On quantum error-correction by classical feedback in discrete time

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We consider the problem of correcting the errors incurred from sending quantum information through a noisy quantum environment by using classical information obtained from a measurement on the environment. For discrete time Markovian evolutions, in the case of fixed measurement on the environment, we give criteria for quantum information to be perfectly corrigible and characterize the related feedback. Then we analyze the case when perfect correction is not possible and, in the qubit case, we find optimal feedback maximizing the channel fidelity.

I. INTRODUCTION

Error correction is a key problem in quantum information processing. Without it, decoherence would easily destroy all hopes for quantum computation and quantum cryptography.

Two important approaches have been developed to combat decoherence. The usual theory of quantum error-correction [1, 2] redundantly encodes the original quantum information in a larger quantum system by a unitary operation which maps the initial Hilbert space into the code space, a subspace of the Hilbert space associated to this larger system. After encoding, the larger system is subjected to noise and then a measurement is performed on the system to diagnose the type of error which occurred. Finally, on the basis of the outcome, a restoring operation is performed to return the system to the original state in the code space.

Another approach [3, 4, 5, 6, 7], based on feedback control, has been developed for systems which are continuously monitored during their noisy evolution. It employs the result of this continuous measurement to determine the errors occurred and, on this basis, perform corrections in real time to protect states which are known to lie initially within a certain code space. The continuous measurement can be performed introducing an additional interaction to the evolution of the system or preferably by simply observing the environment after its interaction with the system. Up to now there is no general theory for quantum feedback control, but some correction schemes have been considered and have dealt only with Hamiltonian feedback.

Taking from feedback control the idea of a correction scheme based on a measurement performed not on the system but on the environment, we have analyzed in an earlier publication [8] the different possible behaviors of a channel with respect to the existence of a measurement allowing perfect correction of information, quantum or classical. No code space is introduced and, for every initial state, the aim is to find proper measurement and restoring operations, not necessarily unitary, to recover the initial information or at least optimally restore it.

Here we develop the analysis in [8] to evolutions composed of many time steps. We consider quantum information carried by a system undergoing a discrete time Markovian evolution (multi-step channel \( T = T^{(n)} \circ \cdots \circ T^{(1)} \)) and allow correction operations between any two subsequent steps: every time we perform a measurement on the environment and a restoring operation on the system. We take the measurements on the environment as given and we look for the best restoring operations chosen on the basis of all the outcomes observed so far. First we give conditions for quantum information to be perfectly corrigible and characterize the related feedback. It turns out that classical feedback is not useful because perfect correction of quantum information is possible only if a unique correction at the end would suffice. Then we analyze the case when perfect correction is not possible and, in the qubit case, we find optimal feedback maximizing the channel fidelity. Similarly to the case of perfect correction, but more surprisingly, classical feedback is still useless if quantum information carried by one qubit because again a unique restoring operation performed at the end of the evolution guarantees the same performance of correction. Anyway classical feedback is shown to be helpful when the quantum carrier has a larger Hilbert space.

Every Section of the paper considers first the case of quantum information sent through a single-step channel, so that it is possible only one correction after this noisy evolution just as in [8], and then the case of a multi-step
channel, so that classical feedback is possible during the noisy evolution. In Section III we set up the framework and the basic correction scheme. In Section III we prove the basic criteria for the existence of a correction scheme for a given channel and given measurements on the environment, and we characterize the related feedback. In Section IV we look for optimal correction scheme when it is not be possible to achieve a complete correction of errors and ...

II. THE CORRECTION SCHEME

We consider quantum information carried by a quantum system with finite dimensional Hilbert space $\mathcal{H}$. We work in the Schrödinger picture, so the action of the noisy channel, which corrupts the information transforming each input density operator $\rho$ on $\mathcal{H}$ to a different output density operator $T(\rho)$ on $\mathcal{H}$, is given by a completely positive, trace preserving, linear map $T : \mathcal{L}(\mathcal{H}) \rightarrow \mathcal{L}(\mathcal{H})$, where $\mathcal{L}(\mathcal{H})$ denotes the space of all linear operators on $\mathcal{H}$. A channel $T$ is not physically reversible, i.e. there is no channel $R$ such that $R \circ T = \text{id}$, unless $T$ is a unitary channel $T(\rho) = u \rho u^*$, with $u \in U(\mathcal{H})$, the group of unitary operators on $\mathcal{H}$.

A. Single-step channel

Every channel can be described as the result of a unitary coupling to an environment, followed by the discard of the environment after the interaction. Nevertheless, the initial information carried by $\mathcal{H}$ is then shared with the environment and indeed, if we controlled perfectly the combined system, then we could recover the initial quantum information simply by reversing the global evolution, so restoring perfectly the input state $\rho$. We do not hypothesize this, but we assume that our control on the environment is good enough to have its initial state pure and to be able to perform any measurement on it after the interaction with $\mathcal{H}$. The measurement of an observable $X$ on the environment decomposes the channel $T$ into an instrument, a family of completely positive maps $T_x$ giving the (non-normalized) output states $T_x(\rho)$ of the subensembles of systems selected according to the result “$x$” of this measurement: the probability of observing $x$ is $P(X = x) = \text{tr} T_x(\rho)$, the normalized output state for the corresponding subensemble is $T_x(\rho)/\text{tr} T_x(\rho)$, and the expectation in that subensemble of a self-adjoint $A \in \mathcal{L}(\mathcal{H})$ is $\text{tr}(T_x(\rho) A)/\text{tr} T_x(\rho)$. Ignoring the result of the measurement one recovers the original channel

$$T = \sum_x T_x. \tag{1}$$

Of course, the result $x$ of the measurement gives classical information about the environment after the interaction, and hence also about $\mathcal{H}$ before the interaction. The idea for the correction scheme is to employ this information to select a proper restoring channel: we introduce a family of channels $R^{(x)} : \mathcal{L}(\mathcal{H}) \rightarrow \mathcal{L}(\mathcal{H})$ where $R^{(x)}$ can depend in an arbitrary way on $x$. After correction, the state of the subensemble for which the measurement has given the result $x$, will be $R^{(x)}(T_x(\rho))$ up to the normalization factor $\text{tr}(T_x(\rho))$. The overall corrected channel is built from these conditional operations by ignoring the intermediate information $x$, and is the sum of these contributions:

$$T_{\text{corr}} = \sum_x R^{(x)} \circ T_x. \tag{2}$$

The goodness of the scheme in restoring quantum information depends on how $T_{\text{corr}}$ can be brought close to the ideal channel on $\mathcal{H}$, i.e. $\text{id}$.

Whether or not we can find a good correction scheme in principle depends not only on the noisy channel $T$, but also on the set of decompositions (1) obtainable by a measurement on the environment, which usually depends on the particular coupling which induces the noisy evolution $T$. Anyway the assumption of a pure environment overcomes this problem because it guarantees that every decomposition of $T$ into c.p. summands $T_x$ can be realized by a measurement on the environment. Moreover, in order to correct quantum information, the preferable decompositions are the finest ones, those for which no proper refinement is possible. Therefore we shall consider the non refinable decompositions given by the Kraus representations of $T$:

$$T(\rho) = \sum_x t_x \rho t_x^*, \quad \text{where} \quad \sum_x t_x^* t_x = \mathbb{1}. \tag{3}$$

In the following we shall assume that a decomposition (4) is given, that it is associated to the measurement of an observable $X$, and for it we shall consider the problem of perfectly correcting quantum information or, if this is not possible, optimally restoring it.
B. Multi-step channel

We are especially interested in multi-step channels, where the noisy evolution $T$ is given by $n$ Markovian steps:

$$T = T^{(n)} \circ \cdots \circ T^{(1)},$$

where $T^{(k)} : \mathcal{L}(\mathcal{H}) \to \mathcal{L}(\mathcal{H})$ are $n$ possibly different channels. In this case we assume to be able to perform a measurement at each step, so that every $T^{(k)}$ is decomposed into

$$T^{(k)}(\rho) = \sum_{x_k} t^{(k)}_{x_k} \rho t^{(k)}_{x_k}^*, \quad \text{where} \quad \sum_{x_k} t^{(k)}_{x_k} t^{(k)}_{x_k}^* = 1,$$

the channel $T$ is decomposed into

$$T(\rho) = \sum_{x_1,\ldots,x_n} \rho^{(n)}_{x_n} \cdots t^{(1)}_{x_1} \rho t^{(1)}_{x_1}^* \cdots \rho^{(n)}_{x_n}^*,$$

and the probability of observing $(x_1,\ldots,x_n)$ is $P(X_1 = x_1, \ldots, X_n = x_n) = \text{tr} \rho^{(n)}_{x_n} \cdots t^{(1)}_{x_1} \rho t^{(1)}_{x_1}^* \cdots \rho^{(n)}_{x_n}^*$.

We also assume to be able to interfere in the evolution of the system after each step by applying a restoring channel selected according to the whole information gathered so far. For every $k = 1, \ldots, n$, we introduce a family of channels $R^{(x_1,\ldots,x_k)} : \mathcal{L}(\mathcal{H}) \to \mathcal{L}(\mathcal{H})$, where $R^{(x_1,\ldots,x_k)}$ can depend in an arbitrary way on $(x_1,\ldots,x_k)$ and it is applied after the measurement of $X_k$ so that the overall corrected channel turns out to be

$$T_{\text{corr}}(\rho) = \sum_{x_1,\ldots,x_n} R^{(x_1,\ldots,x_n)}(\rho^{(n)}_{x_n} \cdots t^{(1)}_{x_1} \rho t^{(1)}_{x_1}^* \cdots \rho^{(n)}_{x_n}^*).$$

So the classical information obtained by the measurement process on the environment is feedback to modify the evolution of the system $\mathcal{H}$. Notice that this general scheme includes the special cases (compare Fig. 1):

- $R^{(x_1,\ldots,x_k)} = R^{(x_k)}$ for every $k = 1, \ldots, n$, i.e. every restoring channel is selected according only to the last observation $x_k$.
- $R^{(x_1,\ldots,x_k)} = \text{id}$ for every $k = 1, \ldots, n-1$, i.e. the information given by the measurement on the environment is gathered during the evolution, but every correction is deferred after it.

![FIG. 1: Different error correction schemes for multiple channels. (a) represents the most general case. In (b) only the information from the immediately preceding step is used. In (c) only one correction is done at the end.](image-url)

In the following we shall assume that a decomposition (6) is fixed, that it is associated to a measurement process, and, given this, we shall consider the problem of perfect or optimal correction of quantum information.
III. PERFECT CORRECTION OF QUANTUM INFORMATION

Given a channel $T$ with a fixed decomposition (\ref{eq:decomposition1}) or (\ref{eq:decomposition2}), our scheme can perfectly correct quantum information if one can find restoring channels $R$ such that

$$T_{\text{corr}} = \text{id} .$$

A. Single-step channel

Let us improve the criterion given in [8].

**Proposition 1** Let $T : \mathcal{L}(\mathcal{H}) \to \mathcal{L}(\mathcal{H})$ be a channel over a finite dimensional Hilbert space $\mathcal{H}$. Given a Kraus decomposition $T(\rho) = \sum_x t_x \rho t_x^*$, the following are equivalent

(a) there exists a family of channels $R^{(x)} : \mathcal{L}(\mathcal{H}) \to \mathcal{L}(\mathcal{H})$ perfectly restoring quantum information;

(b) $t_x^* t_x = p_x \mathbb{1}$ for all $x$, with $p_x \geq 0$, $\sum_x p_x = 1$;

(b') $t_x = \sqrt{p_x} u_x$ for all $x$, with $u_x \in \mathcal{U}(\mathcal{H})$, $p_x \geq 0$, $\sum_x p_x = 1$;

(b'') $T(\rho) = \sum_x p_x u_x \rho u_x^*$ is a convex combination of unitary channels;

(c) $\mathbb{P}(X = x) = \text{tr} t_x \rho t_x^*$ is independent of the input state $\rho$.

When these conditions hold, then the restoring channels in (a) have to be

$$R^{(x)}(\rho) = u_x^* \rho u_x ,$$

and the probability law of the outcome is

$$\mathbb{P}(X = x) = p_x .$$

**Proof.** (a) $\Rightarrow$ (b). Let $R^{(x)}$ be channels such that $\sum_x R^{(x)}(t_x \rho t_x^*) = \rho$ for every state $\rho$. Then for every $x$, by the “No information without perturbation” Theorem, $R^{(x)}(t_x \rho t_x^*) = p_x \rho$, for some $p_x \geq 0$, $\sum_x p_x = 1$. Therefore $\text{tr} t_x^* t_x \rho = \text{tr} t_x \rho t_x^* = \text{tr} R^{(x)}(t_x \rho t_x^*) = p_x$ for all $\rho$, and so $t_x^* t_x = p_x \mathbb{1}$.

(b) $\Leftrightarrow$ (b') $\Leftrightarrow$ (b''). These conditions are clearly all equivalent because $\text{dim} \mathcal{H} < \infty$.

(b') $\Rightarrow$ (c). $\mathbb{P}(X = x) = \text{tr} t_x \rho t_x^* = \sqrt{p_x} u_x \rho \sqrt{p_x} u_x = p_x$ for every $\rho$, so (b') implies (c), and equation (\ref{eq:proof_equation}), too.

(c) $\Rightarrow$ (a). $\text{tr} t_x^* t_x \rho = \text{tr} t_x \rho t_x^* = \mathbb{P}(X = x)$ which does not depend on $\rho$ and so $t_x^* t_x = \mathbb{P}(X = x) \mathbb{1}$. Then $t_x = \sqrt{\mathbb{P}(X = x)} u_x$, where $u_x$ is unitary because $\text{dim} \mathcal{H} < \infty$, and the channels $R^{(x)}(\rho) = u_x^* \rho u_x$ perfectly restore quantum information.

Now we have to show that conditions (a), (b) and (c) imply (\ref{eq:proof_equation}). Consider a family of channels $R^{(x)}$ restoring quantum information, with $R^{(x)}(\rho) = \sum_j r^{(x)}_j \rho r^{(x)}_j^*$ and $\sum_j r^{(x)}_j r^{(x)}_j^* = \mathbb{1}$. Then

$$\sum_{x,j} r^{(x)}_j t_x \rho t_x^* r^{(x)}_j^* = \rho , \quad \forall \rho ,$$

and using again the “No information without perturbation” Theorem we have

$$r^{(x)}_j t_x = \sqrt{p_{x,j}} e^{i\theta_{x,j}} \mathbb{1} , \quad \forall x,j,$$

for some probability law $p_{x,j}$ and some real function $\theta$. Using (b'), we get

$$r^{(x)}_j = \sqrt{p_{x,j}} e^{i\theta_{x,j}} u_x^* \propto u_x^* \quad \forall j,$$

i.e., fixed $R^{(x)}$, all the Kraus operators $r^{(x)}_j$ have to be proportional to the same unitary operator $u_x^*$, and (\ref{eq:proof_equation}) holds. $\square$
Let us remark that condition (b) gives a simple criterion for the existence of channels $R$ perfectly restoring quantum information based directly on the Kraus operators of $T$. Moreover it clarifies the structure of channels which allow perfect correction with our scheme: the measurement on the environment has to decompose $T$ into a convex combination of unitary channels, so that the overall evolution can be seen as an average of reversible evolutions $\rho \mapsto u_x \rho u_x^*$, which occur randomly with probability $p_x$; the measurement detects the transformation occurred and $R^{(x)}(\rho) = u_x^* \rho u_x$ restores the initial state $\rho$. This means also, by condition (c), that the measurement on the environment is completely uninformative about the system $\mathcal{H}$: the output $x$ can be interpreted as classical information about ”what happened” to the system $\mathcal{H}$, but it gives no information about the input system because it is independent of its state. And the uninformative character of the observation, if associated to a Kraus decomposition of $T$, is sufficient for perfect correction. Moreover, if perfect correction is possible, the restoring channels $R$ have to be unitary.

We shall call *corrigible* every channel $T$ with a decomposition satisfying condition (b).

Just to show how useful can be a suitable measurement on the environment, let us remark that our scheme can perfectly correct quantum information sent through a depolarizing channel, which is known to destroy all quantum information but it gives no information about the input system because it is independent of its state. And the uninformative character of the observation, if associated to a Kraus decomposition of $T$, is sufficient for perfect correction. Moreover, if perfect correction is possible, the restoring channels $R$ have to be unitary.

We shall call *corrigible* every channel $T$ with a decomposition satisfying condition (b).

Let us consider now perfect correction for multi-step channels.

**Proposition 2** Let $T = T^{(n)} \circ \cdots \circ T^{(1)}$, with every $T^{(k)} : \mathcal{L}(\mathcal{H}) \to \mathcal{L}(\mathcal{H})$, be a multi-step channel over a finite dimensional Hilbert space $\mathcal{H}$. Given the Kraus decompositions $T^{(k)}(\rho) = \sum_{x_k} t^{(k)}_{x_k} \rho t^{(k)*}_{x_k}$, T.F.A.E.

(a) there exists a family of channels $R^{(x_1)}$, $R^{(x_1,x_2)}$, ..., $R^{(x_1,\ldots,x_n)}$ perfectly restoring quantum information;

(b) every channel $T^{(k)}(\rho) = \sum_{x_k} t^{(k)}_{x_k} \rho t^{(k)*}_{x_k}$ is corrigible, i.e. for all $x_k$ we have $t^{(k)}_{x_k} = \sqrt{p^{(k)}_{x_k}} u^{(k)}_{x_k}$, with $u^{(k)}_{x_k} \in \mathcal{U}(\mathcal{H})$, $p^{(k)}_{x_k} \geq 0$, $\sum_{x_k} p^{(k)}_{x_k} = 1$;

(c) $P(X_1 = x_1, \ldots, X_n = x_n) = \text{tr} t^{(n)}_{x_n} \cdots t^{(1)}_{x_1} \rho t^{(1)*}_{x_1} \cdots t^{(n)*}_{x_n}$ is independent of the input state $\rho$. When these conditions hold, then for every $k = 1, \ldots, n$ the restoring channels in (a) have to be

$$R^{(x_1,\ldots,x_k)}(\rho) = v^{(x_1,\ldots,x_k)} \rho v^{(x_1,\ldots,x_k)*}, \quad v^{(x_1,\ldots,x_k)} \in \mathcal{U}(\mathcal{H}),$$

with

$$v^{(x_1,\ldots,x_n)} = u^{(1)*}_{x_1} v^{(x_1)} \cdots v^{(x_1,\ldots,x_{n-1})*} u^{(n)*}_{x_n}, \quad (11)$$

and the probability law of the outcome process is always

$$\text{tr} R^{(x_1,\ldots,x_n)} \left( t^{(n)}_{x_n} \cdots t^{(1)}_{x_1} \rho t^{(1)*}_{x_1} \cdots t^{(n)*}_{x_n} \right) = \prod_{k=1}^{n} p^{(k)}_{x_k} \quad (12)$$

Therefore, as long as we are interested in perfect correction of quantum information, the multi-step structure of the channel and the possibility of applying feedback during the evolution do not help: perfect correction is possible if and only if every step is corrigible and, in this case, it is enough to make a unique correction at the end. Indeed only unitary corrections are allowed, otherwise the original information would be corrupted by the feedback itself, and then the first $n - 1$ unitaries $v^{(x_1,\ldots,x_k)}$ can be chosen arbitrarily, also $v^{(x_1,\ldots,x_n)} = \mathbb{1}$, provided that the whole evolution is reversed by the last one (eq. (12)). Again, the channel is corrigible if and only if the measured process is uninformative; moreover its probabilistic law, which cannot be modified by the unitary feedback, is that of a sequence of independent random variables.
The proof of Proposition goes via a more general result about the composition of channels when each channel is decomposed according to a measurement and, not only each channel itself, but also its decomposition, may depend on the previous observations. Therefore, denoted by \( x_k \) the outcomes of the measurement at the \( k^{th} \) step, we want to consider the evolution of a quantum system sent through a sequence of channels on \( \mathcal{L}(\mathcal{H}) \)

\[
T(x_1, \ldots, x_{k-1})(\rho) = \sum_{x_k} t_{x_k}(x_1, \ldots, x_{k-1}) \rho t_{x_k}(x_1, \ldots, x_{k-1})^*, \quad \sum_{x_k} t_{x_k}(x_1, \ldots, x_{k-1})^* t_{x_k}(x_1, \ldots, x_{k-1}) = \mathbb{1},
\]

where for the first step, \( k = 1 \), we denote by “0” the empty string of prior results, so we write

\[
T(0)(\rho) = \sum_{x_1} t_{x_1}(0) \rho t_{x_1}(0)^*, \quad \sum_{x_1} t_{x_1}(0)^* t_{x_1}(0) = \mathbb{1}.
\]

Then the total evolution is

\[
T(\rho) = \sum_{x_1, \ldots, x_n} t_{x_n}(x_1, \ldots, x_{n-1}) \cdot \cdots \cdot t_{x_2} t_{x_1} \mathbb{1} = \sum_{x_1} \rho t_{x_1}(0)^* t_{x_1}(0)\mathbb{1},
\]

and the next Proposition holds.

**Proposition 3** Given a finite dimensional Hilbert space \( \mathcal{H} \), let \( T : \mathcal{L}(\mathcal{H}) \rightarrow \mathcal{L}(\mathcal{H}) \) be a channel resulting from the application of \( n \) decomposed channels \( T(x_1, \ldots, x_{k-1}) \). If \( T = \mathbb{1} \), then

(a) every channel \( T(x_1, \ldots, x_{k-1})(\rho) = \sum_{x_k} t_{x_k}(x_1, \ldots, x_{k-1}) \rho t_{x_k}(x_1, \ldots, x_{k-1})^* \) is corrigible;

(b) a channel \( T(x_1, \ldots, x_{k-1}) \) is unitary if later channels and their decompositions do not depend on the value \( x_k \) observed at the \( k^{th} \) step.

**Proof.** If \( T = \mathbb{1} \), then

\[
t(x_1, \ldots, x_{n-1}) \cdots t(0)_{x_1} = \sqrt{p(x_1, \ldots, x_n)} e^{i\theta(x_1, \ldots, x_n)} \mathbb{1}, \quad \forall x_1, \ldots, x_n,
\]

where \( p \) is the joint probability law of the outcomes, independent of \( \rho \), and \( \theta \) is a real function.

(a) Using the normalization property of Kraus operators, we can immediately show that \( T(0) \) is corrigible:

\[
t_{x_1}^*(0) t_{x_1} = \sum_{x_2, \ldots, x_n} t_{x_2}^* t_{x_2}(0) \cdots t_{x_n}^* t_{x_n}(0) t_{x_1}^* t_{x_1}(0) = \sum_{x_2, \ldots, x_n} p(x_1, \ldots, x_n) \mathbb{1} = p(x_1) \mathbb{1},
\]

where \( p(x_1) \) is the probability of observing \( x_1 \) at the first step. Now, since \( t_{x_1} = \sqrt{p(x_1)} u_{x_1} \), for some unitary \( u_{x_1} \), we can fix \( x_1 \) and find that \( T(x_1) \) is corrigible:

\[
t_{x_2}^* t_{x_2} = \frac{1}{p(x_1)} u_{x_1}^* t_{x_1}^* u_{x_1} = \frac{1}{p(x_1)} \sum_{x_3, \ldots, x_n} t_{x_3}^* \cdots t_{x_n}^* t_{x_1} \cdots t_{x_n} \mathbb{1} = \frac{1}{p(x_1)} \sum_{x_3, \ldots, x_n} p(x_1, \ldots, x_n) \mathbb{1} = p(x_2|x_1) \mathbb{1},
\]

where \( p(x_2|x_1) \) is the probability of observing \( x_2 \) at the second step conditioned upon the observation of \( x_1 \) at the first step. Again we have \( t_{x_2}(x_1) = \sqrt{p(x_2|x_1)} u_{x_2} \) and, repeating the same argument, we find for every \( k \)

\[
t_{x_k}^* t_{x_k} = \sqrt{p(x_k|x_1, \ldots, x_{k-1})} u_{x_k}^* u_{x_k} \mathbb{1} = \sum_{x_{k+1}, \ldots, x_{k-1}} u_{x_{k+1}} u_{x_k} \mathbb{1} \in \mathcal{U}(\mathcal{H}),
\]

where \( p(x_k|x_1, \ldots, x_{k-1}) \) is the probability of observing \( x_k \) at the \( k^{th} \) step conditioned upon the observation of \( (x_1, \ldots, x_{k-1}) \) during the previous steps. Equation gives the polar decomposition of \( t_{x_k}^* t_{x_k} \), which in this case is unique.

(b) Combining equations and we get

\[
t_{x_k}^* t_{x_k} = \sqrt{p(x_k|x_1, \ldots, x_{k-1})} e^{i\theta(x_1, \ldots, x_n)} u_{x_{k+1}}^* u_{x_k} \mathbb{1} = \sum_{x_{k+1}, \ldots, x_{k-1}} u_{x_{k+1}}^* u_{x_k} \mathbb{1} u_{x_{k-1}}^* u_{x_k} \mathbb{1}^*.
\]
where, because of the uniqueness of the polar decomposition of $t_{x_k}^{(x_1,\ldots,x_{k-1})}$,
\[ e^{i\theta(x_1,\ldots,x_n)} u_{x_{k+1}} (x_1,\ldots,x_k)^* \cdots u_{x_n} (x_1,\ldots,x_{n-1})^* u_{x_1} (0)^* \cdots u_{x_{k-1}} (x_1,\ldots,x_{k-2})^* = u_{x_k} (x_1,\ldots,x_{k-1})^* , \]
which therefore has to be independent of $x_{k+1},\ldots,x_n$. If moreover $(x_1,\ldots,x_{k-1})$ is such that for all $m > k$ the operators $t_{x_m}^{(x_1,\ldots,x_{m-1})}$ do not depend on $x_k$, then the same is true for the unitary operator $u_{x_{k+1}} (x_1,\ldots,x_{k-1})^* \cdots u_{x_n} (x_1,\ldots,x_{n-1})^* u_{x_1} (0)^* \cdots u_{x_{k-1}} (x_1,\ldots,x_{k-2})^*$ and so the Kraus operators $t_{x_k}^{(x_1,\ldots,x_{k-1})}$ are all proportional to a same unitary operator $u_{x_1} (x_1,\ldots,x_{k-1})^*$ and $T^{(x_1,\ldots,x_{k-1})} (\rho) = u_{x_1} (x_1,\ldots,x_{k-1})^* \rho u_{x_1} (x_1,\ldots,x_{k-1})$.

\begin{proof}[Proof of Proposition 3]
(a) $\Rightarrow$ (b). Let $R^{(x_1,\ldots,x_{k-1})} (\rho) = \sum_j t_j^{(x_1,\ldots,x_{k-1})} \rho t_j^{(x_1,\ldots,x_{k-1})*}$, with $\sum_j t_j^{(x_1,\ldots,x_{k-1})} t_j^{(x_1,\ldots,x_{k-1})*} = \mathbb{1}$. If $\sum_j t_j^{(x_1,\ldots,x_{n})} r_j^{(x_1,\ldots,x_{n})} = \mathbb{1}$, then this decomposition of the ideal channel is associated to a probability measure $p(x_1,\ldots,x_n)$ and Proposition 3 directly implies $t_j^{(x_1,\ldots,x_{n})} = \rho$ for every $\rho$ and $p(x_1,\ldots,x_n)$ is unitary and
\[ p(x_1,\ldots,x_n) = p(x_1,\ldots,x_{n-1}) u_{x_k} (x_1,\ldots,x_{n-1}) \]
and $x_{n-1} = x_n$ because $t_j^{(x_1,\ldots,x_{n})}$ does not depend on $(x_1,\ldots,x_{n-1})$.

(b) $\Rightarrow$ (c). If $t_j^{(x_1,\ldots,x_{n})} = \sqrt{p_j^{(x_1,\ldots,x_{n})}} u_{x_k} (x_1,\ldots,x_{n})$, with $u_{x_k} (x_1,\ldots,x_{n}) \in U(\mathcal{H})$, $p_j^{(x_1,\ldots,x_{n})} \geq 0$, $\sum_j p_j^{(x_1,\ldots,x_{n})} = 1$, then for every $\rho$
\[ P(X_1 = x_1,\ldots,X_n = x_n) = \text{tr} t_j^{(x_1,\ldots,x_{n})} \rho t_j^{(x_1,\ldots,x_{n})*} = \prod_{k=1}^{n} p_k^{(x_1,\ldots,x_{n})} . \]

(c) $\Rightarrow$ (a). $\text{tr} t_j^{(x_1,\ldots,x_{n})} t_j^{(x_1,\ldots,x_{n})*} = \mathbb{1}$, $\text{tr} t_j^{(x_1,\ldots,x_{n})} \rho t_j^{(x_1,\ldots,x_{n})*} = P(X_1 = x_1,\ldots,X_n = x_n)$ which does not depend on $\rho$ and so $t_j^{(x_1,\ldots,x_{n})} t_j^{(x_1,\ldots,x_{n})*} = \mathbb{1}$. Then, with the same argument used in the proof of property (a) of Proposition 3
\[ t_j^{(x_1,\ldots,x_{n-1})} = \sqrt{P(X_{n} = x_1,\ldots,X_n = x_n)} u_{x_{n-1}} (x_1,\ldots,x_{n-2}), \]
where $u_{x_{n-1}} (x_1,\ldots,x_{n-2})$ is unitary, and where $P(X_{n} = x_1,\ldots,X_n = x_n)$ and $u_{x_{n-1}} (x_1,\ldots,x_{n-2}) = u_{x_{n-1}} (x_1,\ldots,x_{n-2})$ because $t_j^{(x_1,\ldots,x_{n-1})}$ does not depend on $(x_1,\ldots,x_{n-1})$. Then the channels $R^{(x_1,\ldots,x_{n})} (\rho) = u_{x_{n-1}} (x_1,\ldots,x_{n-2})^* \rho u_{x_{n-1}} (x_1,\ldots,x_{n-2})$ perfectly restore quantum information.

When (a), (b) and (c) hold, all the restoring channels $R$ in (a) satisfy (10) by Proposition 3 and of course for every choice of $v(x_1,\ldots,x_k)$, $k = 1,\ldots,k-1$, the channel $R^{(x_1,\ldots,x_{n})}$ defined by (11) can perfectly restore quantum information. Finally equation (12) directly follows from condition (b) and equation (10).

\end{proof}

IV. OPTIMAL RECOVERY OF QUANTUM INFORMATION

When perfect correction of quantum information is not possible, we would like the restoring channels $R$ which bring the corrected channel $T_{\text{corr}}$ as close as possible to id, in some sense. We look for channels $R$ which maximize the channel fidelity of the corrected channel, $F(T_{\text{corr}})$. For a channel $T : \mathcal{L}(\mathcal{H}) \rightarrow \mathcal{L}(\mathcal{H})$, $T(\rho) = \sum x t_x \rho t_x^*$, $\dim \mathcal{H} = N$, denoted by $\Omega$ a maximally entangled unit vector in $\mathcal{H} \otimes \mathcal{H}$, the channel fidelity
\[ F(T) = \langle \Omega, T \otimes \text{id}(|\Omega\rangle \langle \Omega|) \Omega \rangle = \frac{1}{N^2} \sum_x |\text{tr} t_x|^2 \]
measures how well $T$ preserves quantum information, reaching 1 if and only if $T = \text{id}$.
A. Single-step channel

Let us recall what was found in [9] for the single-step case. Given $T$, chosen a Kraus decomposition \((8)\) and the restoring channels \(R^{(x)}\),

\[
R^{(x)}(\rho) = \sum_{j} r_{j}^{(x)} \rho r_{j}^{(x)*} \quad , \quad \sum_{j} r_{j}^{(x)*} r_{j}^{(x)} = 1 ,
\]

we are interested in

\[
\mathcal{F}(T_{\text{corr}}) = \frac{1}{N^2} \sum_{x,j} |\text{tr} r_{j}^{(x)} t_{x}|^2 , \tag{17}
\]

and we want to maximize it with respect to all possible families \(\{R^{(x)}\}\).

**Proposition 4** Let $T : \mathcal{L}(\mathcal{H}) \to \mathcal{L}(\mathcal{H})$ be a channel over a finite dimensional Hilbert space $\mathcal{H}$. Fixed a Kraus decomposition $T(\rho) = \sum_{x} t_{x} \rho t_{x}^*$, for every family of channels $R^{(x)} : \mathcal{L}(\mathcal{H}) \to \mathcal{L}(\mathcal{H})$ let $T_{\text{corr}}$ be the corresponding overall corrected channel \((2)\). Then

\[
\mathcal{F}(T_{\text{corr}}) \leq \frac{1}{N^2} \sum_{x} \left( \text{tr} |t_{x}| \right)^2 . \tag{18}
\]

Moreover equality holds if and only if

\[
T_{\text{corr}}(\rho) = \sum_{x} |t_{x}| \rho |t_{x}| , \tag{19}
\]

and it can always be attained choosing

\[
R^{(x)}(\rho) = u_{x}^* \rho u_{x} , \tag{20}
\]

where $u_{x}$ is a unitary operator in the polar decomposition $t_{x} = u_{x} |t_{x}|$.

**Proof.** Inequality \((18)\) follows from \((17)\) because the Cauchy-Schwarz inequality for the Hilbert-Schmidt inner product gives

\[
\sum_{j} |\text{tr} r_{j}^{(x)} t_{x}|^2 = \sum_{j} \left| \text{tr} (r_{j}^{(x)} u_{x} |t_{x}|^{1/2} |t_{x}|^{1/2}) \right|^2 \leq \sum_{j} \left( |t_{x}|^{1/2} u_{x}^* r_{j}^{(x)*} r_{j}^{(x)} u_{x} |t_{x}|^{1/2} \right) \text{tr} |t_{x}| = \left( \text{tr} |t_{x}| \right)^2 . \tag{21}
\]

Equality holds in \((18)\) if and only if equality holds in \((21)\) for every $x$, which occurs if and only if $r_{j}^{(x)} u_{x} |t_{x}|^{1/2} = \lambda_{xj} |t_{x}|^{1/2}$, $\lambda_{xj} \in \mathbb{C}$, for every $x$ and $j$. Then $r_{j}^{(x)} t_{x} = \lambda_{xj} |t_{x}|$ and \((19)\) holds. The opposite implication is obvious.

Finally, if $R^{(x)}$ are chosen according to \((20)\), then $T_{\text{corr}}$ is given by \((19)\) and equality holds in \((18)\). \(\square\)

The structure of the optimal restoring channels \((20)\) obtained by maximizing $\mathcal{F}(T_{\text{corr}})$, is just what one could expect. When a measurement on the environment has given the result $x$, we deal with a subensemble of systems undergone the state transformation $\rho \mapsto t_{x} \rho t_{x}^* = u_{x} |t_{x}| \rho |t_{x}| u_{x}^*$, which can be seen as a composition of $\rho \mapsto |t_{x}| \rho |t_{x}|$ followed by $\rho \mapsto u_{x} \rho u_{x}^*$. Unless we are in the trivial case $|t_{x}| \propto \mathds{1}$, only the second transformation is physically reversible, and this is just what the channels \((20)\) do. Therefore $\mathcal{F}(T_{\text{corr}})$ can be maximized considering only unitary feedback, even if sometimes non unitary feedback could work as well (for example, every time the polar decomposition of $t_{x}$ is not unique).

B. Multi-step channel

Given a multi-step channel $T$, decomposed according to \((6)\), we allow corrections also before the evolution stops and so we want to maximize the channel fidelity of $T_{\text{corr}}$ over all possible families $R^{(x_{1})}$, $R^{(x_{1},x_{2})}$, \ldots, $R^{(x_{1},\ldots,x_{n})}$ in \((7)\). We are interested in the optimal feedback, of course, and we want to compare the maximum attainable fidelity with:
Then, for every family of channels \( R \) the Kraus decompositions
\[
\text{Let the Kraus decompositions}
\]
\[
\text{Quite surprisingly, these two strategies are equivalent, and optimal, in the qubit case (dim } H \geq 2\text{), but in the general case (dim } H \geq 3\text{) there is no relationship between them, and neither of them gives the optimal correction.}
\]

1. Qubit multi-step channels

**Proposition 5** Let \( \dim H = 2 \) and \( T = T^{(n)} \circ \cdots \circ T^{(1)} \) be a multi-step channel, with every \( T^{(k)} : \mathcal{L}(H) \to \mathcal{L}(H) \). Fixed the Kraus decompositions \( T^{(k)}(\rho) = \sum x_k \rho \) for every family of channels \( R^{(x_1)}, R^{(x_1,x_2)}, \ldots, R^{(x_1,\ldots,x_n)} \), let \( T_{\text{corr}} \) be the corresponding overall corrected channel. Then
\[
\mathcal{F}(T_{\text{corr}}) \leq \frac{1}{4} \sum_{x_1,\ldots,x_n} \left( \text{tr} \left| t_{x_n}^{(1)} \cdots t_{x_1}^{(1)} \right| \right)^2.
\]
Moreover equality can always be attained choosing
\[
R^{(x_1,\ldots,x_k)}(\rho) = u^{(x_1,\ldots,x_k)}(x_1,\ldots,x_k)^* \rho u^{(x_1,\ldots,x_k)}(x_1,\ldots,x_k), \quad v^{(x_1,\ldots,x_k)}(x_1,\ldots,x_k)^* \in \mathcal{U}(H), \quad \forall k = 1, \ldots, n.
\]

**Proof.** The key property in a 2-dimensional Hilbert space is that for every operator \( A \)
\[
(\text{tr} \left| A \right|^2 = \text{tr}(\left| A \right|) + 2 \det A), \quad \text{where } \det A = |\det A| \leq \frac{1}{2} \text{tr}(\left| A \right|^2).
\]
Then, for every family of channels \( R^{(x_1,\ldots,x_{k-1})}(\rho) = \sum_{x_k} r_{x_k}^{(x_1,\ldots,x_{k-1})} \rho r_{x_k}^{(x_1,\ldots,x_{k-1})}^* \), \( \sum_{x_k} r_{x_k}^{(x_1,\ldots,x_{k-1})} r_{x_k}^{(x_1,\ldots,x_{k-1})} = I \),
\[
\mathcal{F}(T_{\text{corr}}) = \frac{1}{4} \sum_{x_1,\ldots,x_n} \left| \text{tr} r_{j_n}^{(x_1,\ldots,x_n)} t_{x_n}^{(n)} \cdots r_{j_1}^{(x_1,\ldots,x_1)} t_{x_1}^{(1)} \right|^2 \leq \frac{1}{4} \sum_{x_1,\ldots,x_n} \left( \text{tr} \left| t_{x_n}^{(n)} r_{j_n}^{(x_1,\ldots,x_n-1)} \cdots r_{j_1}^{(x_1,\ldots,x_1)} t_{x_1}^{(1)} \right| \right)^2
\]
\[
= \frac{1}{2} \left( \sum_{x_1,\ldots,x_n} \left| \text{det} t_{x_n}^{(n)} \cdots t_{x_1}^{(1)} \right| \cdot \left| \text{det} r_{j_n}^{(x_1,\ldots,x_n-1)} \cdots r_{j_1}^{(x_1,\ldots,x_1)} \right| \right) \leq \frac{1}{2} + \frac{1}{2} \sum_{x_1,\ldots,x_n} \left| \text{det} t_{x_n}^{(n)} \cdots t_{x_1}^{(1)} \right|
\]
\[
= \frac{1}{4} \sum_{x_1,\ldots,x_n} \left( \text{tr} t_{x_n}^{(n)} \cdots t_{x_1}^{(1)} \right)^2.
\]

**Proof of Proposition 4**
\[
\mathcal{F}(T_{\text{corr}}) = \frac{1}{N^2} \sum_{x_1,\ldots,x_n} \left( \text{tr} \left| t_{x_n}^{(n)} \cdots t_{x_1}^{(1)} \right| \right)^2,
\]
where \( T_{\text{corr}} \) denotes the corrected channel
\[
T_{\text{corr}}(\rho) = \left| t_{x_n}^{(n)} \cdots t_{x_1}^{(1)} \right| \rho \left| t_{x_n}^{(n)} \cdots t_{x_1}^{(1)} \right|.
\]
Analogously for every family of unitary channels $R^{(x_1,\ldots,x_k)}(\rho) = u(x_1,\ldots,x_k)\rho u(x_1,\ldots,x_k)^*$, with $u(x_1,\ldots,x_n) = u(x_1,\ldots,x_n)^*$,

$$
F(T_{\text{corr}}) = \frac{1}{4} \sum_{x_1,\ldots,x_n} \left( \text{tr} \left[ f_{x_n}^{(n)} u(x_1,\ldots,x_{n-1}) \ldots u(x_1) t_{x_1}^{(1)} \right] \right)^2 = \frac{1}{2} + \frac{1}{2} \sum_{x_1,\ldots,x_n} \left| \det f_{x_n}^{(n)} u(x_1,\ldots,x_{n-1}) \ldots u(x_1) t_{x_1}^{(1)} \right|
$$

$$
= \frac{1}{2} + \frac{1}{2} \sum_{x_1,\ldots,x_n} \left| \det f_{x_n}^{(n)} \ldots t_{x_1}^{(1)} \right| = \frac{1}{4} \sum_{x_1,\ldots,x_n} \left( \text{tr} \left[ f_{x_n}^{(n)} \ldots t_{x_1}^{(1)} \right] \right)^2.
$$

\[ \square \]

2. Higher dimensional two-step channels

When $\dim \mathcal{H} \geq 3$ there is no general relationship between the two fidelities [22] and [23]. Consider on $\mathbb{C}^3$ the multi-step channels $T = T^{(2)} \circ T^{(1)}$ and $S = S^{(2)} \circ S^{(1)}$, where

$$
T^{(1)}(\rho) = T^{(2)}(\rho) = \sum_{x=1}^{2} t_x \rho t_x^* , \quad S^{(1)}(\rho) = S^{(2)}(\rho) = \sum_{x=1}^{2} s_x \rho s_x^* ,
$$

$$
|t_1|^2 = |s_1|^2 = \begin{pmatrix} 1/6 & 0 & 0 \\ 0 & 1/3 & 0 \\ 0 & 0 & 1/2 \end{pmatrix} , \quad |t_2|^2 = |s_2|^2 = \begin{pmatrix} 5/6 & 0 & 0 \\ 0 & 2/3 & 0 \\ 0 & 0 & 1/2 \end{pmatrix} ,
$$

$$
t_1 = u|t_1| , \quad t_2 = |t_2| , \quad s_1 = v|s_1| , \quad s_1 = u|s_1| ,
$$

where

$$
u = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} , \quad \text{and} \quad v = \frac{1}{\sqrt{3}} \begin{pmatrix} e^{2i\pi/3} & e^{-2i\pi/3} & 1 \\ e^{-2i\pi/3} & e^{2i\pi/3} & 1 \\ 1 & 1 & 1 \end{pmatrix} .
$$

Then since the absolute values of the Kraus operators coincide, the single-step corrected versions of $T$ and $S$ are the same. Moreover, since these absolute values commute, the iterated absolute values factorize, i.e.,

$$
\left| f_{x_n}^{(n)} \ldots f_{x_2}^{(2)} f_{x_1}^{(1)} \right| = \left| f_{x_n}^{(n)} \right| \ldots \left| f_{x_2}^{(2)} \right| \left| f_{x_1}^{(1)} \right|
$$

(27)

Hence the greedy strategy of correcting for maximal fidelity at every step, using all available information, gives the same result for these channels as the product of the single-step corrected channels. In particular, $S$ and $T$ are equivalent in this respect, and $F(T_{\text{corr}}) = F(S_{\text{corr}})$ (see last line in the table below).

On the other hand, we can leave the system undisturbed, and only make an optimal correction at the end, again using all available information. Finally, we may optimize fidelity over all correction schemes. Numerically this achieved by an iteration, developed in [10], which efficiently determines the maximum of a general positive linear functional on channels. In the case at hand this is the overall channel fidelity as a function of the correcting channels $R$. Since we can correct the unitaries $u$ and $v$ immediately in every step, it is clear that the channels $S$ and $T$ once again give the same corrected fidelities. The results are summarized in the following table:

<table>
<thead>
<tr>
<th>Channel fidelities</th>
<th>$T$</th>
<th>$S$</th>
</tr>
</thead>
<tbody>
<tr>
<td>optimal correction</td>
<td>0.9584</td>
<td>0.9584</td>
</tr>
<tr>
<td>final correction only</td>
<td>0.9556</td>
<td>0.9576</td>
</tr>
<tr>
<td>optimal correction at each step</td>
<td>0.9570</td>
<td>0.9570</td>
</tr>
</tbody>
</table>

Hence, in contrast to the case of perfect corrigibility, it may help to perform corrections on the way, rather than a single correction at the end (column $T$). Perhaps surprisingly, the optimal correction at the intermediate steps requires some foresight, and depends on what is to follow: otherwise the strategy of correcting for highest fidelity using all available information, which is clearly optimal in the last step, would also have to be optimal in the intermediate steps (compare first and last line). Even leaving out the intermediate correction altogether may be better (column $S$).
3. Higher dimensional many-step channels

We noted that in the previous example the correction scheme for $T''_{corr}$ is equivalent to multiplying the one-step corrected channels. That is, whether this correction step may use all available information or just the information from the last step, leads to the same corrected channel. We showed this by noting that the absolute values of all Kraus operators involved commute. This will be true in any dimension if there are only two Kraus operators, as in the example. Here we just note that this equality is not a general fact. In fact using random channels one quickly finds examples (3 Hilbert space dimensions, 3 Kraus operators, and 4 time steps), in which using all information or just information from the last step give different results. Surprisingly, once again the comparison may be either way: sometimes using only one-step information is better than using all information. Of course, this is only possible because the greedy strategy is not optimal in the first place.

V. OUTLOOK

We would like to spend some words about the quantum error-correction in continuous time. Our aim would be to generalize this correction scheme for quantum information corrupted by a noisy Markovian evolution assigned by a Quantum Dynamical Semigroup. The present analysis for a multi-step channel $T = (T^{(1)})^n$ would provide the intervalwise treatment, but it is not easy to take the limit to continuous time. The well established theory of continuous measurements gives the possible decompositions (unravelings) of the channel according to the observed trajectories, but a continuous time formulation of general non-Hamiltonian feedback is missing. There is no general description of the evolution conditioned on the observed process if a feedback depending on the whole measurement record is added. And also if the feedback is supposed to depend only on the present observation, the measured current, still there is no general description for non-Hamiltonian feedback. A theory exists only for Hamiltonian feedback simply proportional to the measured currents \cite{11}. Anyway a preliminary study of perfect correction in this framework leads to the same conclusions of Proposition \ref{prop:perfect}. perfect correction is possible if and only if the measured process is uninformative and in this case a unique correction at the end suffices. It is also possible to characterize the Linblad generator of semigroups allowing such perfect correction and, as pointed out by Luc Bouten, these semigroups are just the ones admitting an essentially commutative dilation \cite{12}.

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\begin{thebibliography}{11}
\end{thebibliography}