Influence of local treatments of convection upon solar \( p \) mode excitation rates.

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Abstract. We compute the rates \( P \) at which acoustic energy is injected into the solar radial \( p \) modes for several solar models. The solar models are computed with two different local treatments of convection: the classical mixing-length theory (MLT hereafter) and Canuto et al. (1996, CGM96 hereafter)’s formulation. Among the models investigated here, our best models reproduce both the solar radius and the solar luminosity at solar age and the observed Balmer line profiles. For the MLT treatment, the rates \( P \) do depend significantly on the properties of the atmosphere whereas for the CGM96’s treatment the dependence of \( P \) on the properties of the atmosphere is found smaller than the error bars attached to the seismic measurements. The excitation rates \( P \) for modes associated with the MLT models are significantly underestimated compared with the solar seismic constraints. The CGM models yield values for \( P \) closer to the seismic data than the MLT models. We conclude that the solar \( p \)-mode excitation rates provide valuable constraints and according to the present investigation clearly favor the CGM treatment with respect to the MLT, although neither of them yields values of \( P \) as close to the observations as recently found for 3D numerical simulations.

Key words. convection - turbulence - atmosphere - stars: oscillations - Sun: oscillations

1. Introduction

In the outermost part of the convective zone (CZ) of intermediate mass stars, convection is highly superadiabatic because of the rapid radiative heat gains and losses of the convective fluid. In that region, entropy fluctuations are the largest and the resulting decrease of the convective transport efficiency is compensated by a large increase of the eddy motions which is responsible for the oscillation mode driving. Modelling inefficient convection is complex. 3D numerical simulations are now being performed but remain still very time consuming. Hence for massive stellar computations, 1D stellar models are used in which only simple prescriptions of convection are implemented.

Among these simplified treatments, Canuto & Mazzitelli (1991)’s approach differs from the classical mixing length approach (MLT hereafter) in that it takes into account the contribution of eddies with different sizes in the calculation of the convective flux and velocity while keeping the computational expenses as low as the MLT. An improved version was proposed by Canuto et al. (1996) which takes into account the feedback of the turbulence on the energy input from the source which generates turbulent convection. These multi-eddy convection models are usually referred to as Full Spectrum of Turbulence (FST) models.

Several non-local formulations of convection have also been proposed (Gough 1977; Xiong 1978, 1985; Canuto 1992, 1993; Canuto & Dubovikov 1998). However, we focus here on the effects of proposed improvements in the description of the energy spectrum and therefore consider only local treatments and compare FST models with MLT ones.

Any model of convection must satisfy several observational constraints provided by our Sun: the solar radius at the solar age, the Balmer line profiles and the \( uvby \) color indices. The MLT, CM91’s and CGM96’s local treatments have been confronted to these observational constraints (e.g. Fuhrmann et al. 1993, 1994; Canuto 1992, 1993; Canuto & Dubovikov 1998). However, we focus here on the effects of proposed improvements in the description of the energy spectrum and therefore consider only local treatments and compare FST models with MLT ones.
Solar seismic observations provide strong additional constraints. Comparisons of theoretical oscillation frequencies with observed solar ones have shown for instance that significant improvement in the agreement between observation and model at high frequency and degree \( \ell \) can be achieved with 3D simulations \cite{Rosenthaletal1999}. We are here interested in amplitudes of oscillation which can also bring several constraints on the convective process in the outer solar envelope. Indeed, the amplitudes of solar-like oscillations result from a balance between excitation and damping. Measurements of the oscillation mode growth rates (through their line-widths) and of the mode amplitudes enable the evaluation of the excitation rates \( P \). Excitation of solar-like oscillations is known to be both due to turbulent convective motions through the driving by the turbulent Reynolds stresses \cite{GoldreichKeeble1977,Balmforth1992,SamadieiGoupil2001} and due to the advection of turbulent entropy fluctuations by the turbulent movements \cite{SamadieiGoupil2001}. The excitation rates \( P \) are thus directly related to the velocity of the convective elements and to the amount of thermal energy advected by convective motions (i.e. the convective flux). The excitation rates then crucially depend on the way the convective velocity and flux are modelled \cite{Houdeketal1999}. Solar seismic measurements therefore provide – through a model of mode excitation – additional constraints on the stellar convective properties. In this framework, the goal of the present paper is to investigate the influence of different local treatments of convection on the calculation of the rates at which energy is injected into the solar radial \( p \) modes and to compare our results with the solar seismic constraints.

For this purpose, we compute two calibrated solar models with the Böhm-Vitense formulation of the MLT \cite[hereafter BV]{Bohm-Vitense1958} and with the CGM96 multi-eddy convection treatment. In each case, the same convection formulation is adopted for the interior and the model atmosphere. Models for the internal structure are built so as to reproduce the solar radius and the solar luminosity at the solar age. The atmosphere of each model is constructed using a \( T(\tau) \) law which is derived from a Kurucz’s model atmosphere \cite{Kurucz1993} computed with the same convection formulation \cite{Kurucz1993} (as described in \cite{Heiteretal2002}). These model atmospheres are built in order to provide the best agreement between synthetic and observed Balmer line profiles \cite{Van'tVeerMenneretMegessier1996} for the MLT treatment (Sect. 2). The matching of the model atmosphere with the interior model is performed – in the manner of \cite{Moreletal1994} – by ensuring the continuity of the temperature gradient, \( \nabla \), and of the convective flux in a transition region between the interior and the atmosphere.

We compute also two models with an Eddington gray atmosphere. One with the MLT treatment and the second one with the CGM96 formulation. These two additional models are considered for comparison purpose only. Indeed, they have an atmosphere with the same mixing-length parameter as in the interior and do not reproduce the Balmer line profiles. As a consequence, in contrast with the interior models including a Kurucz’s atmosphere as described above, their atmospheres do not fulfill constraints on the properties of the convection at the surface.

Calculation of the excitation rates requires the computation of the convective flux, \( F_c \), and of the convective velocity, \( v \). This is done in Sect. 3 by paying special attention to the problem of the transition region. Indeed, the continuity of \( \nabla \) and of \( F_c \) through the transition region imposes a spatial variation of the mixing-length parameter in the transition region. This variable mixing-length parameter is then used in Sect. 3 to compute \( v \). Note that our approach, which is used here to compute \( v \) and \( P \), is different from that of \cite{Schlattlettal1997} who built stellar models assuming a spatially varying mixing-length parameter, with a spatial variation imposed a priori from a comparison to 2D numerical simulations of convection, in order to compute \( \mu \) mode frequencies.

As a last step (Sect. 4), we compute the adiabatic eigenmodes and the excitation rates \( P \) for each model. The adopted model of excitation is that of \cite{SamadieiGoupil2001}. Paper I hereafter) in which the characteristic wavenumber \( k_0 \), the wavenumber dependency of the turbulent spectra as well as the frequency component (\( \chi_k \)) of the correlation product of the turbulent velocity field are constrained with a 3D simulation of the Sun as in \cite{Samadieietal2003b}. Paper II hereafter) and \cite{Samadieietal2003c}. Paper III hereafter). Comparison with solar seismic constraints then allows to conclude about the best local treatment of convection in the solar case (Sect. 5).

2. Solar models

All solar models discussed here are computed with the CESAM code \cite{More1997} including the following input physics and numerical features:

1. Equation of state (EOS): CEFF EOS \cite{Christensen-DalsgaardDiopper1992}.
2. Opacities: OPAL \cite{IglesiasRogers1996} data complemented by \cite{AlexanderFerguson1994} data for \( T \lesssim 10^4 \) K, both set of data being given for \cite{GrevesseNoels1993} solar mixture.
3. Thermonuclear reaction rates: \cite{CaughlanFowler1988}.
4. Convection: either MLT or CGM96’s formalism. The same convection formalism has been used in the interior and in the model atmosphere.
5. Microscopic diffusion: all models include microscopic diffusion of helium and heavy elements calculated according to the simplified formalism of \cite{MichaudProffitt1993} where heavy elements are treated as trace elements.
6. Chemical composition and mixing length parameter for convection: the \cite{GrevesseNoels1993} heavy el-
elements solar mixture has been adopted. The constraint that solar models have the observed solar luminosity and radius at solar age yields the initial helium content \( Y_0 \) and the mixing length parameter of the interior model \( \alpha_1 \) (solar model calibration). Microscopic diffusion modifies the surface composition, therefore the initial ratio of heavy elements to hydrogen \((Z/X)_0\) is adjusted so as to get the ratio \((Z/X)_\odot = 0.0245\) at solar age.

7. The models were calculated with 285 shells in the atmosphere and about 2000 shells in the interior.

The CGM96 formulation of convection is implemented according to Heiter et al. (2002). In contrast with the CGM0 formulation. They will be hereafter labelled as KML T model and KCGM model respectively.

\[ \alpha \] for model atmospheres are built assuming different values of those models are computed using the ATLAS 9 code (Heiter et al. 2002), we use for the two formulations a characteristic scale length of convection which is the mixing-length \( \Lambda = \alpha H_p \) where \( H_p \) is the pressure scale height and \( \alpha \) is the mixing-length parameter which can be different in the interior and in the atmosphere.

2.1. The “Kurucz models” (KMLT and KCGM models)

We consider here two stellar models: one computed with the MLT formulation of convection and the second one with the CGM96 formulation. They will be hereafter labelled as KMLT model and KCGM model respectively.

Treatment of the atmosphere: The model atmospheres of those models are computed using the ATLAS 9 code (Kurucz 1993) as described in Heiter et al. (2002). Solar model atmospheres are built assuming different values for \( \alpha \), the mixing-length parameter assumed for the model atmosphere: \( \alpha_s = 0.4, 0.5, 0.6, 0.7 \). The model atmospheres with \( \alpha_s = 0.4 \) and \( \alpha_s = 0.5 \) provide the best agreement between synthetic and observed H\( \beta \) Balmer line profiles for the two formulations of convection. This is shown in Fig. 1 for the CGM model atmosphere. For the MLT treatment see Fuhrmann et al. (1993, 1994) and van’t Veer-Menneret & Meegesser (1996). Above \( \alpha_s \approx 0.6 \), the synthetic profile rapidly departs from the observed one as well as the effective temperature \( T_{\text{eff}} \) from the known solar \( T_{\text{eff}} \).

There are no significant differences for the H\( \beta \) Balmer line profile between the model atmospheres with \( \alpha_s = 0.4 \) and \( \alpha_s = 0.5 \). Among those model atmospheres we adopt arbitrary those with \( \alpha_s = 0.5 \). Indeed, choosing the model atmospheres with \( \alpha_s = 0.4 \) instead of \( \alpha_s = 0.5 \) will not change the conclusions of this article.

For each formulation of convection we then obtain a \( T(\tau) \) law.

The atmospheres of the KMLT and KCGM stellar models are recomputed according to the procedure described in Morel et al. (1994) from the \( T(\tau) \)-laws mentioned above; the fit between interior (where the diffusion approximation is valid) and atmosphere is performed in a region where \( \tau \lesssim \tau < \tau_2 \) (an acceptable range of values for \( \tau_1 \) and \( \tau_2 \) is discussed below). In the interior region, where \( \tau \gtrsim \tau_2 \), the temperature gradient \( \nabla \) is obtained from the MLT or CGM96 formalism. In the atmospheric region, where \( \tau \lesssim \tau_1 \), the temperature gradient \( \nabla_\alpha \) is computed using the \( T - \tau \) law of the model atmosphere built with the same model of convection as in the interior. In the transition region, where \( \tau_1 \lesssim \tau \lesssim \tau_2 \), in order to ensure the continuity of the temperature gradient, \( \nabla \) is obtained by a linear interpolation of \( \nabla_1 \) and \( \nabla_\alpha \) as a function of the optical depth as follows:

\[
\nabla = \beta(\tau)\nabla_\alpha + (1 - \beta(\tau))\nabla_1
\]

where \( \beta(\tau) = (\tau_2 - \tau)/(\tau_2 - \tau_1) \).

Once the temperature gradients of the interior and the atmosphere are linked together in the transition region according to Eq. (1), we compute afterward in that region the convective flux and an equivalent mixing-length parameter (i.e. a depth dependent mixing-length parameter) as explained in Sect. 3.

Acceptable ranges for \( \tau_1 \) and \( \tau_2 \): Using a Newton-Raphson scheme, \( \nabla_1 \) is adjusted in order that \( F_{\text{rad}}^{(i)} + F_{\text{rad}}^{(i)} = L_\odot/4\pi r^2 \), where \( L_\odot \) is the luminosity of the Sun and \( F_{\text{rad}}^{(i)} \) is the radiative flux of the internal model. Calculation of \( F_{\text{rad}} \) assumes for \( F_{\text{rad}} \) the diffusion approximation for the radiative transfer. This approximation is valid at rather high values of \( \tau \), typically \( \tau \gtrsim 10 \) (see Morel et al. 1994). Therefore, \( \tau_1 \) cannot be much smaller than \( \tau \approx 10 \). Otherwise, \( \nabla_1 \) will have an unrealistic contribution to \( \nabla \) below \( \tau \approx 10 \). On the other hand, for the calculation of \( F_{\text{rad}} \), the radiative flux \( F_{\text{rad}} \) is based on a Kurucz’s model atmosphere which treats the radiative transfer more realistically than the diffusion approximation.

The Kurucz model atmosphere is based on opacity tables which are given up to \( T \approx 2 \times 10^5 \) K and \( P = 10^8 \) dyn cm\(^{-2} \). As a consequence, \( \tau_2 \) cannot be larger than \( \tau \approx 10^7.5 \), i.e. layers for which \( T \approx 30000 \) K. In order to ensure a satisfactory continuity of the temperature gradient \( \tau_2 \) must be sufficiently larger than \( \tau_1 \). On the other hand, the transition region should be as small as possible, i.e. \( \tau_2 - \tau_1 \) must be as small as possible. The main constraint for this region is thus to avoid discontinuities between the interior and the atmosphere.

It is defined through an empirical procedure rather than based on a strict physical theory.

In practice, we find that \( \tau_1 = 4 \) is the minimal acceptable value for \( \tau_1 \); below this value the bias introduced by the diffusion approximation has a significant effect on \( F_{\text{c}} \). In addition, we find that above \( \tau_2 \approx 50 \), the convective velocity \( v \) (see Sect. 3.2) shows a pronounced “kink” at \( \tau = \tau_2 \) for the CGM model (see Fig. 3 such a “kink” is also observed for \( F_{\text{c}} \), but it is less pronounced). On the other hand, the choice of \( \tau_2 = 20 \) avoids the angular point. For the MLT model, whatever the value of \( \tau_2 \), \( v \) shows such a feature. This is a consequence of the much larger values of the mixing length parameter required in the interior in order to still obtain the correct solar radius, if a lower value of \( \alpha \) is used also in regions further within the envelope. The requirement of matching \( R_\odot \) hence provides a more stringent upper limit for the choice of \( \tau_2 \) (cf. also the
Fig. 1. The observed solar H\textsubscript{\&} profile is compared to theoretical ones computed with CGM models and assuming different values for $\alpha_a$. Abscissae are distances in Å from the line center, ordinates are the flux in the profile normalized to the continuum. The large scatter is due to the presence of many spectral lines which overlap and cause an apparent enlargement of the true profile.

Calibration: The mixing-length parameter $\alpha_i$ for the internal structure, $Y_0$, and $(Z/X)_0$ are adjusted such that the stellar model simultaneously reproduces the solar radius, the solar luminosity, and the observed ratio $(Z/X)_\odot = 0.0245$ at the solar age. The calibration yields $(Z/X)_0 = 0.0279$ and $Y_0 = 0.275$. At solar age, the helium abundance in the convection zone is $Y = 0.246$ in reasonable agreement with the value $Y = 0.249 \pm 0.003$ obtained from seismology [Basu 1997]. In the following we will consider $\tau_1 = 4$ and $\tau_2 = 20$ as our optimal choice.

### Table 1. Values of the mixing-length parameters of the KCGM and KMLT models: $\alpha_i$ (for the interior) and $\alpha_a$ (for the model atmosphere). $\alpha_i$ results from the calibration of the full model while $\alpha_a$ is fixed (see Sect. 2.1).

<table>
<thead>
<tr>
<th>Model</th>
<th>$\alpha_i$</th>
<th>$\alpha_a$</th>
</tr>
</thead>
<tbody>
<tr>
<td>KMLT</td>
<td>2.51</td>
<td>0.50</td>
</tr>
<tr>
<td>KCGM</td>
<td>0.78</td>
<td>0.50</td>
</tr>
</tbody>
</table>
model and ECGM model, respectively. The mixing-length parameter $\alpha$ of these models (the same $\alpha$ in the interior as in the atmosphere) is adjusted in order to reproduce the solar luminosity and radius at the solar age. However, as mentioned in the introduction, these models do not reproduce the Balmer line profiles. Table 3 gives the calibrated values of the mixing-length parameters.

### 2.3. Comments

With the CGM96 treatment, $\alpha_i$ is found less than one and closer to $\alpha_a = 0.5$. In contrast, with the MLT treatment the value of $\alpha_i$ is much larger than $\alpha_a = 0.5$.

The CGM models result in a much smaller value for the mixing-length parameter ($\alpha_i$ for the KCGM model and $\alpha$ for the ECGM model) than the MLT models because the convection in nearly adiabatic regions is more efficient with the CGM96 formulation than with the MLT one. Indeed, for the same value of the mixing-length parameter and in the region of high convective efficiency (below the superadiabatic region), the CGM96 treatment predicts a convective flux ten times larger than the MLT one for a given superadiabatic gradient. In a solar model this behavior results in a gradient closer to the adiabatic one below a smaller superadiabatic zone in comparison to the MLT case (Canuto et al. 1996). At the top of the quasi-adiabatic region, energy is predominantly transported by convection, such that $F_c \simeq F$ where $F_c$ is the convective flux and $F$ is the total energy flux. Above, convective transport is no longer efficient ($F_c < F$). Therefore, the solar energy flux $F$ at the top of the quasi-adiabatic region can be reproduced for the CGM models with a smaller value of the mixing-length parameter than that one required for the MLT.

The superadiabatic gradients are displayed in Fig. 2 as a function of $\tau$. The angular point observed in $\nabla - \nabla_{ad}$ at the optical depth $\tau \simeq 20$ for the KMLT model corresponds to the matching point (i.e. at $R_\odot - r \approx 100$ km, where $R_\odot$ is the solar radius at the photosphere, defined to be where $\tau = 2/3$ and calibrated at the precision level given in Table 2). It results from the large difference between $\alpha_i$ and $\alpha_a$. This difference is much smaller for the KCGM model and therefore the “kink” at $\tau \simeq 20$ is much less pronounced.

Our last comment concerns the large difference in the value of the mixing-length parameter between the KMLT and the EMLT models: Both models differ only by the structure of their uppermost layers located 50 - 100 km below the photosphere (see Fig. 3, middle) which represent a tiny fraction of the convection zone depth. The KMLT has a model atmosphere in which convection is much less efficient than that of the EMLT model as a consequence of the fact that $\alpha_a = 0.5$ in the Kurucz’s model atmosphere (see Sec. 2.1). This is the reason why the superadiabatic gradient, $\nabla - \nabla_{ad}$, is reaching at that depth much higher values for the KMLT model than for the EMLT model. Now if $\nabla - \nabla_{ad}$ from two models are vastly different, so is the entropy jump of both. Hence, if a certain entropy of the interior convection zone and thus a certain radius of the convection zone shall be matched, a much more drastic change in $\alpha$ is required with the KMLT model to avoid a too large entropy jump (see a detailed discussion in Montalbán et al. (2004)).

### Table 2

<table>
<thead>
<tr>
<th>model</th>
<th>$\Delta R/R_\odot$</th>
<th>depth CZ</th>
</tr>
</thead>
<tbody>
<tr>
<td>KMLT</td>
<td>$-10^{-6}$</td>
<td>0.2860</td>
</tr>
<tr>
<td>KCGM</td>
<td>$5 \times 10^{-6}$</td>
<td>0.2859</td>
</tr>
</tbody>
</table>

### Table 3

<table>
<thead>
<tr>
<th>model</th>
<th>$\alpha$</th>
</tr>
</thead>
<tbody>
<tr>
<td>EMLT</td>
<td>1.76</td>
</tr>
<tr>
<td>ECGM</td>
<td>0.69</td>
</tr>
</tbody>
</table>

Fig. 2. The superadiabatic gradient $\nabla - \nabla_{ad}$ is plotted versus the optical depth $\tau$ in the outer region for the KMLT model (dashed line), EMLT model (dot-dashed line), ECGM model (dot-dot-dashed line) and KCGM model (solid line). The dotted vertical lines correspond to the layers where $\tau = \tau_1 = 4$ and $\tau = \tau_2 = 20$, respectively, and delimit the transition region.
3. Convective velocity and entropy fluctuations

3.1. Convective flux

Part of the mode excitation rates stems from the advective part of turbulent entropy fluctuations by turbulent motions (the so-called “entropy source term”). This term describes the entropy fluctuations due to turbulent convection which has a similar form to the momentum equation. The spatially averaged anisotropy factor which is defined as (Gough 1977):

$$\bar{\Phi}(r) \equiv \frac{v^2}{\langle u^2 \rangle}$$

where $u_2$ is the vertical component of $u$ and $v$ and $w$ are defined as $v^2 \equiv \langle u^2 \rangle$ and $w^2 \equiv \langle u_2^2 \rangle$, respectively.

For the CGM96 formulation, $F_c$ is computed according to Eqs. (2) and (17)-(21) in Héritier et al. (2002) and for the MLT treatment, it is calculated according to Eq. (14.118) in Cox (1968, Chap. 14).

$F_c$ can be viewed as function of $\alpha$ and $\nabla$, $F_c = h(\nabla, \alpha)$, where $h$ is given by the adopted model of convection.

**ECGM and EMLT models:** for these two models only one mixing-length parameter is involved and $F_c$ can directly be retrieved from $\alpha$ and $\nabla$.

**KCGM and KMLT models:** in the outer region ($\tau < \tau_1$) as well as in the interior region ($\tau > \tau_2$), values of $F_c$ can be directly retrieved from $\alpha$ and $\nabla$. In the transition region ($\tau_1 < \tau < \tau_2$), however, we have to deal with two functions of the convective flux: $F_c^{(a)} = h(\nabla, \alpha)$, the convective flux calculated as in the interior, and $F_c^{(i)} = h(\nabla, \alpha)$, the convective flux calculated for the atmosphere. As a result of Eq. 11, the convective flux $F_c$ of the model in the transition region can be related to $F_c^{(i)}$ and $F_c^{(a)}$ as follows:

$$F_c = \lambda(\tau)F_c^{(a)} + (1 - \lambda(\tau))F_c^{(i)}$$

where $\lambda(\tau)$ is the function of $\tau$ which ensures the continuity of the convective flux. This function must decrease with $\tau$ and must fulfil $\lambda(\tau) = 1$ for $\tau \leq \tau_1$, and $\lambda(\tau) = 0$ for $\tau \geq \tau_2$. We point out that both $F_c^{(i)}$ and $F_c^{(a)}$ fulfill $F_c + Frad = L_0/4\pi\tau^2$ at any optical depth $\tau$. As for $\beta(\tau)$, the choice for $\lambda(\tau)$ is rather arbitrary. For the case of $\nabla$ (Eq. 11), we assume $\lambda(\tau) = \beta(\tau) = (\tau_2 - \tau)/(\tau_2 - \tau_1)$ for $\tau_1 < \tau < \tau_2$.

Calculation of the driving by the entropy source term requires, in addition to the convective flux ($F_c$), a model for the mean anisotropy ($\bar{\Phi}$). In the CGM96 model of convection the expressions for $v^2$ and $F_c$ do not depend explicitly on the mean anisotropy factor $\bar{\Phi}$. However, CGM96 adopt a model of anisotropy which fixes the ratio $x = k_h/k_v$, where $k_h$ and $k_v$ are the horizontal and vertical wavenumbers associated with the eddy of wavenumber $k$ (note that $k^2 = k_h^2 + k_v^2$). As a result of that model, for the largest scales $x = 1/2$ while it increases quadratically with the total wavenumber $k$ for the smaller scales. Let us define $\phi(k) = u_2^2(k)/u_2^2(k)$, a k-dependent anisotropy factor. For an incompressible fluid – a property assumed by the models investigated here (see also CM91) – one can show that $\phi(k) = 1 + x^{-1}$. Hence $x = 1/2$ implies $\phi = 3$, i.e. an isotropic velocity field. As a result of its functional dependence on $k$, from the larger scales ($k \sim k_0$) to the smaller scales ($k \gg k_0$) $\phi(k)$ decreases in the CGM96 model from $\sim 3$ towards $\sim 1$. However, we recall that the model of stochastic excitation (MSE) we consider is basically isotropic. The anisotropy is taken into account only at large scales through Gough’s mean anisotropy factor ($\bar{\Phi}$). Therefore, although CGM96’s treatment adopts a model where the anisotropy varies with $k$, we are left with the inconsistency that the turbulent spectrum, $E(k)$, assumed for the MSE (see Sect. 3.1) is isotropic along the turbulent cascade. A possible anisotropy is only be taken into account at large scales through $\Phi$. But as the modes are predominantly excited by turbulent eddies with $k \sim k_0$, which carry most of the kinetic energy, this approximation is not expected to affect significantly our prediction. Hence, we assume $\Phi = 3$ for the CGM96 models in the discussion given below.

3.2. Convective velocity

Driving of the oscillation modes by the Reynolds term is proportional to $\rho_0v^4$.

For the CGM96’s treatment, $v^2$ is computed according to Eq. (88-90) of CGM96.

The MLT approach provides a theoretical expression for $w^2$, the mean square of the vertical component of the convective velocity. It can be related to the velocity $v$ by means of $\Phi$ (Eq. 2). BV’s formulation of the MLT assumes $\Phi = 2$ (Gough 1977). Here, we compute $w^2$ according to Eq. (14.110) of Cox (1968, Chap. 14) and deduce $v$ from Eq. (2) with $\Phi = 2$.

Just as the convective flux, the convective velocity $v$ can be viewed as a function of $\nabla$ and $\alpha$, $v = f(\nabla, \alpha)$.

**ECGM and EMLT models:** as for the convective flux, $v$ can be retrieved from $\alpha$ and $\nabla$.

**KCGM and KMLT models:** in the outer region (i.e. $\tau < \tau_1$) as well as in the inner region ($\tau > \tau_2$), only one $\alpha$ and one $\nabla$ are defined. In those regions $v$ is computed as $v = f(\nabla, \alpha)$. However, in the transition region we must deal with two different values of $\alpha$ (namely $\alpha_i$ and $\nabla_i$ from the inner region and $\alpha_a$ and $\nabla_a$ from the atmosphere) and
v is not a linear function of α. We thus face the difficulty to define properly a convective velocity consistent with $F_c$ (Eq. 3) in this region.

We proceed as follows: $\nabla(\tau)$ and $F_c(\tau)$ are defined by Eq. (1) and Eq. (3), respectively. Then, at fixed $\nabla$ and $\tau$, we define an equivalent mixing-length parameter, $\alpha^*$, such that $F_c = h(\nabla, \alpha^*)$. This parameter is variable with depth. We next compute $v = f(\nabla(\tau), \alpha^*)$ which hence is consistent with $F_c$ of Eq. (3).

Figure 3 (middle and bottom) shows $\alpha^*$ and $v$ as a function of depth. For the MLT models, our calculation of $v$ assumes $\Phi = 2$ which is consistent with BV’s formulation of the MLT (see Gough 1977) and for the CGM models it assumes $\Phi = 3$.

3.3. Comments

As shown in Fig. 3 the EMLT and KMLT models have very different convective structures: up until close to the top of the superadiabatic region (located at $R_\odot - r \sim 70$ km for those models), the EMLT model results in a convective velocity and convective flux smaller than those of the KMLT model. This is a consequence of the fact that $\alpha_{EMLT} < \alpha_{KMLT}$ (see Table 1 and Table 3). On the other hand, the EMLT model results in larger $v$ and $F_c$ above the top of the superadiabatic region because $\alpha_{EMLT} > \alpha_{a} = 0.5$.

In contrast with the MLT models, the KCGM and ECGM models have rather similar convective structures. Indeed, $v_{KCGM}$ and $v_{ECGM}$ ($F_{KCGM}$ and $F_{ECGM}$ resp.) have very similar shapes. This in turn is a consequence of the fact that the CGM models require values of $\alpha_{KCGM}$ and of $\alpha_{ECGM}$ close to that one required for the atmosphere ($\alpha_a = 0.5$).

For the KMLT model, there is a pronounced “kink” at the bottom boundary of the transition region (i.e. at $\tau = 20$ or $R_\odot - r = 100$ km), especially for $v$. For the KCGM model the “kink” is much less important. These features are directly connected with the angular point observed for $\nabla$ in that layer (see Sect. 2.3 and Fig. 2).

At the bottom of the transition region (i.e. at $\tau = \tau_2$), for both the KMLT and KCGM models, $\alpha^*(\tau)$ reaches – as expected – the “interior” value of the mixing-length parameter (i.e. $\alpha_i$), namely: $\alpha_{KCGM} = 0.78$ and $\alpha_{KMLT} = 2.51$. At the top of the transition region (i.e. at $\tau = \tau_1$), $\alpha^*(\tau)$ reaches for both the KCGM and KMLT models the asymptotic value $\alpha^* \simeq 0.50$.

4. Calculation of the solar $p$ mode excitation rates

4.1. Procedure

We compute the rate $P$ at which acoustic energy is injected into solar radial $p$-modes according to the theoretical model of stochastic excitation of Paper I and assume here – as in Paper II and Paper III – that injection of acoustic energy into the modes is isotropic and consider only radial $p$ modes. The rate at which a given mode with frequency $\omega_0 = 2\pi\nu_0$ is excited is then calculated with the set of Eqs (1-11) of Paper III and Eq. (3) of Samadi et al. (2004).
The calculation requires the knowledge of three different types of quantities. First of all, quantities which are related to the average properties of the medium:

- the mean density \( \rho \), \( \alpha_s \) (Eq. A.25), the mean square convective velocity \( v^2 \), and the mean square of the entropy fluctuations \( s^2 \) (Eq. A.38). They are obtained from the equilibrium models as explained in Sect. 3.

Secondly, quantities which are related to the turbulence modes:

- the eigenfunctions \( \xi_r \) and the eigenfrequencies \( \nu \). They are computed with the adiabatic pulsation code FILOU (Tran Minh & León 1993) for each model.

Finally, quantities which are related to the properties of the turbulent flow:

- the wavenumber \( (k) \) dependency of \( E \), i.e. the turbulent kinetic energy spectrum;
- the values and depth dependency of \( k_0 \), the wavenumber at which the convective energy has its maximum and is “injected” into the inertial range of the turbulent kinetic energy spectrum \( E \);
- the \( \nu \)-dependency of \( \chi_k \), the frequency component of the auto-correlation product of the turbulent velocity field.

According to the results in Paper II and Paper III obtained on the basis of a 3D numerical solar granulation simulation, the \( k \)-dependency of \( E(k, \nu) \) is approximately reproduced by an analytical spectrum called ‘Extended Kolmogorov Spectrum’ (EKS) and defined in Musielak et al. (1994). The \( \nu \)-dependency of \( \chi_k \) is found to be better modelled with a Lorentzian function rather than by a Gaussian function, which is usually assumed for \( \chi_k \) (see Paper III). Within most part of the excitation region the spatially averaged anisotropy factor \( \Phi \) is found almost constant with a value of \( \bar{\Phi} \sim 2 \) in agreement with BV’s value.

At the top of the superadiabatic region, it was found that \( k_0 \sim 3.6 \text{ Mm}^{-1} \) and that \( k_0 \) decreases slowly inwards with depth (see Paper II). A good approximation for our region of interest within the sun is to assume a constant \( k_0 \).

### 4.2. Comparison with the observations

Results for \( P \) are presented in Fig. 4. The theoretical estimates for \( P \) are compared with the ‘observed’ \( P_{\text{obs}} \), calculated from Chaplin et al. (1998)’s seismic data according to the relation:

\[
P_{\text{obs}}(\nu) = 2\pi \Gamma \frac{I}{\xi_r^2(r_s)} v_s^2(\nu) = 2\pi \Gamma M v_s^2(\nu),
\]

where \( \nu \) is the mode frequency, \( r_s \) is the radius at which oscillations are measured,

\[
I = \int_0^{\infty} dm \xi_t^2 
\]

is the mode inertia, \( M = I/\xi_t^2(r_s) \) is the mode mass, and finally \( \Gamma \) and \( v_s \) are the mode line-width and the mode surface velocity, respectively, and are obtained from Chaplin et al. (1998). We point out that, according to the definition of Eq. (4), the derived value of \( P_{\text{obs}} \) depends on the model one considers through \( M \). Indeed, for a given mode, \( M \) – a priori – differs from one model to another. However, the mode masses of the models we consider here are very close to each other such that the changes on \( P_{\text{obs}} \) due to the use of the mode mass of the different models are not significant compared to the error bars attached to the measurements. For each mode, we can then compute a unique value for \( P_{\text{obs}} \) and compare the values of \( P \) obtained for the different models to each other and to \( P_{\text{obs}} \). We choose to derive \( M \) from the radial eigenfunctions \( \xi_r \) computed for the KCGM model and we adopt \( r_s = R_\odot + 200 \text{ km} \) consistently with Chaplin et al. (1998)’s observations.

As shown in Fig. 4, differences between \( P_{\text{KCGM}} \) and \( P_{\text{ECGM}} \) are found smaller than the error bars associated with \( P_{\text{obs}} \) from Chaplin et al. (1998). This is a consequence of the fact that the ECGM and KCGM models present very similar convective structures (see Sect. 3.3 and Fig. 3). On the other hand, \( P_{\text{KMLT}} \) is found significantly larger than \( P_{\text{EMLT}} \) as a consequence of the fact that the KMLT models result in larger \( v \) and \( F_c \) values than the EMLT ones (see Sect. 3.3 and Fig. 3) for \( \tau \gtrsim 10 \ldots 20 \).

Furthermore, \( P_{\text{KCGM}} \) and \( P_{\text{ECGM}} \) are found closer to \( P_{\text{obs}} \) than \( P_{\text{KMLT}} \). However, above \( \nu \gtrsim 2.5 \text{ mHz} \), differ-
ences between $P_{\text{obs}}$ and $P_{\text{KCGM}}$ (or $P_{\text{ECGM}}$) remain important. The origin of this discrepancy is discussed in Sect. 5.

For the KCGM and ECGM models we have so far assumed $\Phi = 3$. According to Eq. (A.6), assuming $\Phi = 2$ – a value which is consistent with results from the 3D solar simulation – results in a driving by the entropy source smaller by a factor $\sim 2/3$ compared to the case $\Phi = 3$. This decrease, however, remains small compared to the difference in $P$ between the different models and hence does not influence our main results.

![Fig. 5.](image)

Fig. 5. The integrand $dP/dm$ (Eq. (2) of Paper II) is plotted versus $R_0 - r$ for a mode with order $n = 20$ ($n = 1$ being the fundamental mode) for the KMLT model (dashed line), EMLT model (dot-dashed line), ECGM model (dot-dot-dot-dashed line) and KCGM model (solid line).

We present in Fig. 5 the integrand $dP/dm$ (Eq. (2) of Paper II) corresponding to the excitation rate $P$ of a mode of order $n = 20$. The plot is done for the four solar models. For three of the four models the extent of the region where most of the excitation takes place is very thin (less than 50 km). Obviously, this is the consequence of the very shallow extent of the superadiabatic region (see Fig. 2). This tiny extent of the excitation region strongly contrasts with that one found in Stein & Nordlund (2001) and in Paper III. For instance, the latter authors found a size of order $\sim 500$ km for a mode of the same order. This discrepancy is attributed to the local nature of the convective treatments investigated in this work (see Sect. 6). Note that in Fig. 5 the EMLT model with its large value of $\alpha$ for the entire superadiabatic region predicts a broader excitation region than the other models. This is due to a smaller superadiabatic peak. However, in this model the transport of convective heat occurs with a smaller convective velocity and hence, as expected, the excitation is smaller than for the other models. We note here that despite the EMLT model results in a temperature structure closer to the numerical simulations (smaller superadiabatic peak), the predicted excitation amplitudes are smaller than for the other models investigated here and are the most discrepant in comparison with the data. This confirms that excitation rates provide a decisive additional test for convection models.

5. Conclusions

We have computed the rates $P$ at which acoustic energy is injected into the solar radial $p$ modes for several solar models. The solar models are computed with two different local treatments of convection: the classical mixing-length theory (MLT hereafter) and Canuto et al.'s CGM96 formulation.

For one set of solar models (EMLT and ECGM models), the atmosphere is gray and assumes Eddington’s approximation. The models only assume one mixing-length parameter value and reproduce the solar radius at solar age but not the Balmer line profiles. For a second set of models (KMLT and KCGM models), the atmosphere is built using a $T(\tau)$ law which has been obtained from a Kurucz’s model atmosphere computed with the same local treatment of convection. The mixing-length parameter in the model atmosphere is chosen so as to provide a good agreement between synthetic and observed Balmer line profiles, while the mixing-length parameter in the interior model is calibrated so that the model reproduces the solar radius at solar age.

Both the KMLT and the KCGM models reproduce the Balmer line profile and the solar radius and luminosity but – as shown in Figs. (2)-(4) – the CGM models model the transition between the region of high convective efficiency (the interior) and the region of low efficiency (the atmosphere) in a more realistic way than the MLT models, as they reproduce the observed excitation rate $P$ more closely and predict a smoother transition region. Furthermore the KMLT model requires a change of the mixing-length by a factor of five in a layer of $\sim 20$ km thickness, which is significantly less than a pressure scale height ($\sim 300$ km). Given the meaning of alpha, this means that the mixing-length varies from about 150 km to 750 km in a layer of $\sim 20$ km thickness (!), which does not make much sense from a physical point of view. On the other hand, the KCGM model does not require such large change in $\alpha$.

For the MLT treatment, the oscillation excitation rates, $P$, do significantly depend on the properties of the atmospheres investigated here. Indeed, differences in $P$ between the EMLT model and the KMLT model are found to be very large. On the other hand, for the CGM96 treatment, differences in $P$ between the ECGM and the KCGM models are very small compared to the error bars attached to the seismic measurements. This result shows that an Eddington gray atmosphere can be assumed for the calculation of $P$ when the CGM96 formulation is adopted. This would be particularly convenient in the case of massive computations of $P$ for a large set of stellar models.

For the EMLT and KMLT models, $P$ is significantly underestimated compared to the solar seismic constraints obtained from Chaplin et al.’s measure-
ments. KCGM and ECGM models yield values for $P$ closer to the seismic data than the EMLT and KMLT models. Constraints on the $H_\beta$ Balmer line profile and on the solar radius can be satisfied by the two formulations (MLT and CGM96), provided that the mixing-length parameters $\alpha_i$ and $\alpha_\alpha$ are suitably adjusted. Once the above constraints are satisfied, the solar seismic data provide additional valuable constraints and according to the present investigation (focussed on local approaches) they clearly favor the CGM96 treatment.

Our calculations are based here on Grevesse & Noels (1993)'s solar abundances. There was recently a change in these values (see Asplund et al. 2004–2007) with quite some implications for the internal structure of the Sun (see Basu & Antia 2004; Montalbán et al. 2004; Bahcall et al. 2005; Antia & Basu 2005). Then the implication for the calculation of the excitation rates $(P)$ must be in principle tested consistently by changing the solar mixture both in the interior and the atmosphere (work in progress). However, we except small changes in $P$. Indeed, as a first step we have calculated a solar model having the low metallicity $Z/X = 0.0171$ inferred from the new Asplund et al. (2004)'s revised solar abundances in which the interior calculation is based on the detailed Asplund et al.'s mixture and associated opacities while the atmosphere considers the low metallicity but keeps the Grevesse & Noels (1993)'s solar abundances and associated opacities. Changes in $P$ smaller than $\sim 10\%$ — much smaller than the errors bars ($\sim 20\%$) associated with the current measurements — have been obtained.

The remaining discrepancy above $\nu \gtrsim 2.5$ mHz between computed and observed $P$ (Fig. 4) is attributed to the assumption of locality in the present treatment of convection. As a matter of fact, Samadi et al. (2003a, Paper III) have succeeded in reproducing the seismic constraints much better using constraints from a 3D solar granulation simulation. One reason for this improvement is that convection is intrinsically a non-local phenomenon. In the terminology of classical turbulence modelling, the eddies located at different layers contribute to the convective flux of a given layer (cf. also the discussion in Houdek 1996). Hence, a non-local description of convection is expected to predict a more extended superadiabatic region. This is suggested, for instance, by the comparison of our present results with that of Paper II. Non-local theories — such as those by Gough (1977) and by Canuto & Dubovikov (1998) — also support this explanation: they typically predict a smaller temperature gradient in the superadiabatic region than the local theories do (see Houdek 1996; Kupka & Montgomery 2002) and thus a more extended superadiabatic region as well.

Another property of solar granulation caused by non-locality is the observed asymmetry between the areas covered by up- and downflows. This allows for a lower root mean square velocity while larger velocities (and thus more effective mode driving) can be reached in the downflows with their much higher velocities (note that such an asymmetry can be accounted for through non-local models as proposed by Canuto & Dubovikov 1998, see also Kupka & Montgomery 2002, although in a more simplified manner). On the other hand, the local models studied here cannot account for the different properties of up- and downflow areas at all. Hence, the superadiabatic region in these models is physically different from that one expected from non-local models and found in numerical simulations. Solar modes above $\nu \gtrsim 2$ mHz, however, are predominantly excited in the superadiabatic region (Paper III). A larger amount of acoustic energy is then injected in those modes when convection is treated — as is in the 3D simulation or on the base of a non-local theory — in a more realistic manner than through local theories.

The results presented here so far only concern our Sun. Samadi et al. (2003a) found that $P$ scales as $(L/M)^s$ where $s$ is the slope of the power law and $L$ and $M$ are the mass and luminosity of their computed 1D stellar models. By building a set of stellar models with the MLT and another one with Gough (1977)'s non-local formulation of convection, the authors found that the slope $s$ is quite sensitive to the 1D treatment of convection. In this respect, it would be interesting to compare the influence of the CGM96 formulation or of Canuto & Dubovikov (1998)'s non-local convection treatment on the value of $s$ and to test whether or not measurements of $P$ can — for stars other than the Sun — discriminate the best 1D treatment of convection.

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Appendix A: Relation between the entropy fluctuations and the convective flux

As in Paper I, we relate the entropy fluctuations, $s_t$, to temperature fluctuations, $\theta$, as follows:

$$s_t = \frac{c_p}{T_0} \theta$$

where $T_0$ is the mean temperature and $c_p = (\partial s/\partial \ln T)_p$. Hence, the mean square of the entropy fluctuations, $< s_t^2 >$, can be expressed as

$$< s_t^2 > \approx \left( \frac{c_p}{T_0} \right)^2 < \theta^2 >.$$  \hfill (A.2)

The convective flux is related to $\theta$ and $u_z$, the vertical component of convective velocity, as

$$F_c \approx \rho_0 c_p < u_z \theta >,$$  \hfill (A.3)
where $\rho_0$ is the mean density. We furthermore assume, consistently with the adopted quasi-normal approximation in Paper I, that $< u_x^2 s_t^2 >$ can be decomposed as

$$< u_x^2 s_t^2 > = ( < u_x^2 > < s_t^2 > ) = w^2 < s_t^2 > .$$  

(A.4)

Finally, one can show that

$$\alpha_s \equiv \left( \frac{\partial p}{\partial s} \right)_\rho = \rho_0 T_0 \Gamma_1 \nabla_{ad},$$  

(A.5)

where $s$ is the entropy and $p$ the pressure, $T_0$ is the mean temperature, $\Gamma_1 = (\partial \ln p / \partial \ln \rho)_s$ is the adiabatic exponent and $\nabla_{ad} = (\partial \ln T / \partial \ln p)_s$ is the adiabatic temperature gradient.

The mean square of the entropy fluctuations can then be deduced from the set of Eqs. (A.1-A.5) and Eq. (2):

$$< s_t^2 > \approx \frac{\Phi}{3} \left( \frac{F_c}{\rho_0 T_0 \Gamma_1} \right)^2 ,$$  

(A.6)

where $\Phi$ is the spatially averaged anisotropy factor, which is defined in Eq. 2. Driving by the entropy source term is then proportional to $(\alpha_s/\rho_0 T_0)^2 (\Phi/3)^2 F_c^2$ – see Paper I – and thus scales like the square of $F_c$.

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