(p_{1\perp}^2 - \tilde{k}_{1\perp}^2)^2 + \mu^2}{x - z} \right) + \left[ x \leftrightarrow y, \tilde{k}_{1\perp} \leftrightarrow \tilde{k}_{1\perp} \right]. \quad (D3)$$
Eqs. (D1)-(D3) are easily recognized to be covariant under kinematical light-front boosts. However, the covariance of the four-dimensional wave-function (41) is certainly lost by a finite expansion of $W(K)$ in Eq. (11) and the use of the corresponding $w(K)$ while covariance continues to hold for the solution of Eq. (11).
REFERENCES


FIGURE CAPTIONS

Fig.1. Light-front time ordered diagrams for $w^{(2)}(K)$ (a) and $w^{(4)}(K)$ (b), representing the light-front time ordered view of one and two $\sigma$ exchanges, respectively.

Fig.2. Results for $g_s$ as a function of the two-body bound state mass $M_B$ for $\mu = 0.5m$. Numerical solution of the covariant four-dimensional BSE (49) (solid curve), the light-front Eq.(38) with interaction including up to three-particles in the intermediate states, i.e., with $w(K_B) \simeq w^{(2)}(K_B)$ (dashed curve) and including up to four-particles in the intermediate states, i.e., with $w(K_B) \simeq w^{(2)}(K_B) + w^{(4)}(K_B)$ (dotted curve). Solution of the quantum mechanics squared mass eigenvalue equation (60), with $w(K_v) \simeq w^{(2)}(K_v)$ (long-dashed curve), and with $w(K_v) \simeq w^{(2)}(K_v) + w^{(4)}(K_v)$ (short-dashed curve) defining the two-particle potential in Eq.(63).

Fig.3. Results for the transverse momentum distribution $f(q)$ as a function of the transverse component, $q$, of the individual four-momentum, for $M_B = 0$ and $\mu = 0.5m$: (a) numerical solution of the four-dimensional BSE with $g_s = 20.14$; (b) relative error of the various approximations with respect to the four-dimensional BSE results, defined by $Df(q) = 1 - f^{(n)}_{\text{app}}(q)/f_{\text{exact}}(q)$ with $n = 2$ and 4. Results for the light-front Eq.(38) with an interaction including up to three-particles in the intermediate states, i.e., with $w(K_B) \simeq w^{(2)}(K_B)$ where $g_s = 20.8$ (dashed curve) and with an interaction including up to four-particles in the intermediate states, i.e., with $w(K_B) \simeq w^{(2)}(K_B) + w^{(4)}(K_B)$ where $g_s = 20.2$ (dotted curve). Solutions of the quantum mechanics squared mass eigenvalue equation (60), with the two-particle potential in Eq.(63) defined by $w(K_v) \simeq w^{(2)}(K_v)$ where $g_s = 15.7$ (long-dashed curve), and with $w(K_v) \simeq w^{(2)}(K_v) + w^{(4)}(K_v)$ where $g_s = 14.9$ (short-dashed curve).

Fig.4. Results for the transverse momentum distribution $f(q)$ as a function of the transverse component, $q$, of the individual four-momentum, for $M_B = 1.98m$ and $\mu = 0.5m$: (a) numerical solution of the four-dimensional BSE with $g_s = 9.03$ ; (b) relative error of the various approximations in respect to the four-dimensional BSE results, defined by $Df(q) =$
$1 - \frac{f_{\text{app}}^{(n)}(q)}{f_{\text{exact}}(q)}$ with $n = 2$ and 4. Results for the light-front Eq.(38) with interaction including up to three-particles in the intermediate states, i.e., with $w(K_B) \simeq w^{(2)}(K_B)$ where $g_s = 9.10$ (dashed curve) and with an interaction including up to four-particles in the intermediate states, i.e., with $w(K_B) \simeq w^{(2)}(K_B) + w^{(4)}(K_B)$ where $g_s = 9.03$ (dotted curve). Solutions of the quantum mechanics squared mass eigenvalue equation (60), with the two-particle potential in Eq.(63) defined by $w(K_v) \simeq w^{(2)}(K_v)$ where $g_s = 8.33$ (long-dashed curve), and with $w(K_v) \simeq w^{(2)}(K_v) + w^{(4)}(K_v)$ where $g_s = 8.23$ (short-dashed curve).
FIGURES

Fig. 1a

Fig. 1b
FIG. 2

\[ S_\parallel \]

$\mu=0.5$

4D (solid)

LF–3P (dashed)

LF–4P (dotted)

QM–3P (long-dashed)

QM–4P (short-dashed)
FIG. 3a

\[ f(q) \]

\[ \mu = 0.5 \quad M_0 = 0 \]
FIG. 4a

\( \mu = 0.5 \quad M_0 = 1.98 \)
FIG. 2

\( \mu = 0.5 \)
4D (solid)
LF–3P (dashed)
LF–4P (dotted)
QM–3P (long–dashed)
QM–4P (short–dashed)
FIG. 4a

\[ \mu = 0.5 \quad M_B = 1.98 \]