Bayesian model selection and isocurvature perturbations

María Beltrán,1,2 Juan García-Bellido,1 Julien Lesgourgues,3 Andrew R. Liddle,2 and Anže Slosar4

1Departamento de Física Teórica C-XI, Universidad Autónoma de Madrid, Cantoblanco, 28049 Madrid, Spain
2Astronomy Centre, University of Sussex, Brighton BN1 9QH, United Kingdom
3LAPTH, F-74941 Annecy-le-Vieux Cedex, France and INFN Padova, Via Marzolo 8, I-35131 Padova, Italy
4Faculty of Mathematics and Physics, University of Ljubljana, Slovenia

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Present cosmological data are well explained assuming purely adiabatic perturbations, but an admixture of isocurvature perturbations is also permitted. We use a Bayesian framework to compare the performance of cosmological models including isocurvature modes with the purely adiabatic case; this framework automatically and consistently penalizes models which use more parameters to fit the data. We compute the Bayesian evidence for fits to a dataset comprised of WMAP and other microwave anisotropy data, the galaxy power spectrum from 2dFGRS and SDSS, and Type Ia supernovae luminosity distances. We find that Bayesian model selection favours the purely adiabatic models, but so far only at low significance.

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I. INTRODUCTION

Following recent developments in observational cosmology, particularly observations by the Wilkinson Microwave Anisotropy Probe (WMAP) 1, there exist compelling reasons to talk about a Standard Cosmological Model based on the ΛCDM paradigm seeded with purely adiabatic perturbations. In addition, there have been many attempts to analyze more general models featuring additional physics, either to constrain such processes or in the hope of discovering some trace effects in the data. A case of particular interest is the possible addition of an admixture of isocurvature perturbations to the adiabatic ones 2 3 which has been studied in the post-WMAP era by many authors 1 2 3 4 5 6 7 8 9 10.

The bulk of investigations so far have as a starting point chosen a particular set of parameters to define the cosmological model under discussion, and then attempted to constrain those parameters using observations, a process known as parameter fitting. Based on such analyses, many parameters are determined to a high degree of accuracy. Much less attention has been directed at the higher-level inference problem of allowing the data to decide the set of parameters to be used, known as model comparison or model selection 12 13, although such techniques have been widely deployed outside of astrophysics. Recently, one of us applied two model selection statistics, known as the Akaike and Bayesian Information Criteria, to some simple cosmological models 14, and showed that the simplest model considered was the one favoured by the data. These criteria have recently been applied to models with isocurvature perturbations by Parkinson et al. 8, who concluded that the purely adiabatic model was favoured.

Those statistics are not however full implementations of Bayesian inference, which appears to be the most appropriate framework for interpreting cosmological data. The correct model selection tool to use in that context is the Bayesian evidence 12 13, which is the probability of the model in light of the data (i.e. the average likelihood over the prior distribution). It has been deployed in cosmological contexts by several authors 15, and the ratio of evidences between two models is also known as the Bayes Factor 16. The Bayesian evidence can be combined with prior probabilities for different models if desired, but even if the prior probabilities are assumed equal, the evidence still automatically encodes a preference for simpler models, implementing Occam’s razor in a quantitative manner.

Whenever one aims to decide whether or not a particular parameter $p$ should be fixed (for example at $p = 0$), one should use model selection techniques. If one carries out only a parameter-fitting exercise and then examines the likelihood level at which $p = 0$ is excluded, such a comparison fails to account for the model dimensionality being reduced by one at the point $p = 0$, and hence draws conclusions inconsistent with Bayesian inference. This typically overestimates the significance at which the parameter $p$ is needed. An example is spectral index running, which parameter fitting favours at a modest (albeit unconvincing) confidence level 17, but which is disfavoured by model selection statistics 14.

In this paper we use the Bayesian evidence to compare isocurvature and adiabatic models in light of current data. We will closely follow the notation of Beltrán et al. 18, who recently carried out a parameter-fitting analysis of isocurvature models, and we use the same datasets. We follow the notation of that paper and provide only a brief summary in this article.

1 The difference in Bayesian Information Criterion can be used as a crude approximation to ln(Bayes Factor), but the existence of parameter degeneracies in cosmological data fitting are likely to violate the conditions for the validity of the approximation.
\section{Bayesian Evidence}

\subsection{Theoretical Basis}

The Bayesian evidence is the average likelihood of a model over its prior parameter space, namely

\begin{equation}
E = \int \mathcal{L}(\theta) \, \text{pr}(\theta) \, d\theta,
\end{equation}

where $\theta$ is the parameter vector defining the model, $\text{pr}(\theta)$ the normalized priors on those parameters (typically taken to be top-hat distributions over some range), and $\mathcal{L}(\theta)$ is the likelihood. In essence, it asks the question: ‘If I consider the possible model parameters I was allowing before I knew about this data, on average how well did they fit the data?’ Generally speaking, models with fewer parameters tend to be more predictive, and provided that for some parameter choices they fit the data well, then the average likelihood can be expected to be higher. On the other hand, a simple model which cannot fit the data for any parameter choices will not generate a good likelihood. The Bayesian evidence therefore sets up the desired tension between model simplicity and ability to explain the data.

Models are ranked in order of their Bayesian evidence, usually using its logarithm. The overall normalization is irrelevant. As the evidence is the (unnormalized) probability of the model, if two models are being compared, the odds of the one with the lower evidence is $1/(1 + \exp(\Delta \ln E))$. What constitutes a significant difference is to some extent a matter of personal taste, but a useful guide is given by Jeffreys \cite{12} who rates $\Delta \ln E < 1$ as ‘not worth more than a bare mention’, $1 < \Delta \ln E < 2.5$ as ‘substantial’, $2.5 < \Delta \ln E < 5$ ‘strong’ to ‘very strong’ and $5 < \Delta \ln E$ as ‘decisive’, in each case the decision being against the model with the smaller evidence. Note that a difference $\Delta \ln E$ of 2.5 corresponds to odds of 1 in about 13, and $\Delta \ln E$ of 5 to odds of 1 in 150.

A significant, but unavoidable, disadvantage of the use of the evidence is that it depends on the prior ranges chosen for the parameters. For instance, if one doubles the range of one parameter by allowing it to vary in a region where the likelihood is negligibly small, then the evidence will half. Indeed, one can make any model disfavoured simply by extending its prior range indefinitely in a direction where there is no hope of fitting the data. From a Bayesian point of view this is unsurprising; of course your belief in a model should be influenced by what you thought of it before the data came along, and the Bayesian analysis has the virtue of forcing you to make your assumptions explicit.

However, the prior width is not as crucial as one might na"ively expect. The main reason is that the likelihood is typically falling off exponentially away from the best fit, while the parameter volume is growing only as a polynomial function. For example, consider a one-dimensional toy-model for which the likelihood is given by

\begin{equation}
\mathcal{L}(x) = \mathcal{L}_0 \exp \left( -\frac{(x - \mu)^2}{2} \right),
\end{equation}

and consider two models: model A is $x = 0$ and model B is $x \neq 0$ with a top-hat prior $0 < x < a$. In the case $\mu = 1$, a conventional 1-$\sigma$ non-detection, the evidence would be unable to strongly distinguish between the models ($|\Delta \ln E| < 2.5$) for up to $a \sim 50$. In the case $\mu = 5$, a conventional 5-$\sigma$ detection, the evidence would prefer model B for all $a \lesssim 5 \times 10^4$. In other words, for reasonable prior ranges the evidence will robustly pick up the correct model. Its main advantage is that it is a quantitative measure with clear interpretation within Bayesian statistics, and can be applied in cases where the usual frequentist arguments do not provide us with definite answers. Typically, Bayesian analysis contradicts the frequentist results whenever the latter accepts a parameter in light of a marginally better $\chi^2$ value. If this improvement is not significant, the increase of the volume of the parameter space will penalize the addition of the new parameter and thus decrease the evidence of the extended model.

Generally the evidence is not reparametrization invariant, in the sense that the choice of a flat prior in one parametrization will probably not correspond to a flat prior under another parametrization. The choice of parametrization is a matter of personal preference, though obviously truly robust model selection results should be preserved under reasonable changes in parametrization. In the case of isocurvature perturbations there are different, equally plausible, choices of parametrization, in particular geared to dealing with the problem of the cross-correlation angle becoming unconstrained as the isocurvature mode amplitude becomes small \cite{11}. For illustration we will compare the results obtained under two different parametrization choices.

\subsection{Numerical Implementation}

The evidence for a given model can be computed by a Markov Chain Monte Carlo method. However it cannot be directly calculated from chains used in parameter estimation (for instance from the program CosmoMC \cite{13}), because those chains are sampled from the posterior distribution, which is peaked around the maximum likelihood, and do not carry the necessary information on the likelihood far from the maximum. Equally, one cannot simply sample from the prior distribution, because the dominant contribution from the high-likelihood regions will not be properly sampled. Consequently, a hybrid technique is required, a useful method being thermodynamic integration \cite{18,19}.

Thermodynamic integration alters the sampling of a Markov chain by introducing a parameter $\lambda$, thought of as an inverse temperature, with the acceptance rate governed by the likelihood raised to the power $\lambda$. As $\lambda$ is var-
ied from zero to one, this interpolates between sampling from the prior and the posterior distributions. Defining
\[ E(\lambda) = \int \mathcal{L}^\lambda(\theta) \, p_r(\theta) \, d\theta, \quad (3) \]
it can be shown that
\[ \ln E = \ln \frac{E(1)}{E(0)} = \int_0^1 \frac{d \ln E}{d\lambda} \, d\lambda = \int_0^1 \langle \ln \mathcal{L} \rangle_{\lambda} \, d\lambda, \quad (4) \]
where
\[ \langle \ln \mathcal{L} \rangle_{\lambda} \equiv \frac{\int \ln \mathcal{L}^\lambda(\theta) \, p_r(\theta) \, d\theta}{\int \mathcal{L}^\lambda \, p_r(\theta) \, d\theta} \quad (5) \]
is the average of \( \ln \mathcal{L} \) over the distribution at temperature \( 1/\lambda \). That the priors in Eq. (1) must be normalized implies that \( E(0) \) equals one, though the prior normalization anyway cancels out in the integrand Eq. (5).

Previous work in cosmology has typically evaluated the evidence during the burn-in phase of a chain to be used for parameter estimation. In this process, the temperature is slowly cooled from \( \lambda = 0 \) to \( \lambda = 1 \) to facilitate the relaxation of the chain into its stationary distribution and those chain elements are used for evidence computation; they are then discarded and the remaining elements, all sampled at \( \lambda = 1 \), are used for parameter estimation. This method is ideal for complex inference problems with dimensionality \( d \gg 1 \) and multimodal likelihood distributions, where a slow burn-in phase is necessary to explore the posterior in an unbiased manner and thus the evidence calculation comes ‘for free’. However, in a typical cosmological problem the likelihood surface is considerably simpler, arguably unimodal, and the number of samples required for a reliable burn-in is much smaller than the number of samples needed for an accurate evidence estimation. Therefore, we choose a different approach in which we heat the chain, using the endpoint of a parameter estimation run as the starting point. Since the volume of parameter space is larger at higher temperatures it should be much easier to ensure that the chain is stationary at each temperature step during heating rather than cooling. We implemented two different heating schedules:

- **Continuous temperature change.** We let the inverse sampling temperature change continuously at each step as
  \[ \lambda(n) = (1 - \xi)^n, \quad (6) \]
  where \( n \) is the step number. The single sample taken at that temperature can be viewed as an unbiased (although noisy) estimate of \( \langle \ln \mathcal{L} \rangle_{\lambda} \). This continuous approach obviates the problem of deciding the number of steps per position, transferring it to the step size. When the algorithm decides to stop, the integral is closed to \( \lambda = 0 \) in the last step. The stopping criterion is that the closure of the integral by the last step would change \( \ln E \) by less than a certain threshold, \( \epsilon_{\text{stop}} \), even for the most extreme likelihood encountered. The choices of \( \xi \) and \( \epsilon_{\text{stop}} \) determine the accuracy and speed of the evidence calculator, and optimum values must be determined empirically. After trying various possibilities we settled for \( \xi = 5 \times 10^{-5} \) and \( \epsilon_{\text{stop}} = 0.001 \). We have tested that decreasing either \( \xi \) or \( \epsilon_{\text{stop}} \) further does not affect our results.

- **Stepwise temperature change.** The integrand of Eq. (3) is first estimated at \( \lambda = 1 \) and 0, then at intermediate temperatures given by
  \[ \lambda_n = \frac{1}{q^n}, \quad (7) \]
  \( q \) (typically 1.5 – 2 and \( n \) an increasing integer). The thermodynamic integral is calculated by the trapezoid rule after each additional point is added. The points are added until the integral converges to a user-specified stopping accuracy \( \epsilon_{\text{stop}} \). At each temperature the integral is calculated by making a short burn-in at that temperature (typically 400 samples, since the chain must already be roughly burned in from the previous step) and then calculating \( \langle \ln \mathcal{L} \rangle_{\lambda} \) from a further number (typically 1000) of accepted samples. This approach has the disadvantage that extra samples are needed for burn-in at each temperature and that there might be systematics associated with stepwise temperature change. However, it is less sensitive to the quality of covariance matrix as a poorer covariance matrix simply results in more samples being taken to get enough accepted samples (note that we cannot do the same for the continuous scheme without biasing the result, unless one is willing to burn-in at each ‘continuous’ temperature change step).

Additionally, we modify the proposal function so that its width scales with \( \lambda^{-1} \) (up to a certain width), which ensures that at high temperatures the chain is sampling randomly from the prior, rather than random-walking with the step-size corresponding to the \( \lambda = 1 \) posterior.

These two methods have been extensively tested to give results that are consistent and accurate to within a unit of \( \ln E \) for a single run. The final numbers for all models were calculated using the continuous temperature change method. Additionally we have performed a comparison with an analytic approximation to the posterior and got results that are also consistent to better than one unit of \( \ln E \) in the adiabatic case, though slightly worse in the isocurvature case.

In all cases we find that the number of samples required to accurately estimate the evidence and avoid systematics associated with covariance matrices, proposal widths and similar is unexpectedly large; an order of magnitude larger than what is required for a simple parameter estimation. This makes the computation a challenging task as it is limited by the speed of the likelihood evaluations which require generation of the model
power spectra. This also suggests that the uncertainties on evidence values already found in the literature may be underestimated, though we note that the high quality of the WMAP data makes this task considerably more difficult than it was in the pre-WMAP era. Further investigation into evidence estimation methods is clearly warranted and will be a focus of a forthcoming paper.

### III. EVIDENCE FOR ISOCURVATURE MODELS

Our principal aim is to compare the evidence of isocurvature models with purely adiabatic ones. We will follow the notation of Beltrán et al. [10]. In general there are four types of isocurvature modes [3] — cold dark matter isocurvature (CDI), baryon isocurvature (BI), neutrino isocurvature density (NID), and neutrino isocurvature velocity (NIV) — but the first two are observationally indistinguishable [3] so we ignore the baryon isocurvature case. These modes can exist in any combination, and with correlations both amongst themselves and with the adiabatic modes. We will only allow a single type of isocurvature mode in any model, though we will allow a general spectral index both for the isocurvature modes and for their correlation with the adiabatic ones.

The flat prior ranges for all parameters are given in Table I. We consider two adiabatic models. AD-HZ is the simplest model giving a good fit to the data, with a Harrison–Zel’dovich spectrum and five variable parameters. We also computed the evidence for an extended adiabatic model AD-νs in which we set νs fixed to 1. AD-νs, δcor, α and β were fixed to 0. In the AD-νs model, νs also varies. Every isocurvature model holds the same priors for the whole set of parameters.

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Prior Range</th>
<th>Model</th>
</tr>
</thead>
<tbody>
<tr>
<td>ω_h</td>
<td>(0.018,0.032)</td>
<td>AD-HZ, AD-νs, ISO</td>
</tr>
<tr>
<td>ω_dm</td>
<td>(0.04,0.16)</td>
<td>AD-HZ, AD-νs, ISO</td>
</tr>
<tr>
<td>θ</td>
<td>(0.98,1.10)</td>
<td>AD-HZ, AD-νs, ISO</td>
</tr>
<tr>
<td>τ</td>
<td>(0,5)</td>
<td>AD-HZ, AD-νs, ISO</td>
</tr>
<tr>
<td>ln[10^10 R_{rad}]</td>
<td>(2.6,4.2)</td>
<td>AD-HZ, AD-νs, ISO</td>
</tr>
<tr>
<td>νs</td>
<td>(0.8,1.2)</td>
<td>AD-νs, ISO</td>
</tr>
<tr>
<td>νiso</td>
<td>(0.3)</td>
<td>ISO</td>
</tr>
<tr>
<td>δcor</td>
<td>(-0.14,0.4)</td>
<td>ISO</td>
</tr>
<tr>
<td>√α</td>
<td>(-1.1)</td>
<td>ISO</td>
</tr>
<tr>
<td>β</td>
<td>(-1.1)</td>
<td>ISO</td>
</tr>
</tbody>
</table>

#### TABLE II: Evidences for the four different models studied, normalized to the AD-HZ evidence. The absolute value for that model was ln E = -854.1.

The parameter δcor is related to the spectral tilt of the correlation mode, n cor, and its boundaries are fixed by the pivot scale and the k_{min} = 4 × 10^{-5} Mpc^{-1} and k_{max} = 0.5 Mpc^{-1} scales used for the analysis. It is defined as

\[ \delta_{\text{cor}} \equiv n_{\text{cor}} / \ln |\beta|^{-1}. \] (9)

Thus the priors on the first seven parameters are theoretically motivated, whereas the priors on the last three are automatically set by the model. Throughout the analysis the equation of state parameter of the dark energy was set to -1.

We have used the following datasets: cosmic microwave anisotropy data from the WMAP satellite including temperature–polarization cross-correlation [1], VSA [20], CBI [21] and ACBAR [22], matter power spectrum data from the two-degree field galaxy redshift survey (2dFGRS) power spectrum [23] and from the Sloan Digital Sky Survey [24], and the supernovae apparent magnitude–redshift relation [25].

We ran 32 independent computations of the evidence for each model. In all of them the stopping criterion was satisfied after about 2.5×10^5 steps, so the total number of likelihood evaluations was approximately 10^7 per model. The results, given as the logarithm of the evidence, are described in Table II. We have expressed all the calculated evidence values relative to the AD-HZ model, as the absolute value is just a particular of the likelihood code. We see from the table that the evidences are calculated to sufficient accuracy to draw conclusions, but that the comparison is rather inconclusive. Firstly, the two adiabatic models happen to produce the same evidence, with ∆ ln E being 1.0 relative to AD-HZ in each case. According to the Jeffreys’ scale this is just at the edge of being worthy of attention.

As mentioned in Section II, these results are not reparametrization invariant, since changing the basis of parameters typically leads to a different choice of priors. Various parameterizations have been used in the literature. For instance, a change of pivot scale leads to an
(n_a – n_iso)–dependent rescaling of α, and to an n_{cor}–
dependent rescaling of β. Even if the pivot scale is fixed, various
definitions of the amplitude parameters can be introduced. The normalization of the isocurvature mode can be parametrized by the ratio of isocurvature to adiabatic primordial fluctuations f_{iso} \in [0, \infty] instead of the fraction of isocurvature contribution to the total primordial spectrum α \in [0, 1] \in [0, 1]. In this work, as in Ref. [10], we chose to vary \sqrt{\alpha} \in [-1, 1] in order to avoid dealing with boundary effects and to have a posterior distribution falling down to zero on the two ends of the prior range. We could nevertheless instead have chosen a flat prior for α. Similarly, the cross-correlation amplitude can be parametrized either by the correlation angle \beta \in [-1, 1], as in Refs. [4, 11], or by the amplitude of the cross-correlation power spectrum 2β√α(1−α) \in [0, 1] [6]. The advantage of the latter is that the total power spectrum depends linearly on it, and so it is well constrained by the data, while starting from a flat prior on β we can get a flat posterior distribution if the preferred model is purely adiabatic, so that the value of β does not matter (this point is discussed in detail in Ref. [11] where a third choice is also introduced). Finally, we defined the parameter δ_{cor} in order to deal with a simple top-hat prior, but we could decide to use instead to impose a flat β–dependent prior directly on n_{cor}.

To get a hint of the effect of reparametrization, we recomputed the evidences using a second parameter basis: instead of (\sqrt{\alpha}, \beta) we vary (α, 2β√(1–α)) with a flat prior inside the two-dimensional ellipse in which these parameters are defined, and instead of δ_{cor} we vary n_{cor} within the range [−0.14ln(|β|^{−1}), 0.41ln(|β|^{−1})]. Since the prior on n_{cor} is too loose when β is close to zero, we imposed the additional prior over n_{cor} \in [-1, 1].

The results are quoted in Table III and show differences from the ones that use the original parametrization. Even though the difference is still not big enough to exclude any isocurvature model, we conclude that, as mentioned in Section II, parametrization does matter for the evidence calculation.

\begin{table}
\centering
\begin{tabular}{|l|c|}
\hline
Model & ln(Evidence) \\
\hline
AD-HZ & 0.0 ± 0.1 \\
CDI & −1.0 ± 0.2 \\
NID & −2.0 ± 0.2 \\
NIV & −2.3 ± 0.2 \\
\hline
\end{tabular}
\caption{Evidences for the four models using the second parametrization, again normalized to the AD-HZ evidence.}
\end{table}

IV. CONCLUSIONS

We have carefully calculated the evidence for two adiabatic models and three physically-distinguishable isocurvature models using recent cosmic microwave background, supernovae and large-scale structure data. We find very similar evidences for all the models. For the first parametrization used, the odds of the isocurvature models compared to the adiabatic ones are 1 in about 4. Using a second parametrization of the isocurvature parameters we find the odds for the neutrino cases drop to 1 in 10. Therefore, we conclude that present data are unable to offer a clear verdict for or against the inclusion of isocurvature degrees of freedom. This conclusion is similar to that found by Parkinson et al. [9] using the information criteria. Although the extra parameters introduce extra complexity, these models are still able to satisfactorily fit the present data for a wide range of their parameters and thus the evidence quantifies the common sense that one should allow these models to be considered. We also showed the relevance of the parametrization for evidence computation.

While the present comparison is inconclusive, a key question for future data will be to select between the adiabatic and isocurvature paradigms. Parameter estimation analyses cannot do this, as even if the adiabatic model is correct they can only impose limits on the isocurvature parameters. The Bayesian model selection approach we have described is the ideal tool to carry out such a selection.

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