NMR detection with an atomic magnetometer

I. M. Savukov and M. V. Romalis

Department of Physics, Princeton University, Princeton, New Jersey 08544

(Dated: November 17, 2004)

PACS numbers: 33.25.+k,82.56.-b,83.85.Fg, 87.61.-c

We demonstrate detection of NMR signals using a non-cryogenic atomic magnetometer and describe several novel applications of this technique. A water free induction decay (FID) signal in a 0.5 μT field is detected using a spin-exchange-relaxation-free K magnetometer and the possibility of using a multi-channel magnetometer for 3-D MRI requiring only a single FID signal is described. We also demonstrate detection of less than $10^{13}$ $^{129}$Xe atoms whose NMR signal is enhanced by a factor of 540 due to Fermi-contact interaction with K atoms. This technique allows detection of less than $10^{9}$ $^{129}$Xe spins in a flowing system suitable for remote NMR applications.

In this Letter we demonstrate NMR detection using an atomic magnetometer and describe several novel applications based on unique properties of atomic magnetometers. Recent advances in atomic magnetometry [1], in particular demonstration of a spin-exchange-relaxation-free (SERF) magnetometer [2] have allowed alkali-metal magnetometers to exceed the sensitivity of low-temperature SQUID detectors [7]. In addition to high sensitivity, atomic magnetometers also allow low-cost multi-channel measurements with a high spatial resolution and do not require cryogenic cooling. Here we demonstrate first detection of NMR free induction decay (FID) signals from a thermally polarized water sample with an atomic magnetometer. Previous measurements using atomic magnetometers have only detected DC magnetization of hyperpolarized gases [3,4,10]. We also describe a novel MRI method that allows reconstruction of a 3-D image from a single FID signal in the presence of a constant magnetic field gradient by relying on multi-channel magnetic field measurements. In a separate experiment, we investigate a unique method for enhancing NMR sensitivity by allowing the nuclei to occupy the same volume as the active atoms of the magnetometer. In addition to reducing the distance between the nuclear spins and the atoms measuring the magnetic field, this method can also enhance the NMR signal due to Fermi-contact interaction between the alkali-metal valence electron and the nuclei spins [11,12]. With this technique we detect a signal from $2 \times 10^{13}$ $^{129}$Xe atoms with a signal-to-noise ratio of 10 in a single shot with a bandwidth of 10 Hz. Straight-forward optimization of this technique can achieve sensitivity of about $10^9$ $^{129}$Xe spins without averaging. For comparison, detection of NMR using traditional pick-up coils is limited at a level $3 \times 10^{12}$ spins even with substantial averaging [13,14].

Detection of optically pumped Ga spins using magnetic resonance force microscopy has achieved sensitivity of $7 \times 10^8$ spins [15]. Hyperpolarized $^{129}$Xe is widely used for MRI [18], as a biosensor [19,20], and for remote NMR detection [21]. However, measurements with human subjects are restricted due to anesthetic properties of xenon in high concentrations. Combining the techniques of remote NMR encoding with a flow-through spin-detection system using an atomic magnetometer would allow one to use much smaller $^{129}$Xe concentrations.

Atomic magnetometers operate by measuring the precession of electron spins in a magnetic field, usually using an alkali metal vapor. The sensitivity of the magnetometer is determined by the number of atoms in the active volume and their transverse spin relaxation time. Atomic collisions usually limit the transverse spin relaxation time, particularly at high alkali-metal density. As was first shown in [22], the dominant relaxation mechanism due to spin-exchange collisions can be eliminated by operating in a very low magnetic field with a high alkali-metal density. Such spin-exchange relaxation-free (SERF) magnetometer has achieved magnetic field sensitivity of 0.5 fT/Hz$^{1/2}$ using an active volume of only 0.3 cm$^3$ [7]. The small active volume is important for obtaining a short effective distance between the magnetometer and the NMR sample. The magnetometer consists of a glass cell containing K vapor and a high pressure buffer gas to slow the diffusion of atoms across the
Optical pumping laser spin-polarizes the atoms with a noise floor of $2 \times 10^{-14}$ T/Hz$^{1/2}$. An optical pumping laser spin-polarizes the atoms while an orthogonal probe laser detects their precession in the magnetic field. Because of slow K diffusion, a single probe laser can be used to simultaneously measure the magnetic field in multiple points by imaging it on a multi-channel photo-detector. In this arrangement most elements of the magnetometer are common, allowing one to construct an inexpensive system with hundreds or even thousands of channels. One challenge for using an atomic magnetometer for NMR detection is the need to match the resonance frequencies of the electron and nuclear spins whose gyromagnetic ratios are different by a factor of 100-1000. One possibility is to use a set of coils to create different magnetic fields in the NMR sample and the magnetometer cell as was recently demonstrated in [10]. If the nuclear spins are directly interacting with the atomic magnetometer, one can use these interactions to match the two resonance frequencies [23].

The experimental arrangement for detection of water NMR is shown in Fig. 1b). To obtain independent control of the magnetic fields experienced by the protons and the K magnetometer, the water sample is contained in a solenoid. The magnetic flux produced by the solenoid is returned through the magnetic shields, so it’s external field is a factor of 1000 smaller than the internal field. In previous experiments designed to detect NMR with SQUIDs in a very low magnetic field the thermal polarization was increased by briefly sending a large current through a solenoid [1]. In our system the inner-most magnetic shield is made from a soft METGLAS material which easily magnetizes and creates a large field drift. To avoid this problem we used a flow system where the water was polarized by a permanent magnet outside of the shields. The K cell is heated to 180°C in a double-wall oven made from thin G7 sheets. Hot air flows between the two walls of the oven but does not cross the path of the laser beams to avoid optical noise. Microporous thermal insulation is used to insulate the oven, keeping the total distance between the K cell and the room-temperature surface to about 1 cm. Magnetometer coils inside the shields are used to set to zero the magnetic field at the K cell in order to achieve the maximum sensitivity of the SERF magnetometer. One coil is also used to generate a $\pi/2$ pulse to tip the proton spins. The transverse relaxation time of K spins is much faster than those of protons in water, so the transient signal of the magnetometer decays quickly relative to water FID. A single-shot water NMR signal is shown in Fig. 1b) and its FID is shown in Fig. 1c) The Fourier transform reveals a single peak at a frequency of 20 Hz with a S/N ratio of greater than 10. The S/N ratio is comparable or better than those obtained with SQUID magnetometers [1].

In addition to avoiding the need for cryogenics, NMR detection using atomic magnetometers also allows simple construction of multi-channel systems. The electronics needed for each channel is much simpler than for an RF pick-up coil or a SQUID detector and there is no inductive coupling between different channels. This opens the possibility of using spatial information obtained from a large number of channels to implement more efficient MRI techniques. Parallel MRI techniques using phased RF arrays have been used to reduce imaging time by omitting some phase-encoding steps in a traditional MRI technique.
sequence \[24\]. It is well known that even a complete knowledge of the magnetic field outside of a closed volume is not sufficient to reconstruct the distribution of an arbitrary static current or magnetization inside the volume. The situation is different in NMR, where the magnetization starts out parallel to the magnetic field and always has a non-zero net magnetic moment, eliminating possible silent sources. However, the information obtained from the external fields is still insufficient for imaging. For example, uniform spherical magnetization distributions of different sizes can produce the same magnetic dipole field. As a result, inversion procedures using a 3-D grid of discrete dipoles \[27, 28, 29\] are not unique. It can be shown that at least one magnetic field gradient has to be applied to solve the inverse problem uniquely, as illustrated in Fig. 2. The magnetic field gradient separates different slices of the sample in frequency and within each slice an image can be uniquely obtained from the array of sensors outside. This problem is analogous to the determination of a 2-dimensional current density or susceptibility distribution using magnetic field measurements \[27, 28, 29\]. The inverse problem can be solved exactly, however the spatial resolution drops exponentially with the distance between the magnetometer plane and the imaging slice. Thus, this imaging method would sacrifice some spatial resolution to obtain very fast imaging speed. With a large array of sensitive detectors it should be possible to obtain a complete 3-D image from a single FID in less than 1 msec, enabling new MRI applications of time-varying processes.

Another unique aspect of alkali-metal magnetometers is their ability to interact directly with the nuclei of interest. This interaction is particularly well understood in the case of noble gases and has been used to produce hyperpolarized gases for a wide range of applications \[30\]. The attraction of the alkali metal valence electron to the noble gas nucleus results in an enhancement of the dipole moment. A small concentration of \(^{129}\)Xe enriched to 80\% is added to the magnetometer cell. \(^{129}\)Xe is polarized parallel to the pump beam by spin-exchange collisions with K atoms. To tip the \(^{129}\)Xe spins, a static transverse magnetic field \(B_x\) of 1 mG is turned on for about 200 msec. The field causes K atoms to depolarize and \(^{129}\)Xe atoms to precess by \(\pi/2\). After the field is turned off, K atoms are quickly repolarized and \(^{129}\)Xe precess around the field \(B_x\). The transverse oscillating magnetization generates the field \(B_K\) which is detected by the K magnetometer.

Fig. 3a) shows the FID signal of \(^{129}\)Xe nuclear precession. The data are well described by an exponentially-decaying oscillation after subtracting a slowly-varying background. The transverse spin relaxation time \(T_2^*\) is determined by the inhomogeneities of the K polarization

\[
B_K = \frac{8\pi}{3}\kappa_0 M,
\]

where \(M\) is the nuclear magnetization \[12\]. Hence, the classical dipolar field produced by nuclear spins is increased by a factor of \(\kappa_0\) which ranges from 6 for \(^3\)He \[13\] to about 600 for \(^{129}\)Xe \[14\]. The magnetization of K atoms \(M_K\) also creates an effective field experienced by the noble gas,

\[
B_{Xe} = \frac{8\pi}{3}\kappa_0 M_K = \frac{8\pi}{3}\kappa_0 g_\mu B Xe [K]
\]

In a high-density alkali-metal vapor this field causes \(^{129}\)Xe atoms to precess at a frequency of a few Hz while K atoms remain in a nearly zero field.

In Fig. 3a) we illustrate the principle of the experiment. A small concentration of \(^{129}\)Xe atoms (740 \(\mu\)Torr of \(^{129}\)Xe enriched to 80\%) is added to the magnetometer...
across cell. We found that applying a \(B_z\) field of 10–100 \(\mu\)G and increasing the optical pumping rate increases the \(^{129}\)Xe signal due to a more uniform K polarization.

By measuring the equilibrium \(^{129}\)Xe signal from a train of \(\pi/2\) pulses as a function of the separation time between the pulses we determined \(T_1\) relaxation of \(^{129}\)Xe for different temperatures corresponding to different densities of K. Measurements of the effects of K-K spin-exchange collisions \([6,31]\) on the K Larmor resonance frequency and linewidth were used to determine the density and the polarization of K atoms. For example at 180°C the potassium polarization is \(P_K = 85\%\) and the density is \([K] = 2 \times 10^{13} \text{ cm}^{-3}\), about 3 times smaller than saturated vapor pressure. The dependence of \(1/T_1\) on the density of K is shown in Fig. 3 from which we determine the K-\(^{129}\)Xe spin-exchange cross-section, \(\sigma_{SE} = 6.3 \times 10^{-21} \text{ cm}^2\), which compares well with a theoretical estimate \(\sigma_{SE} = 8 \times 10^{-21} \text{ cm}^2\). We also measured the Xe precession frequency as a function of K density, as shown in Fig. 3). In accordance with Eq. 2 the frequency is proportional to the density of K atoms. From the slope of the fit we determine \(K_\sigma = 540\), in good agreement with the theoretical estimate \(K_\sigma = 660\). The equilibrium \(^{129}\)Xe polarization is given by \(P_K = \frac{P_{SE}[\text{K}]}{(T_{1\text{wall}}^{-1} + \sigma_{SE}[\text{K}])}\) and is equal to approximately 35% at 180°C. For the \(^{129}\)Xe density of \(2 \times 10^{13} \text{ cm}^{-3}\) the effective field seen by K atoms \(B_K = 12 \text{ pT}\), in excellent agreement with the measured signal of 11.4 pT after correcting for the signal decay during the dead time of the magnetometer. The \(S/N\) is approximately equal to 10 in a bandwidth of 10 Hz and the effective measurement volume determined by the intersection of the pump and probe beams was about 1 cm³. Thus, the magnetometer sensitivity is about \(7 \times 10^{11}/\text{Hz}^{1/2}\) \(^{129}\)Xe atoms. With additional optimization and better magnetic field shielding it should be possible to achieve magnetic field sensitivity of better than 1 fT/Hz\(^{1/2}\), giving sensitivity to about \(10^9\) \(^{129}\)Xe spins in a single shot. This detection technique can be easily adapted for detection of low \(^{129}\)Xe concentration in a flow-though system \([32]\) as long as \(^{129}\)Xe spends much less than \(T_1 \sim 20\) sec in the cell. \(^{129}\)Xe can be initially polarized by optical pumping, flow through the sample where the information is encoded in the longitudinal polarization and then flow through the K cell for detection. This work was supported by NSF, Packard Foundation and Princeton University.